

Data Analysis III: Stochastic Background

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Scope of This Lecture

- Ground-based detectors (IFOs & bars)
- Cross-correlation measurements
- Assume uncorrelated noise \gg stochastic GW signal

Outline

I Optimally Filtered Cross-Correlation Statistic

II Overlap Reduction Function

III Specific Detector Pairs

Conventions

- One-sided PSD (so $\langle \tilde{h}(f)^* \tilde{h}(f') \rangle = \frac{1}{2} \delta(f - f') P(f)$)
- Detector response is $h(t) = d^{ab} h_{ab}(t, \vec{x})$
 - $d_{ab}^{\text{ifo}} = \frac{1}{2} (\hat{u}_a \hat{u}_b - \hat{v}_a \hat{v}_b)$
 - $d_{ab}^{\text{bar}} = \hat{u}_a \hat{u}_b$
- Overlap reduction function is

$$\gamma_{12}(f) = \frac{5}{2} \Gamma_{12}(f) = \frac{5}{8\pi} \sum_{A=+, \times} \int_{S^2} d\hat{\Omega} e^{i2\pi f \hat{\Omega} \cdot \Delta \vec{x} / c} F_{1A}(\hat{\Omega}) F_{2A}(\hat{\Omega})$$

- Detector response $F_{1A}(\hat{\Omega}) = d_{ab} e_A^{ab}(\hat{\Omega})$
- Work with $h_0^2 \Omega_{\text{GW}}(f) = \frac{h_0^2}{\rho_{\text{crit}}} \frac{d\rho_{\text{GW}}}{d \ln f} = \frac{4\pi^2 h_0^2}{3H_0^2} f^3 S_h(f)$

I. Cross-correlation statistic

- Basic idea: look for correlations between detectors
 - Detector 1: $h_1 = s_1 + n_1$, Detector 2: $h_2 = s_2 + n_2$
- Assume noise uncorrelated **with signal** & **between detectors**
- Cross-correlation:

$$\langle h_1 h_2 \rangle = \langle n_1 n_2 \rangle + \langle n_1 s_2 \rangle + \langle s_1 n_2 \rangle + \langle s_1 s_2 \rangle$$

only surviving term is from stochastic GW signal

Cross-Correlation Statistic (cont'd)

$$\begin{aligned} Y_Q &= \int dt_1 dt_2 h_1(t_1) Q(t_1 - t_2) h_2(t_2) \\ &= \int df \tilde{h}_1^*(f) \tilde{Q}(f) \tilde{h}_2(f) \end{aligned}$$

- Mean from

$$\langle \tilde{h}_1^*(f) \tilde{h}_2(f') \rangle = \delta(f - f') \frac{3H_0^2}{20\pi^2} |f|^{-3} \Omega_{\text{GW}}(f) \gamma_{12}(|f|):$$

$$\langle Y \rangle = \frac{3H_0^2}{20\pi^2} T \int df |f|^{-3} \Omega_{\text{GW}}(f) \gamma_{12}(|f|) \tilde{Q}(f)$$

- Variance from $\langle \tilde{h}_i(f)^* \tilde{h}_i(f') \rangle = \frac{1}{2} \delta(f - f') P_i(f)$:

$$\langle Y^2 \rangle = \frac{T}{4} \int df P_1(f) |\tilde{Q}(f)|^2 P_2(f)$$

(Assume **environmental noise** dominates variance)

Optimal Filter

Choose $\tilde{Q}(f)$ to maximize signal-to-noise ratio:

$$\text{SNR}^2 = \frac{\langle Y \rangle^2}{\langle Y^2 \rangle} = \left(\frac{3H_0^2}{20\pi^2} \right)^2 T \frac{\left(\int df A(f)^* P_1(f) P_2(f) \tilde{Q}(f) \right)^2}{\int df \tilde{Q}(f)^* P_1(f) P_2(f) \tilde{Q}(f)}$$

this is accomplished by choosing

$$\tilde{Q}(f) \propto A(f) = \frac{f^{-3} \Omega_{\text{GW}}(f) \gamma_{12}(f)}{P_1(f) P_2(f)}$$

& gives

$$\text{SNR}^2 = \left(\frac{3H_0^2}{20\pi^2} \right)^2 T \int df \frac{(f^{-3} \Omega_{\text{GW}}(f) \gamma_{12}(f))^2}{P_1(f) P_2(f)}$$

