

LSC Meeting, November 12, 2003

Lasti EPI

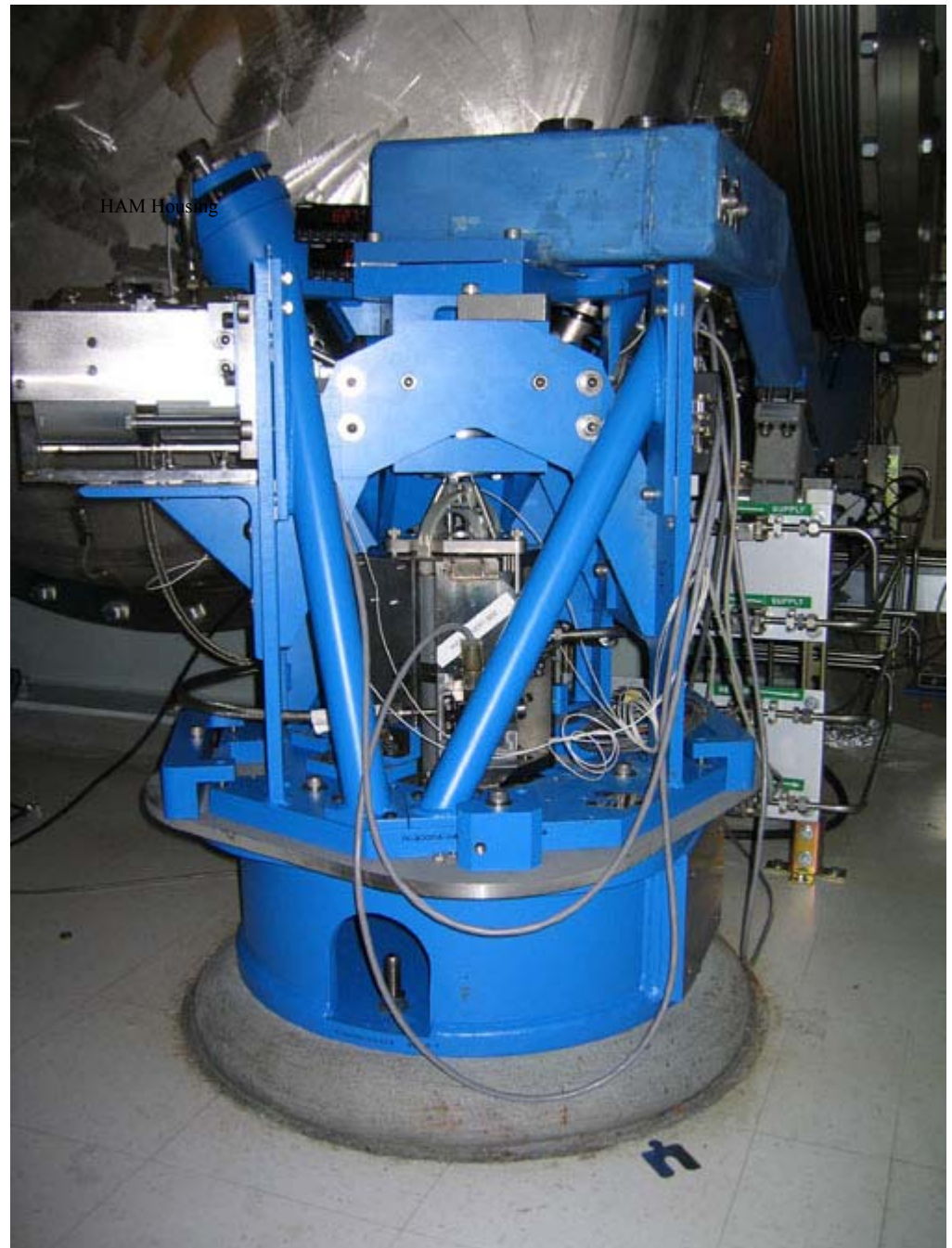
Way to many People to List

Presented by Richard Mittleman

BSC With EPI

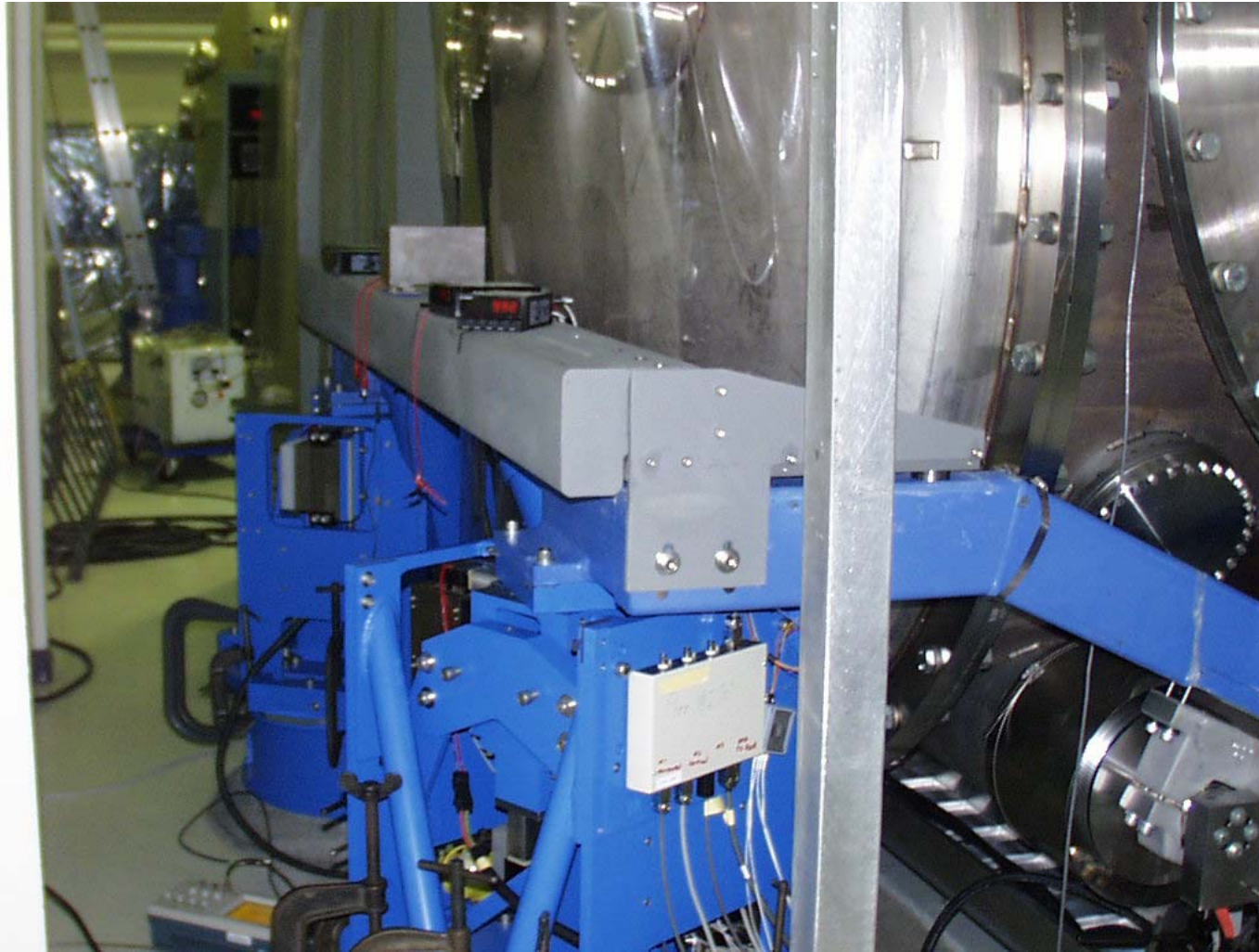


HAM EPI Actuator Housing with HEPI Actuators



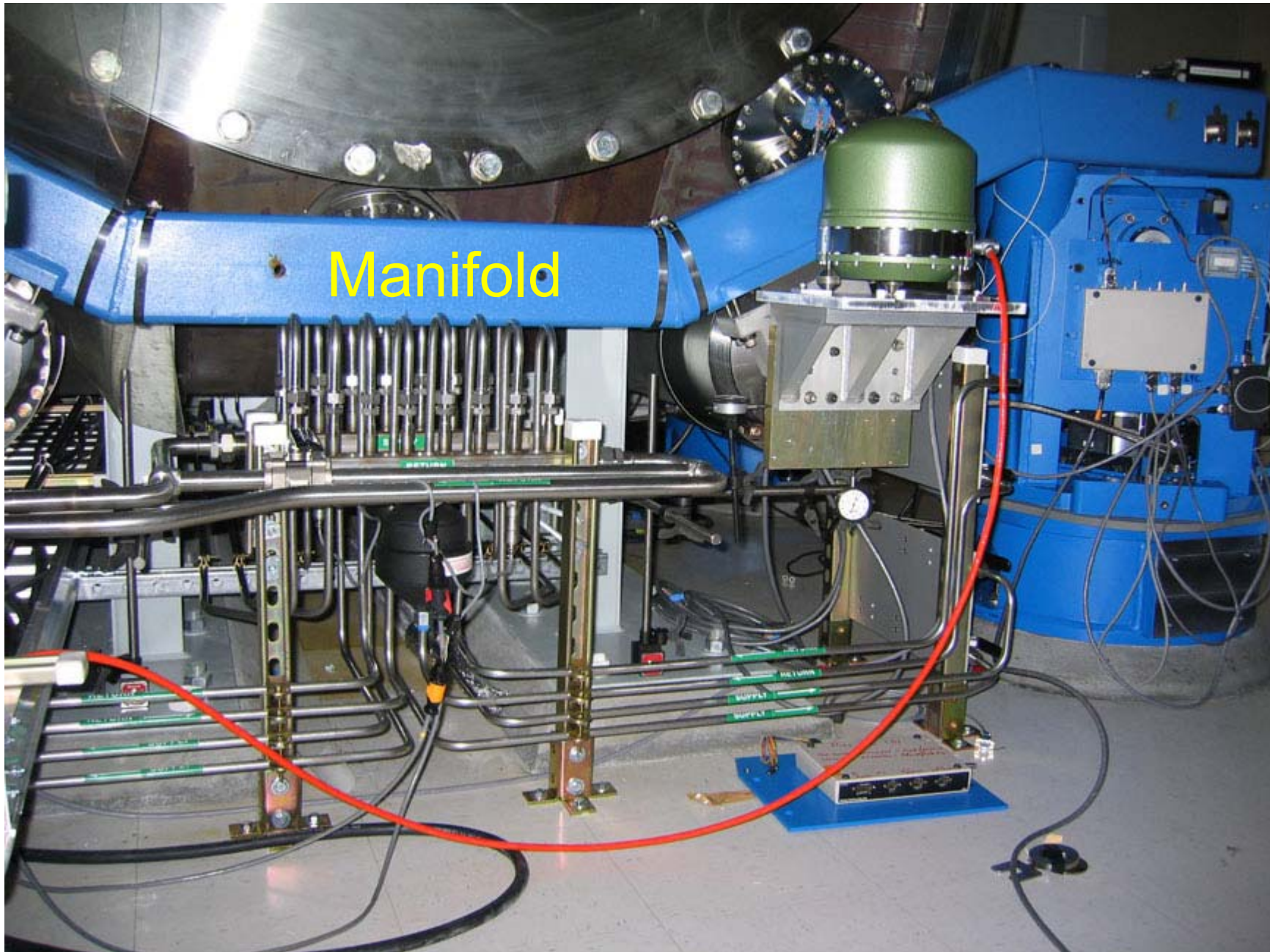
LIGO-G030653-00-Z

