

# Squeezer Angle Compensation

## Setup

```
In[1]:= Needs["Controls`LinearControl`"]

In[2]:= $TextStyle = {FontFamily -> "Helvetica", FontSize -> 13};

In[3]:= plotopt = PlotStyle -> {{Thickness [0.007], RGBColor [1, 0, 0]},
                                {Thickness [0.007], RGBColor [0, 0, 1]},
                                {Thickness [0.007], RGBColor [0.1, 0.7, 0.2]},
                                {Thickness [0.007], RGBColor [0.5, 0.5, 0.2]}};

In[4]:= par[r1_, r2_] := 
$$\frac{1}{1/r1 + 1/r2}$$


In[5]:= pole[f_, p_] := 
$$\frac{1}{1 + i f / p}$$

        zero[f_, p_] := 
$$1 + i f / p$$

        pole[f_, p_, Q_] := 
$$\frac{1}{1 + i \frac{1}{Q} \frac{f}{p} - (f/p)^2}$$

        zero[f_, p_, Q_] := 
$$1 + i \frac{1}{Q} \frac{f}{p} - (f/p)^2$$

```

## Simplified Target

## Target

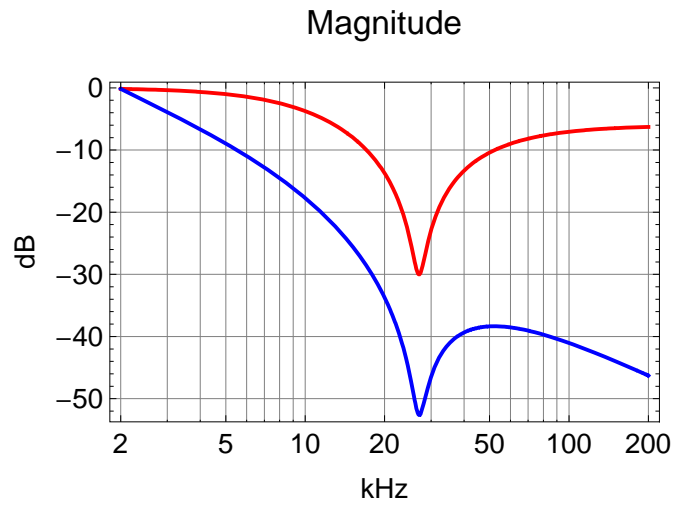
```
In[40]:= targ[f_] := zero[f, 25, 20] pole[f, 25]^2;
        comp[f_] := zero[f, 10] pole[f, 40];

In[124]:= targ[f_] := zero[f, 27, 10] pole[f, 27] pole[f, 13.5];
        comp[f_] := 1000 pole[f, 0.002]
        {targ[f], targ[f] comp[f]} /. f -> 26.4 // dB
        {targ[f], targ[f] comp[f]} /. f -> 30. // dB

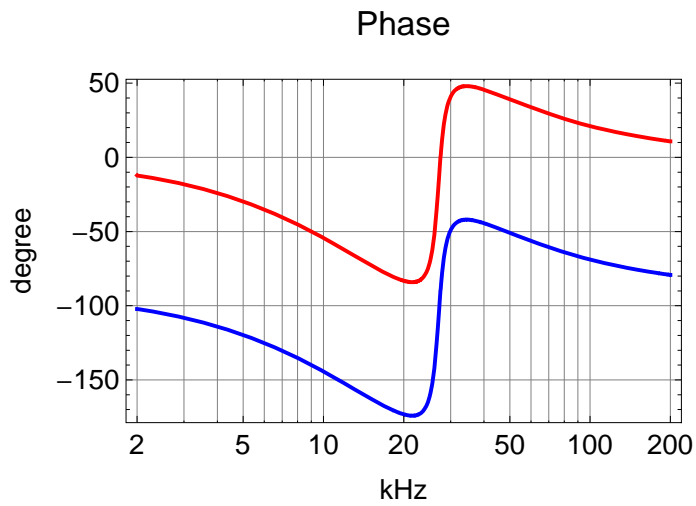
Out[126]= {-29.144, -51.5555}

Out[127]= {-22.944, -46.4658}
```