Note role of **signal**, **geometry** & **noise**

Overlap Reduction Function (cont'd)

$$\begin{aligned}\gamma_{12}(f) &= d_1^{ab} d_2^{cd} \frac{5}{8\pi} \sum_{A=+, \times} \int_{S^2} d\hat{\Omega} e^{i2\pi f \hat{\Omega} \cdot \Delta \vec{x} / c} e_{Aab}(\hat{\Omega}) e_{Acd}(\hat{\Omega}) \\ &= d_{1ab} d_2^{cd} \frac{5}{4\pi} \int_{S^2} d\hat{\Omega} P^{TTab}_{cd}(\hat{\Omega}) e^{i2\pi f \hat{\Omega} \cdot \Delta \vec{x} / c}\end{aligned}$$

where $P^{TTab}_{cd}(\hat{\Omega}) = \frac{1}{2} \sum_{A=+, \times} e_A^{ab}(\hat{\Omega}) e_{Acd}(\hat{\Omega})$ is a projection operator onto traceless symmetric tensors transverse to $\hat{\Omega}$.

Note we can replace each d_{ab} with its traceless part

$$D_{ab} = d_{ab} - \frac{1}{3} \delta_{ab} d_c^c$$

\exists a closed-form solution for $\gamma(f)$ i.t.o. Bessel functions; look at the simpler form of $\gamma(0)$...

Coïncident Overlap Reduction Function

$$\gamma(0) = d_{1ab} d_2^{cd} \frac{5}{4\pi} \int_{S^2} d\hat{\Omega} P^{\text{TT}ab}_{cd}(\hat{\Omega})$$

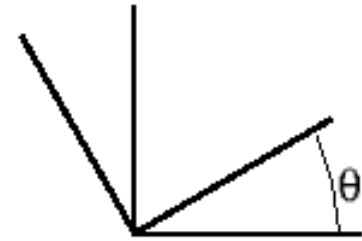
But $\int_{S^2} d\hat{\Omega} P^{\text{TT}ab}_{cd}(\hat{\Omega}) \propto P^{\text{T}ab}_{cd}$ (projection onto traceless symmetric tensors) by symmetry, & since $P^{\text{T}ab}_{ab} = 5$ & $P^{\text{TT}ab}_{ab}(\hat{\Omega}) = 2$, the proportionality constant must be $(2/5)4\pi$, so

$$\gamma(0) = 2D_{1ab} D_2^{ab}$$

This holds in the $f \rightarrow 0$ limit, or for **coïncident** detectors.

Coïncident Interferometers

Geometry described by angle θ between IFOs



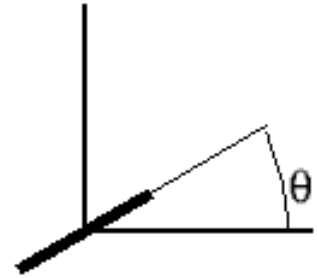
$$D_1 = \frac{1}{2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$D_2 = \frac{1}{2} \begin{pmatrix} \cos^2 \theta - \sin^2 \theta & 2 \cos^2 \theta \sin^2 \theta & 0 \\ 2 \cos^2 \theta \sin^2 \theta & \sin^2 \theta - \cos^2 \theta & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\gamma = 2D_{1ab}D_2^{ab} = \cos 2\theta$$

Coïncident Interferometer & Bar

Geometry described by angle θ between IFO & bar



$$D_1 = \frac{1}{2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$D_2 = \begin{pmatrix} \cos^2 \theta - \frac{1}{3} & \cos^2 \theta \sin^2 \theta & 0 \\ \cos^2 \theta \sin^2 \theta & \sin^2 \theta - \frac{1}{3} & 0 \\ 0 & 0 & -\frac{1}{3} \end{pmatrix}$$

$$\gamma = 2D_{1ab}D_2^{ab} = \cos 2\theta$$

Coïncident Bars

Geometry described by angle θ between bars



$$D_1 = \begin{pmatrix} \frac{2}{3} & 0 & 0 \\ 0 & -\frac{1}{3} & 0 \\ 0 & 0 & -\frac{1}{3} \end{pmatrix}$$

$$D_2 = \begin{pmatrix} \cos^2 \theta - \frac{1}{3} & \cos^2 \theta \sin^2 \theta & 0 \\ \cos^2 \theta \sin^2 \theta & \sin^2 \theta - \frac{1}{3} & 0 \\ 0 & 0 & -\frac{1}{3} \end{pmatrix}$$