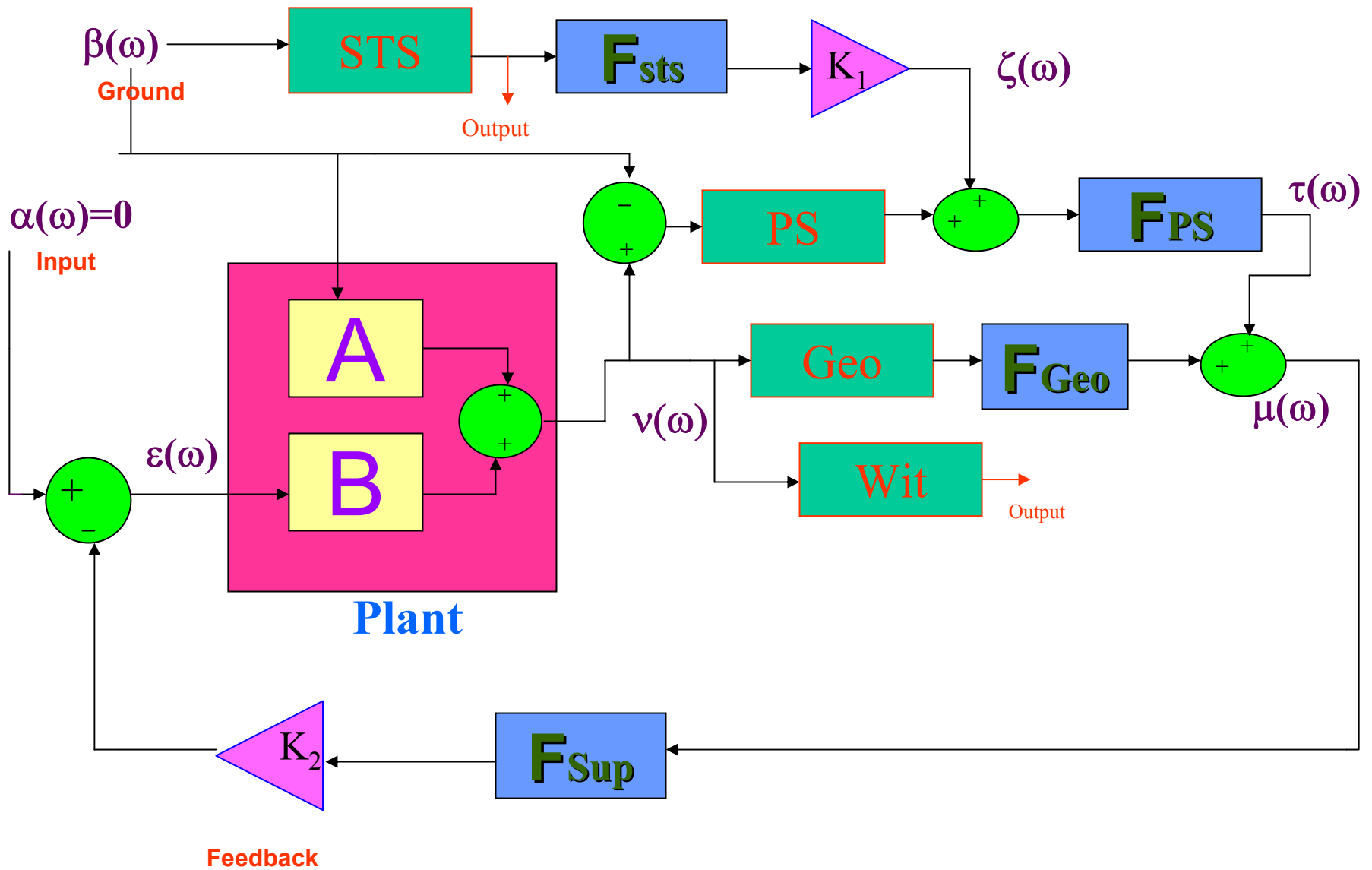
Ham Cross Beam



LIGO-G030653-00-Z

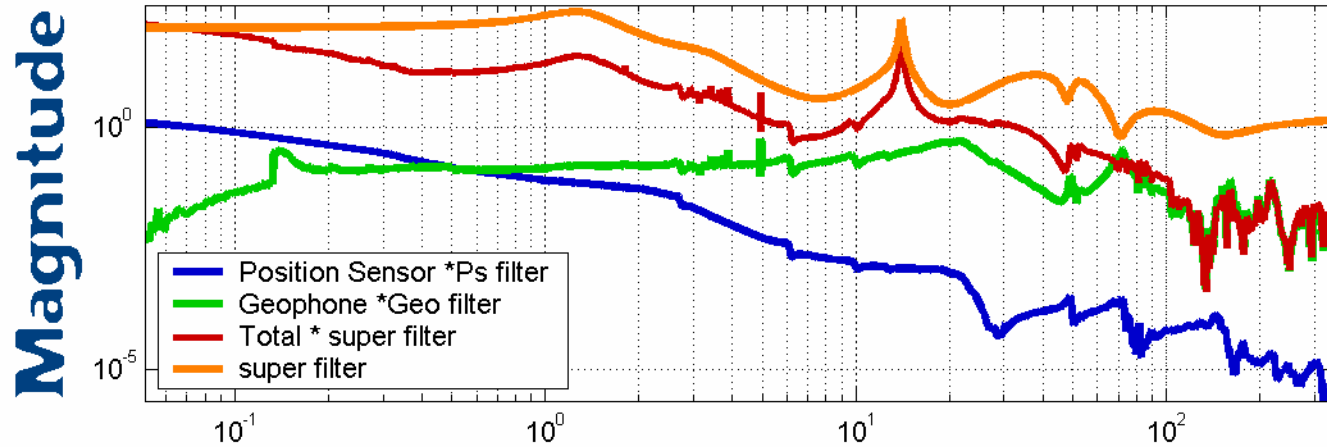
Manifold



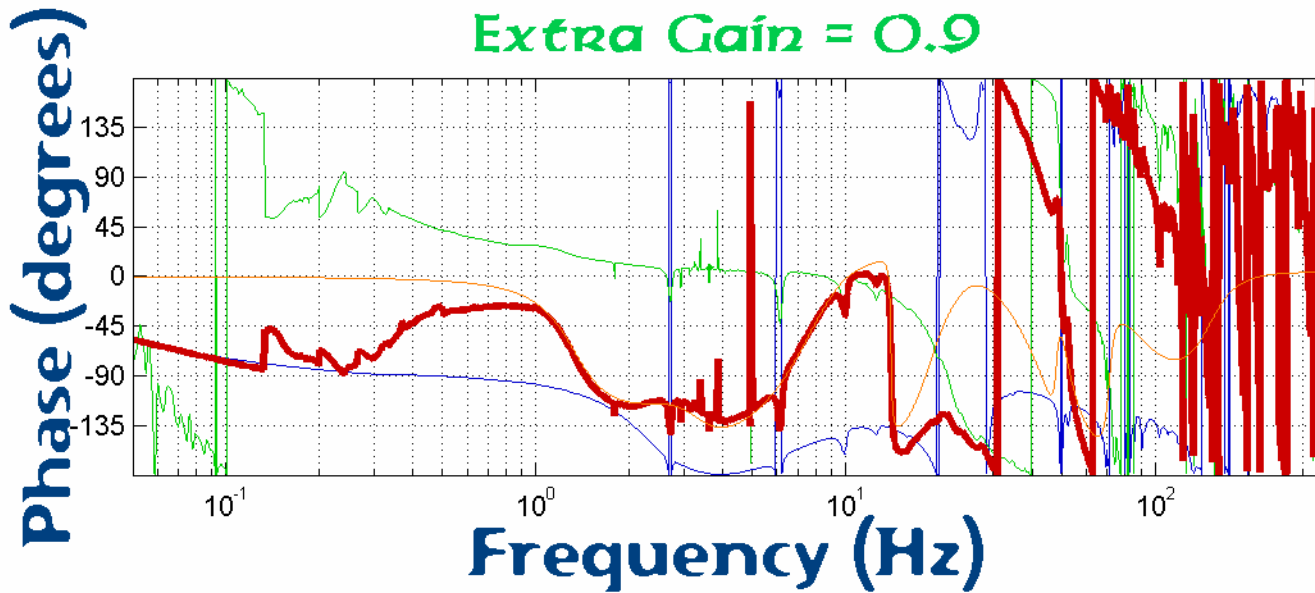


Control Strategy

ZZ MODE BLENDING



Extra Gain = 0.9



$$\chi_{PS} = PS \times B \quad \text{Transfer Function from dSpace to Position Sensors}$$

$$\chi_{Geo} = Geo \times B \quad \text{Transfer Function from dSpace to Support Table Geophones}$$

$$\chi_{sup} = F_{Geo} \chi_{Geo} + F_{PS} \chi_{PS} \quad \text{Open Loop transfer function}$$

$$\tilde{\chi}_W = A \times Wit / STS \quad \text{Transfer Function from Ground STS to Witness Sensor}$$

$$\chi_W = A \times Wit \quad \text{Transfer Function from dSpace to Witness Sensor}$$

$$\frac{\nu(\omega) \times Wit}{\beta(\omega) \times STS} = \frac{\tilde{\chi}_W - K_2 F_{sup} F_{PS} \times \left[K_1 F_{STS} \chi_{Wit} - \chi_{PS} \left(\frac{Wit}{STS} \right) \right]}{1 + K_2 \chi_{sup}}$$