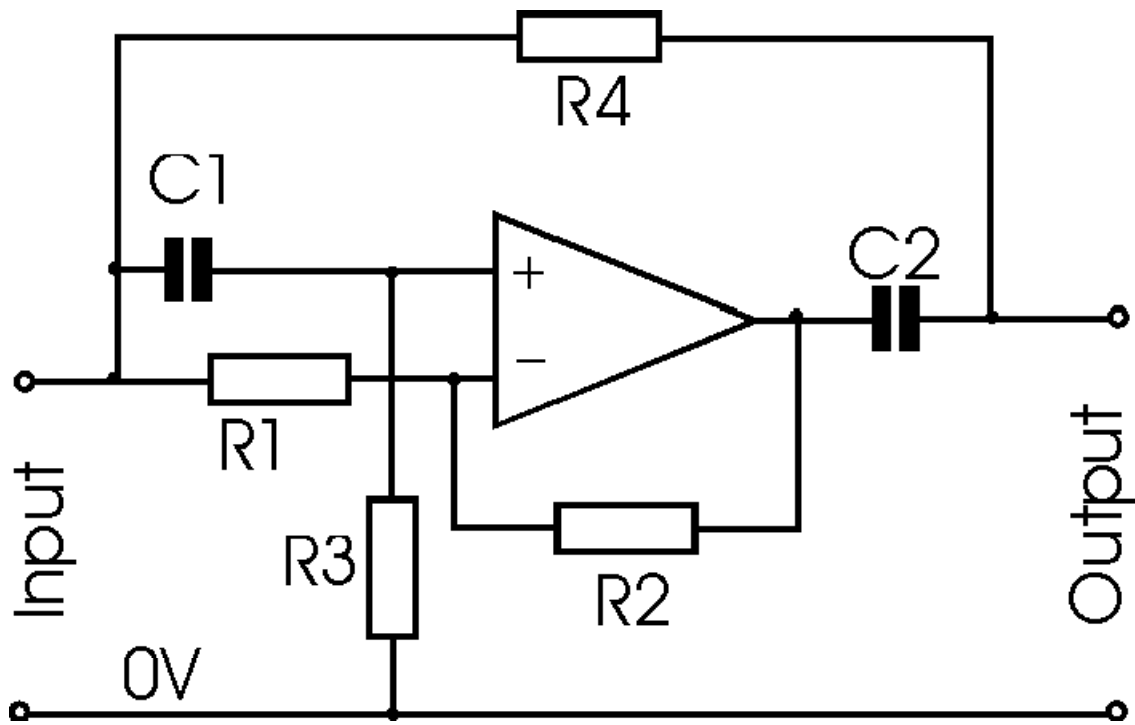
```
In[128]:= BodePlot[{targ[f], targ[f] comp[f]}, {f, 2, 200}, plotopt,  
  BaseStyle -> $TextStyle, XAxisLabel -> "kHz", MagnitudeRange -> All]
```