$$\gamma = 2D_{1ab}D_2^{ab} = \frac{1}{3}(1 + 3 \cos 2\theta)$$

Note this means for parallel bars, $\gamma(0) = \frac{4}{3}$

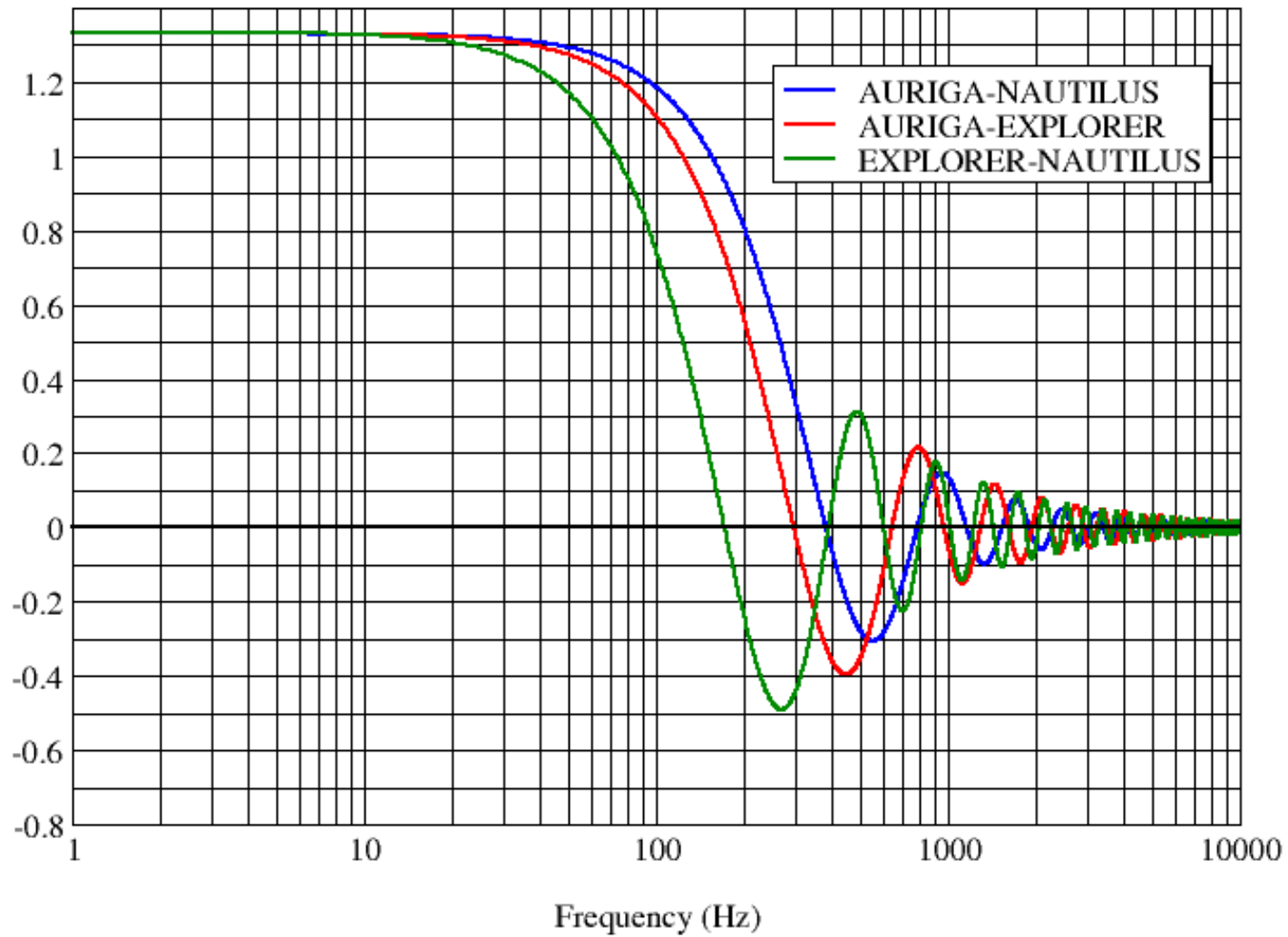
III. Specific Correlation Experiments

- European Bars: **EXPLORER**/**NAUTILUS**/**AURIGA**
- Correlations with **LIGO Livingston** (aka **LLO** or **LIGO-LA**)
- Correlations with **VIRGO**

(Overlap reduction function plots made with Erick Vallerino)

Overlap Reduction Function

(European bar detectors)