Closed Loop Transfer Function from ground to witness sensor

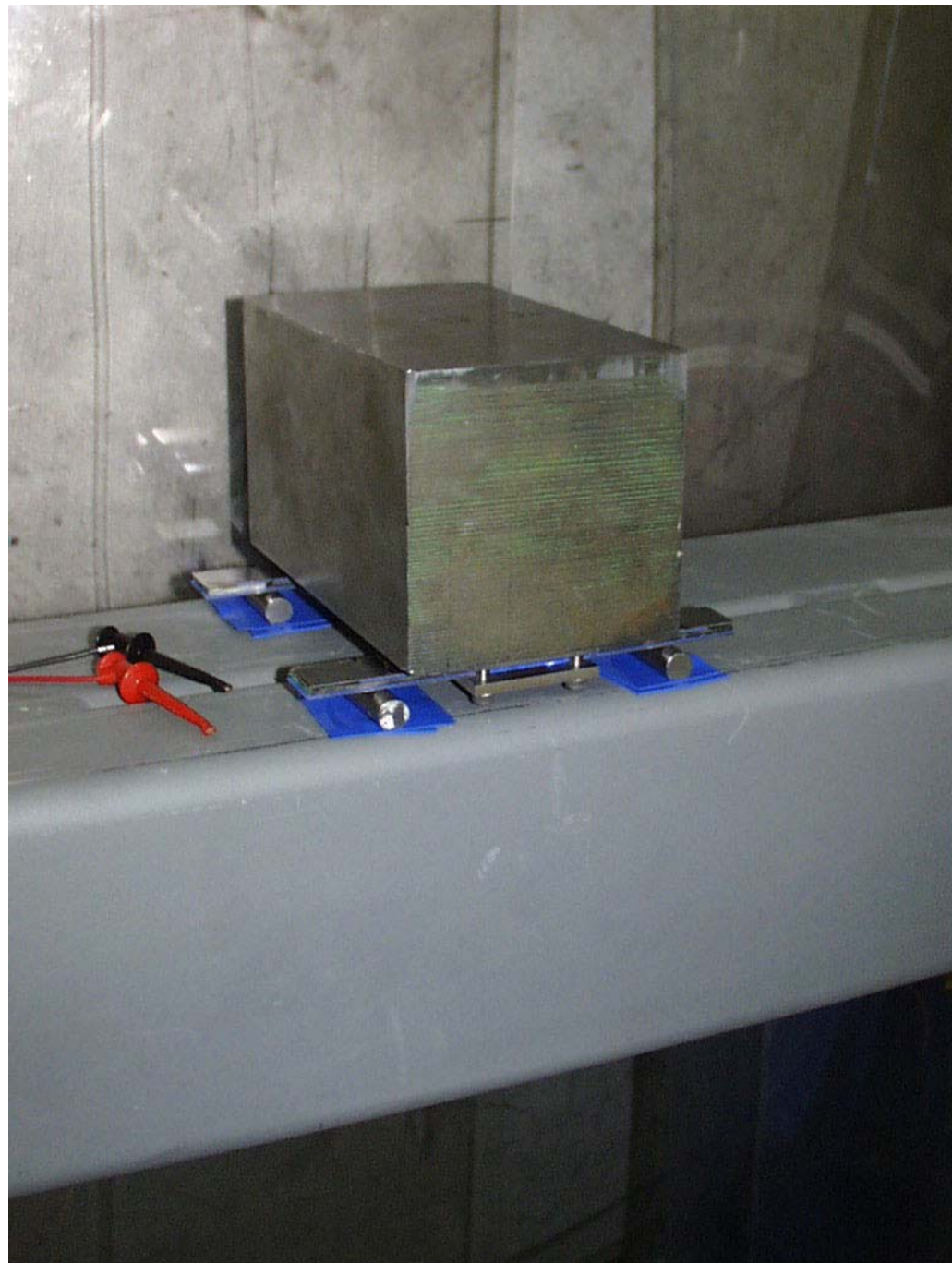
Tuned Mass Damper

Designed by