Out[128]=



## Notch Circuit



## Equations

$C3$  is at the output to ground.

```

In[129]:= eq1 =  $\frac{vp - vin}{\frac{1}{s C1}} + \frac{vp}{R3} == 0$ 

eq2 =  $\frac{vm - vin}{R1} + \frac{vm - vo}{R2} == 0$ 

eq3 = vm == vp
eq4 = R3 == R4
eq5 = C1 == C2

eq6 =  $\frac{vout - vo}{\frac{1}{s C2} + Rdamp} + \frac{vout - vin}{R4} + \frac{vout}{\frac{1}{s C3}} == 0$ 

Solve[{eq1, eq2, eq3, eq4, eq5, eq6}, vout, {vp, vm, R4, C2, vo}]

sol =  $\frac{vout}{vin}$  /. %[[1]]
Limit[sol, s → 0]

Collect[Simplify[ $\frac{Numerator[sol]}{R1}$  /. Rdamp → 0 /. R2 → R1 -  $\frac{R1}{Q}$  /. C1 →  $\frac{1}{\omega R3}$ ], s]

zsol = Solve[ $\frac{Numerator[sol]}{R1} == 0$  /. Rdamp → 0 /. R2 → R1 -  $\frac{R1}{Q}$  /. C1 →  $\frac{1}{\omega R3}$ , s] // PowerExpand

Collect[Simplify[ $\frac{Denominator[sol]}{R1}$  /. Rdamp → 0], s]

psol = Solve[Denominator[sol] == 0 /. Rdamp → 0 /. R3 →  $\frac{1}{\omega C1}$ , s]

Out[129]=  $\frac{vp}{R3} + C1 s (-vin + vp) == 0$ 

Out[130]=  $\frac{-vin + vm}{R1} + \frac{vm - vo}{R2} == 0$ 

Out[131]= vm == vp

Out[132]= R3 == R4

Out[133]= C1 == C2

Out[134]=  $C3 s vout + \frac{-vin + vout}{R4} + \frac{-vo + vout}{Rdamp + \frac{1}{C2 s}} == 0$ 

Out[135]=  $\left\{ \left\{ vout \rightarrow \left( \frac{(R1 + C1 R1 R3 s - C1 R2 R3 s + C1 R1 Rdamp s + C1^2 R1 R3^2 s^2 + C1^2 R1 R3 Rdamp s^2) vin}{(R1 (1 + C1 R3 s) (1 + C1 R3 s + C3 R3 s + C1 Rdamp s + C1 C3 R3 Rdamp s^2))} \right) \right\} \right\}$ 

Out[136]=  $\left( \frac{R1 + C1 R1 R3 s - C1 R2 R3 s + C1 R1 Rdamp s + C1^2 R1 R3^2 s^2 + C1^2 R1 R3 Rdamp s^2}{(R1 (1 + C1 R3 s) (1 + C1 R3 s + C3 R3 s + C1 Rdamp s + C1 C3 R3 Rdamp s^2))} \right)$ 

Out[137]= 1

Out[138]=  $1 + \frac{s^2}{\omega^2} + \frac{s}{Q \omega}$ 

Out[139]=  $\left\{ \left\{ s \rightarrow \frac{-\omega - \sqrt{\omega^2 - 4 Q^2 \omega^2}}{2 Q} \right\}, \left\{ s \rightarrow \frac{-\omega + \sqrt{\omega^2 - 4 Q^2 \omega^2}}{2 Q} \right\} \right\}$ 

```

$$\text{Out}[140]= 1 + (2 C1 R3 + C3 R3) s + (C1^2 R3^2 + C1 C3 R3^2) s^2$$

$$\text{Out}[141]= \left\{ \{s \rightarrow -\omega\}, \left\{ s \rightarrow -\frac{C1 \omega}{C1 + C3} \right\} \right\}$$

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## Parameters

$$\text{In}[241]= \text{prm} = \{C1 \rightarrow 1.8 \times 10^{-9}, R3 \rightarrow 3.34 \times 10^3, R1 \rightarrow 3.34 \times 10^3, R2 \rightarrow 3.01 \times 10^3, C3 \rightarrow 1.8 \times 10^{-9}, \text{Rdamp} \rightarrow 20\}$$

$$\text{Out}[241]= \{C1 \rightarrow 1.8 \times 10^{-9}, R3 \rightarrow 3340., R1 \rightarrow 3340., R2 \rightarrow 3010., C3 \rightarrow 1.8 \times 10^{-9}, \text{Rdamp} \rightarrow 20\}$$

$$\text{In}[242]= \text{sol} /. \text{prm} (* s \text{ polynomial } *)$$

$$\frac{1}{2 \pi C1 R3} /. \text{prm} (* \text{ frequency of zeroes and one of the poles } *)$$

$$\frac{R1}{R1 - R2} /. \text{prm} (* Q \text{ of zeroes } *)$$

$$\frac{C1}{C1 + C3} /. \text{prm} (* \text{ shift of one of the poles } *)$$

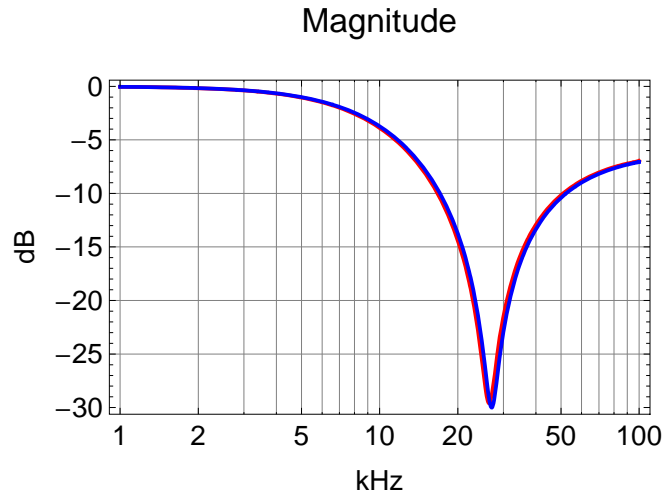
$$\text{Out}[242]= \frac{0.000299401 (3340. + 0.0021042 s + 1.21444 \times 10^{-7} s^2)}{(1 + 6.012 \times 10^{-6} s) (1 + 0.00001206 s + 2.16432 \times 10^{-13} s^2)}$$