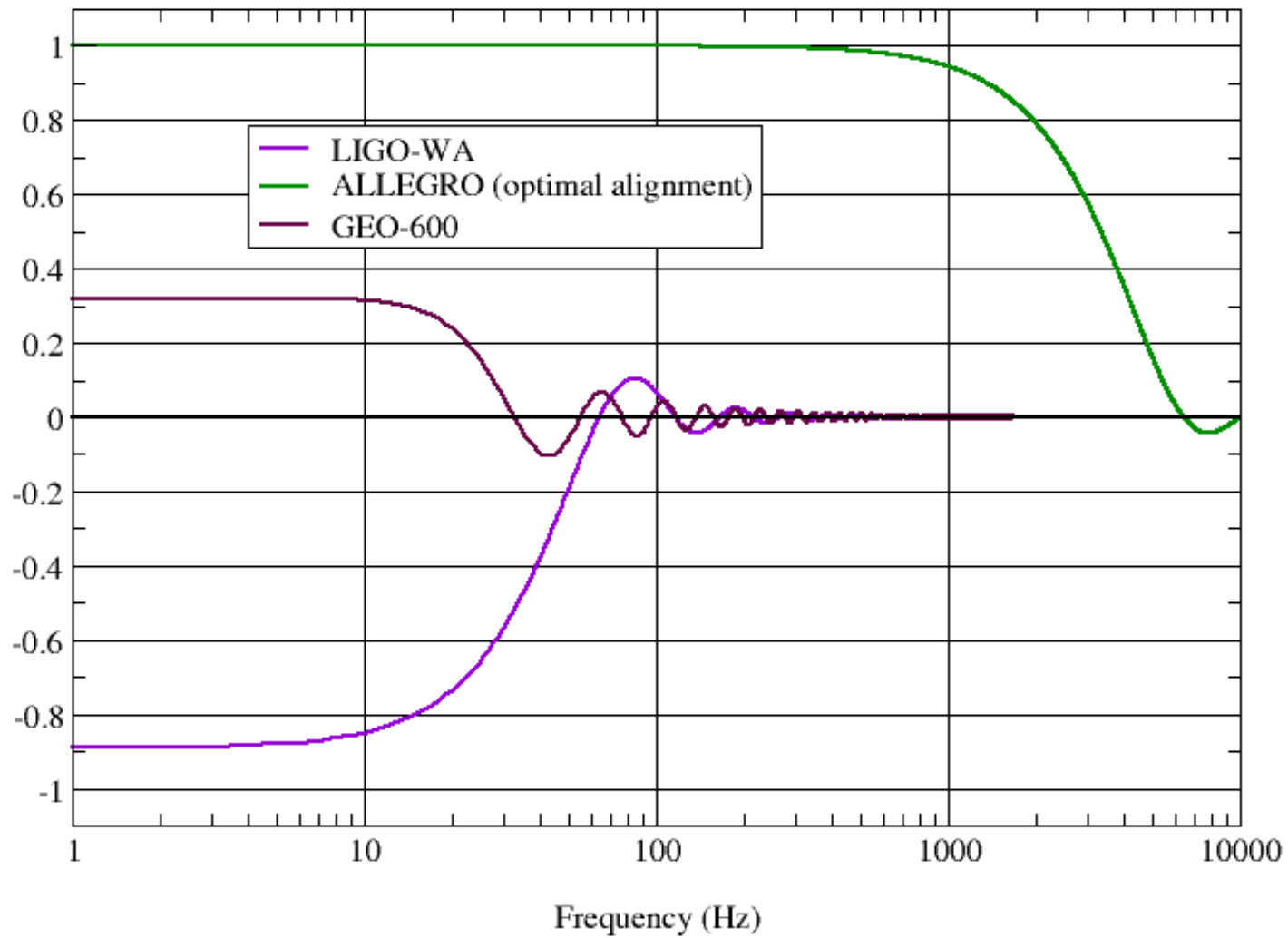


Correlations Between European Bar Detectors

- Important value is $\gamma(907 \text{ Hz})$
- $10\% < \gamma(907 \text{ Hz}) < 20\%$ for all bars
- Current best upper limit: correlation between **EXPLORER** & **NAUTILUS** bars (Astone et al, 1999):
 $\Omega_{\text{GW}}(907 \text{ Hz}) \leq 60$

Overlap Reduction Function

(LIGO-LA and other detectors)