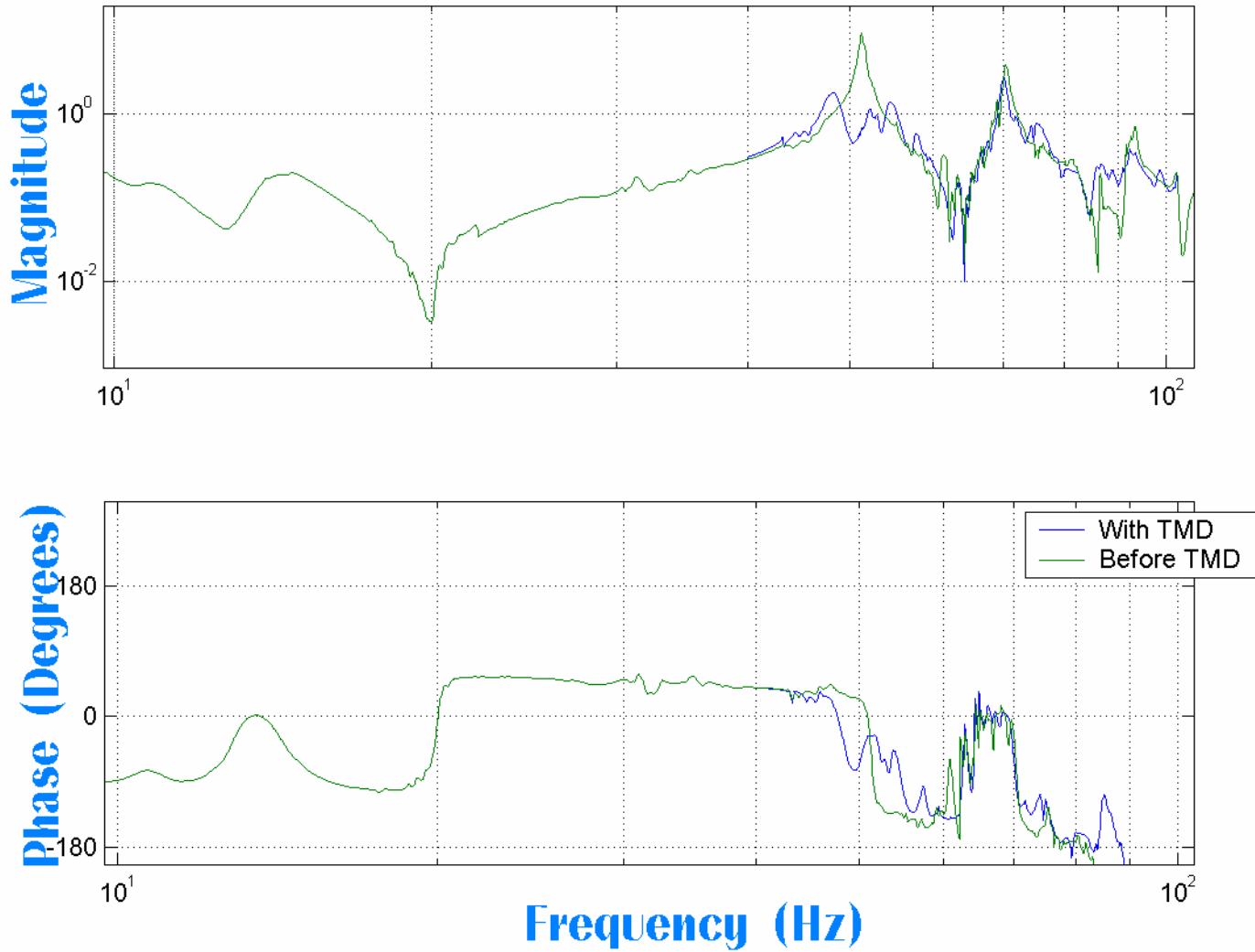
Lei Zuo

MIT

Mechanical
Engineering
Department

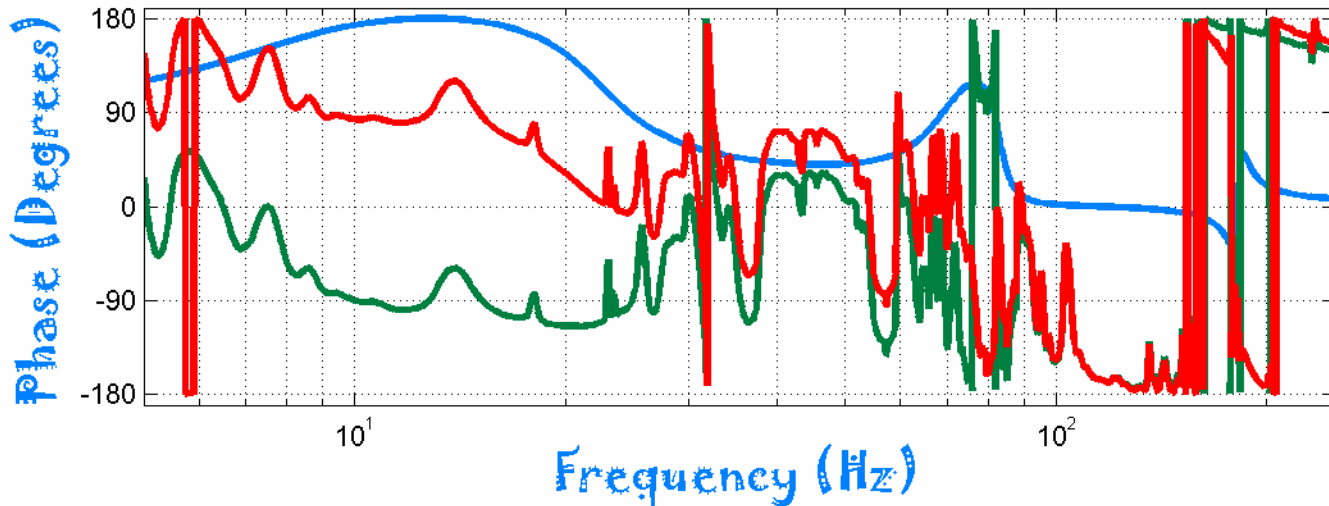
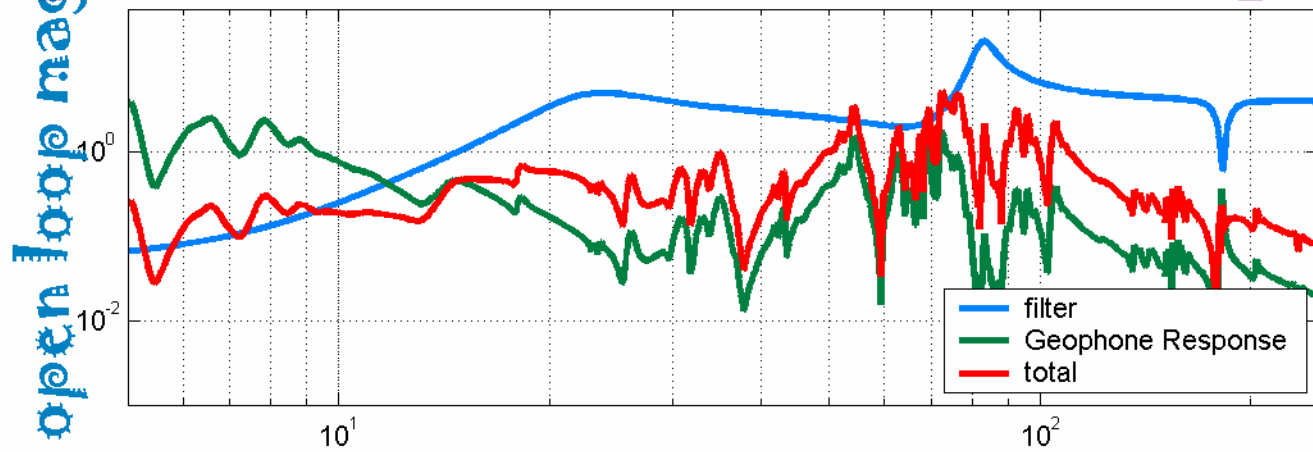