$$\text{Out}[243]= 26472.9$$

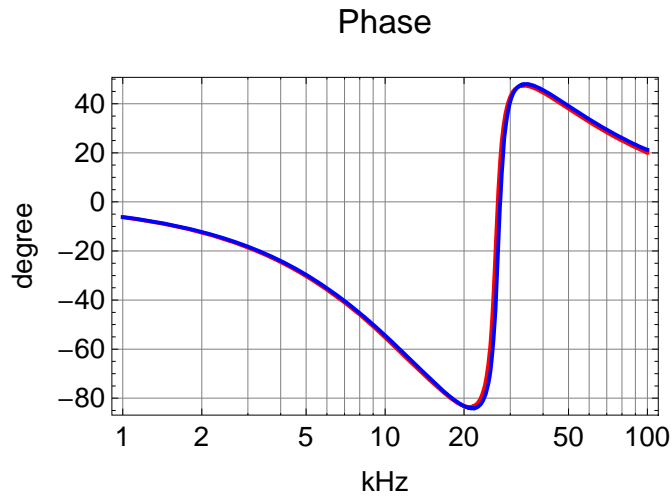
$$\text{Out}[244]= 10.1212$$

$$\text{Out}[245]= 0.5$$

```
In[246]:= BodePlot[{sol /. prm /. s → 2 π i 1*^3 f, targ[f]}, {f, 1, 100},
  plotopt, BaseStyle → $TextStyle, XAxisLabel → "kHz", MagnitudeRange → All]
```



```
Out[246]=
```



```
In[247]:= Solve[Numerator[sol] == 0 /. s → -2 π f, f] /. prm (* zero frequencies *)

$$\frac{\sqrt{(f /. \%[1]) (f /. \%[2])}}{2 \sin[\text{Arg}[i f /. \%[2]]]} // \text{Chop} (* \text{frequency} *)$$

1
(* Q *)
Solve[Denominator[sol /. Rdamp → 0] == 0 /. s → -2 π f, f] /. prm (* pole frequencies *)
```

```
Out[247]= {{f → 1378.8 - 26 357.9 i}, {f → 1378.8 + 26 357.9 i}}
```

```
Out[248]= 26 394.
```

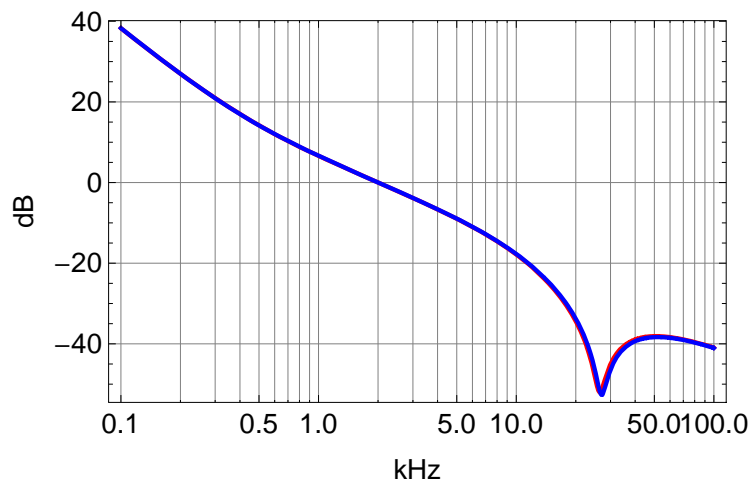
```
Out[249]= 9.57139
```

```
Out[250]= {{f → 26 472.9}, {f → 13 236.4}}
```

## Compensation

```
In[251]:= boost[f_] := 100 pole[f, 0.004] zero[f, 0.4]
BodePlot[
  {200 pole[f, 0.01] boost[f] sol /. prm /. s -> 2 π i 1*^3 f, 200 pole[f, 0.01] boost[f] targ[f]},
  {f, .1, 100}, plotopt, BaseStyle -> $TextStyle, XAxisLabel -> "kHz"]
```

Magnitude



Out[252]=

Phase