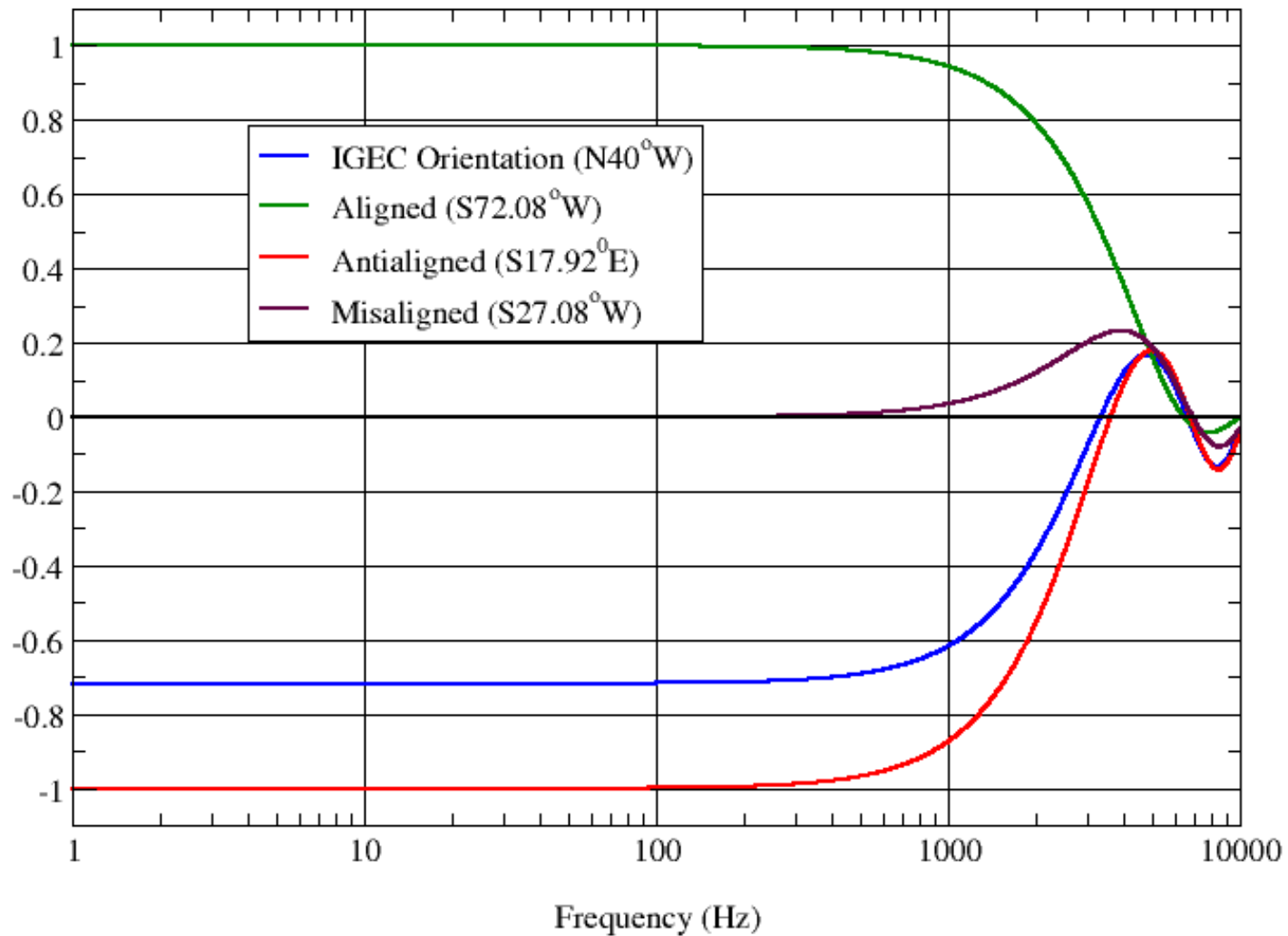
LIGO-LIGO Correlations

- Tradeoff between noise spectrum & overlap reduction fcn
→ most of the correlations should come from **lower frequencies** (50–250Hz)
- If amplitude spectral density has same shape as **design sensitivity**, just scaled up, can set a **90%** confidence level upper limit on **constant $\Omega_{\text{GW}}(f)$** around

$$\Omega_{\text{GW}}(f) \lesssim 6 \times 10^{-6} \times \left(\frac{17 \text{ days}}{T} \right)^{1/2} \times \left(\frac{(\text{LHO ASD})(\text{LLO ASD})}{(\text{LIGO-1 ASD})^2} \right)$$

Overlap Reduction Function

(LIGO-LA and ALLEGRO)