Y- (GEOPHONE) MODE PLANT MODIFICATIONS



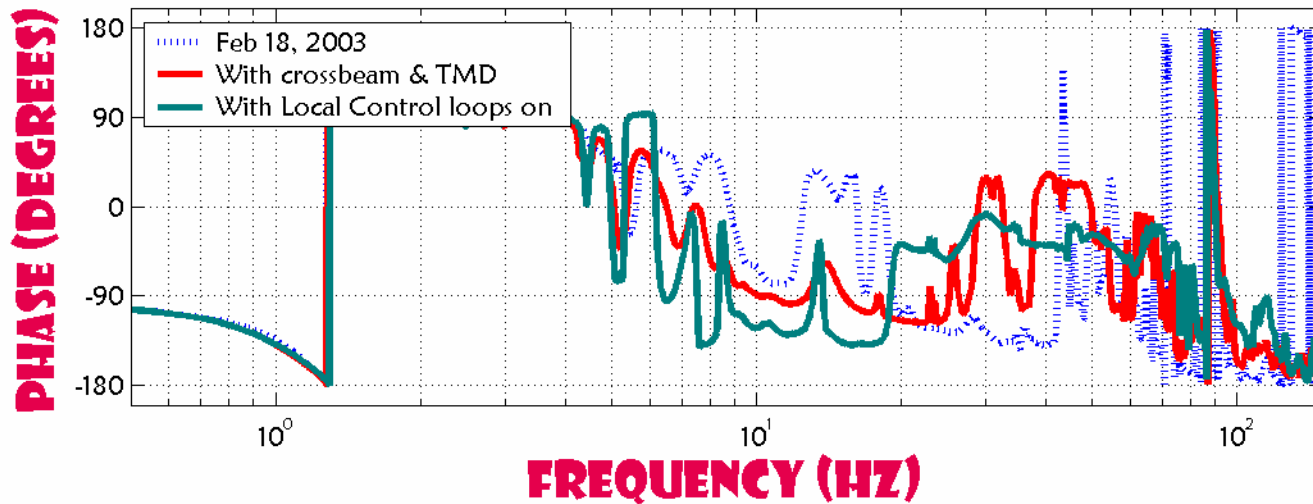
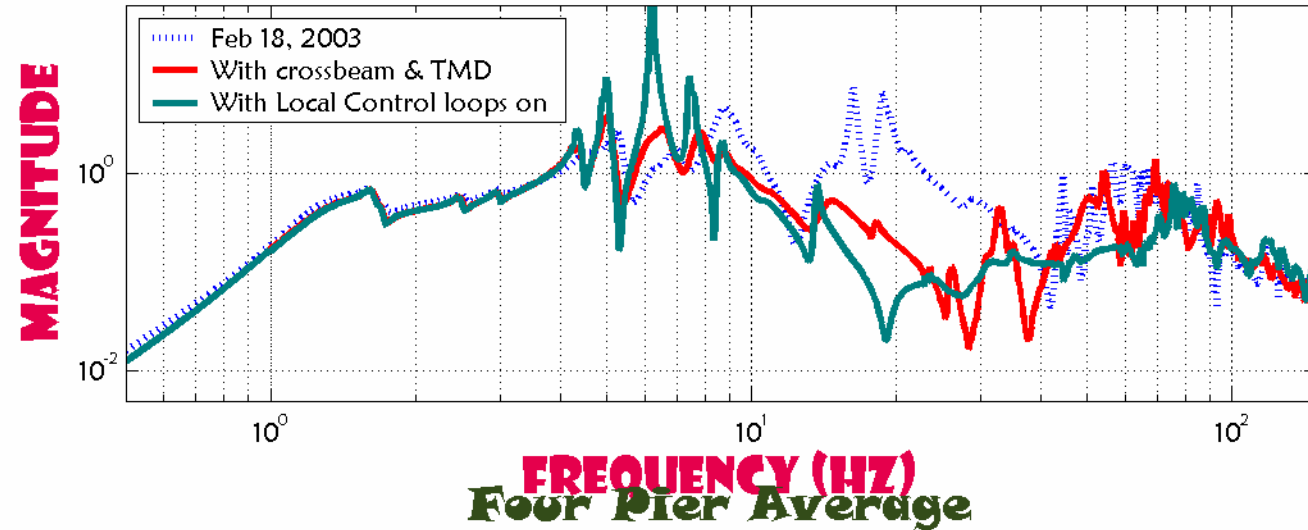
Local Control