LIGO-ALLEGRO Correlations

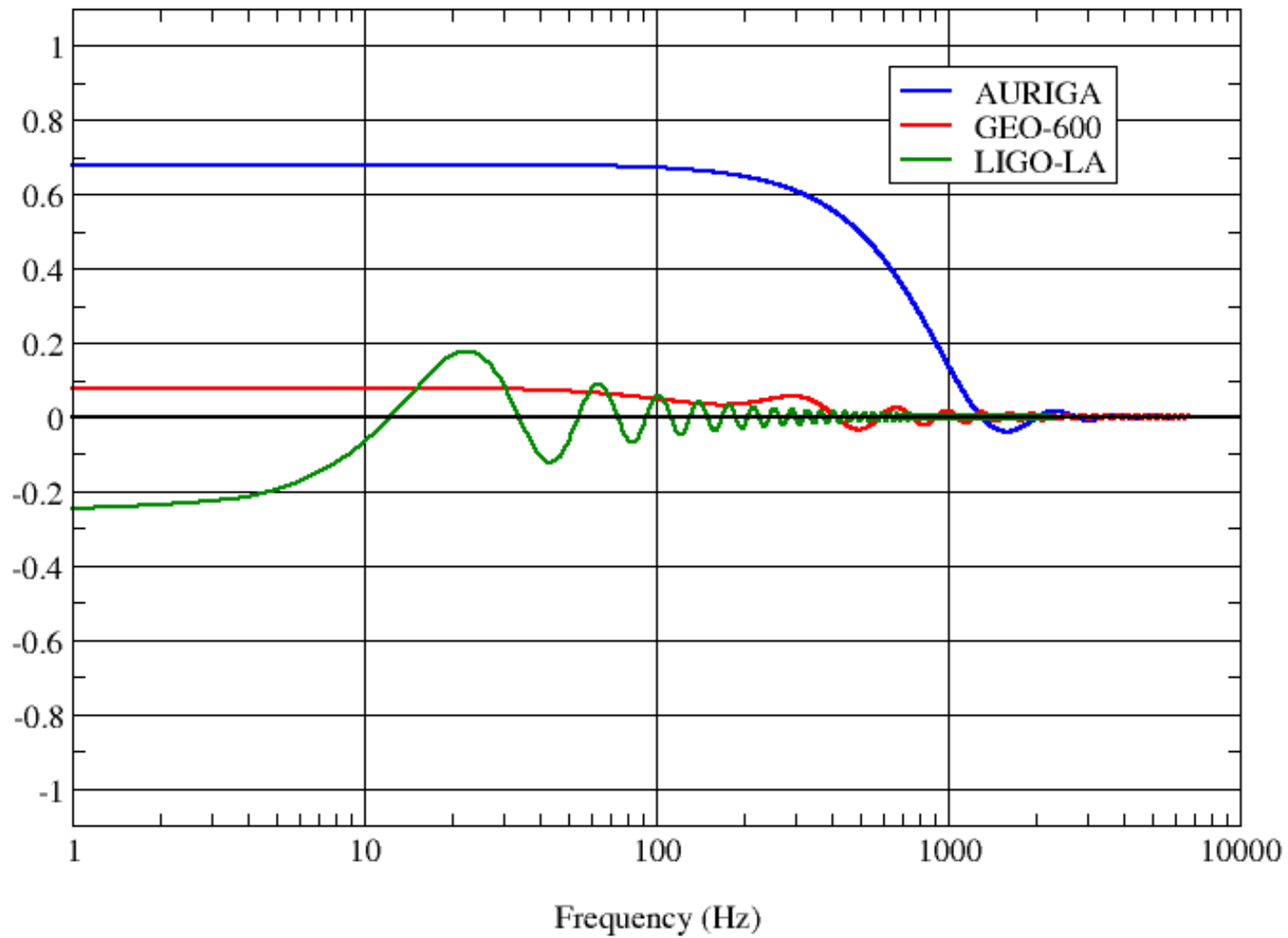
- **ALLEGRO** and **LIGO-Livingston** only 40km apart
- For optimal alignment, $\gamma(900 \text{ Hz}) \approx 95\%$
- W/**No correlated noise** & **ALLEGRO** bandwidth & noise as in **PRD 54, 1264 (1996)** could set a **90%** confidence level **upper limit** around

$$\Omega_{\text{GW}}(900 \text{ Hz}) \lesssim 0.2 \times \left(\frac{17 \text{ days}}{T} \right)^{1/2} \times \left(\frac{\text{LLO ASD}(900 \text{ Hz})}{10^{-22} \text{ Hz}^{-1/2}} \right)$$

- Comparing correlations for different **ALLEGRO** orientations can distinguish **stoch BG** from **correlated noise**.
(Finn & Lazzarini 2001)

Overlap Reduction Function

(VIRGO and other detectors)

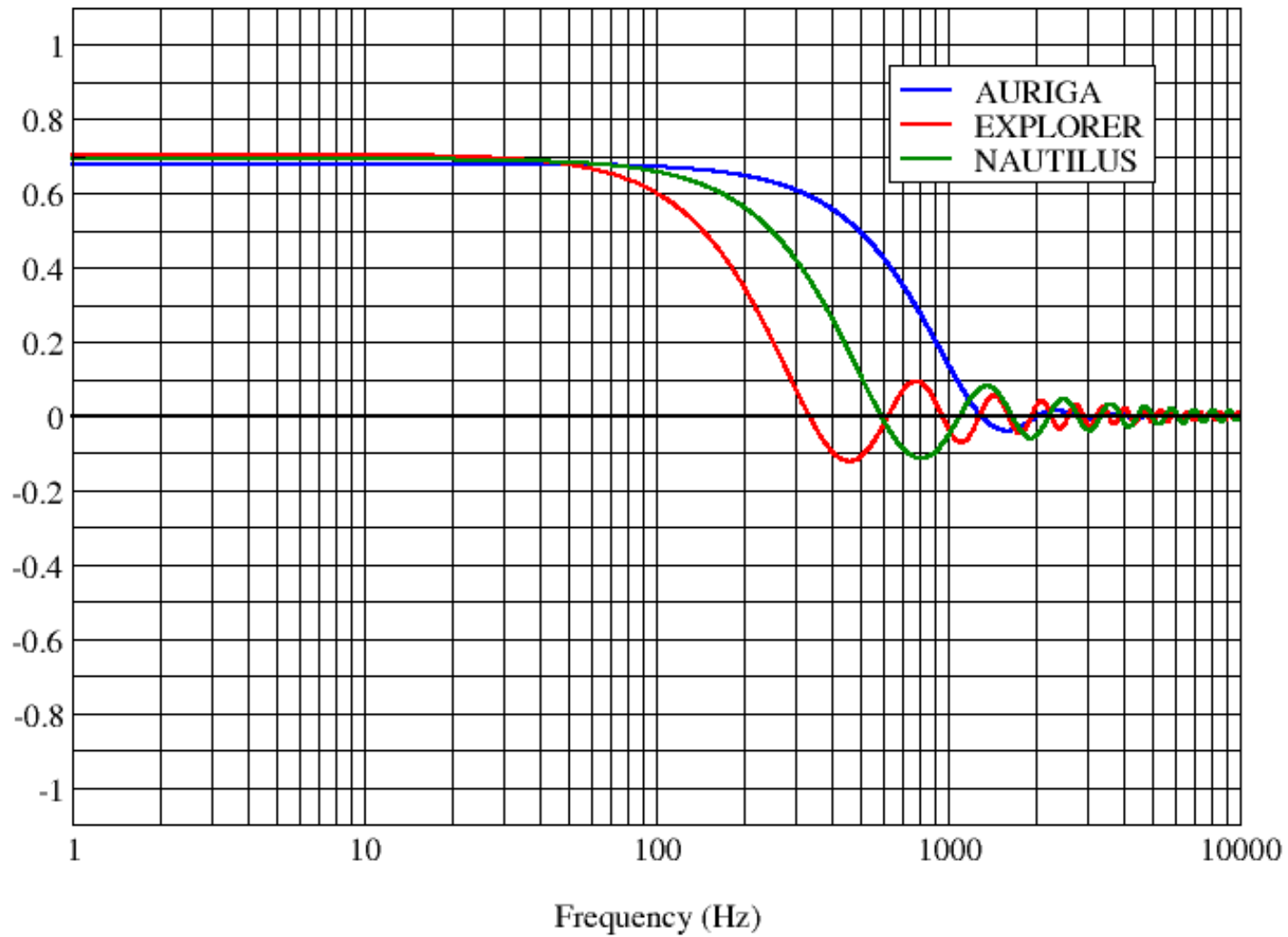


Correlations Involving VIRGO

- GEO-600 probes a different polarization
- Other detectors far away
- Low-frequency sensitivity potentially helpful for corr w/IFOs
- Some potential for correlations with bars (but note bar resonance near onset of high-frequency cancellations)

Overlap Reduction Function

(VIRGO and European bar detectors)

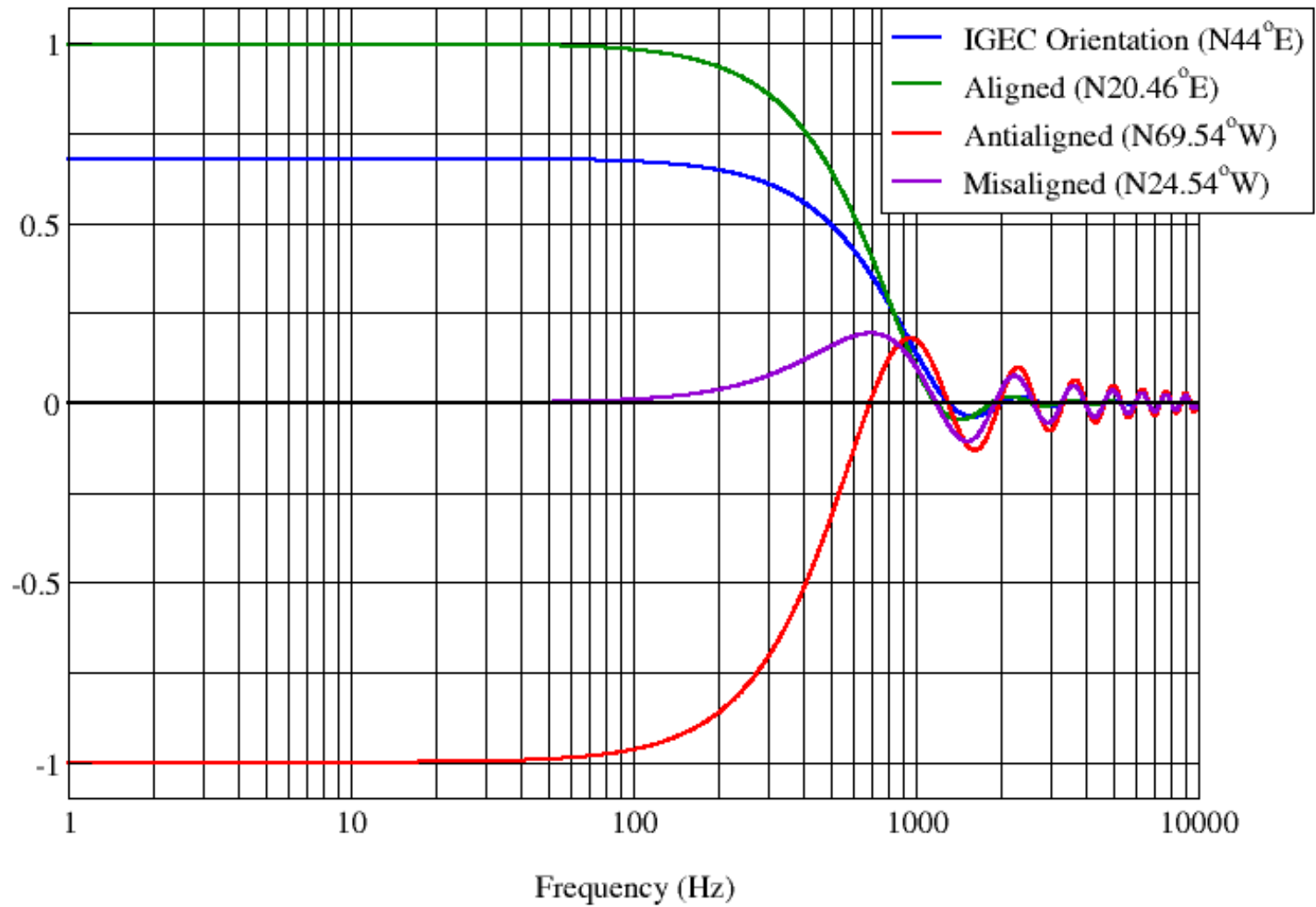


Correlations Between VIRGO & Existing Bars

- AURIGA closest (223 km)
- Existing bars slightly too far away for best overlap at current resonant frequency

Overlap Reduction Function

(VIRGO and AURIGA)



Orientation Dep of VIRGO-AURIGA Overlap Reduction Function

- At current bar resonant frequency, VIRGO-AURIGA GW correlations are \sim independent of AURIGA orientation
→ Can't modulate VIRGO-AURIGA GW signal
à la LLO-ALLEGRO

Coda: Current Observational Upper Limits

- Current best upper limit: correlation between **EXPLORER** & **NAUTILUS** bars (Astone et al, 1999):
 $\Omega_{\text{GW}}(907 \text{ Hz}) \leq 60$
- Upper limit from **single** bar (Astone et al, 1996):
 $\Omega_{\text{GW}}(907 \text{ Hz}) \leq 100$
- Correlation between **Garching** & **Glasgow** prototype IFOs (Compton et al, 1994):
 $\Omega_{\text{GW}}(f) \lesssim 3 \times 10^5$

LLO-LHO & **LLO-ALLEGRO** upper limit calculations underway with data from 2002 Jan LIGO E7 Engineering Run (**LIGO-GEO** also to follow)

Summary

- To detect a stochastic GW background, look for a **cross-correlation** among detectors
- Maximize signal-to-noise using an **optimal filter**
$$\tilde{Q}(f) \propto \frac{f^{-3} \Omega_{\text{GW}}(f) \gamma_{12}(f)}{P_1(f) P_2(f)}$$
- **Overlap Reduction Function** $\gamma_{12}(f)$ determines role of **observing geometry** (distance & orientation)

References

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Poster: LIGO graphical presentation G010246-00-E