Geophone Collocated H3 Local Loop Filter

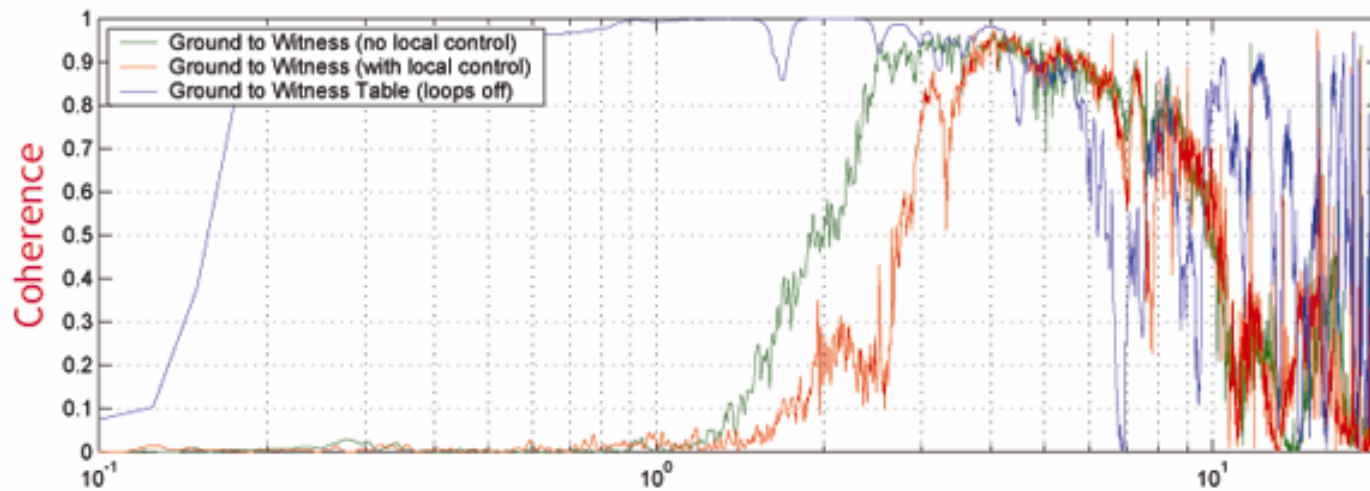
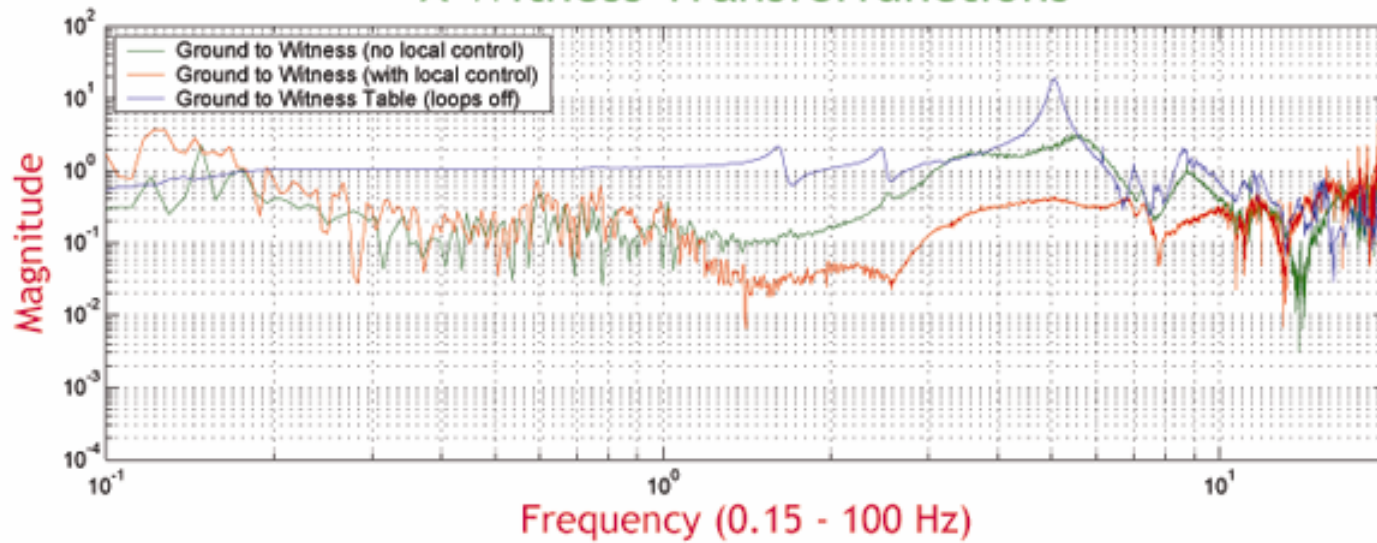


MEPI-Collocated

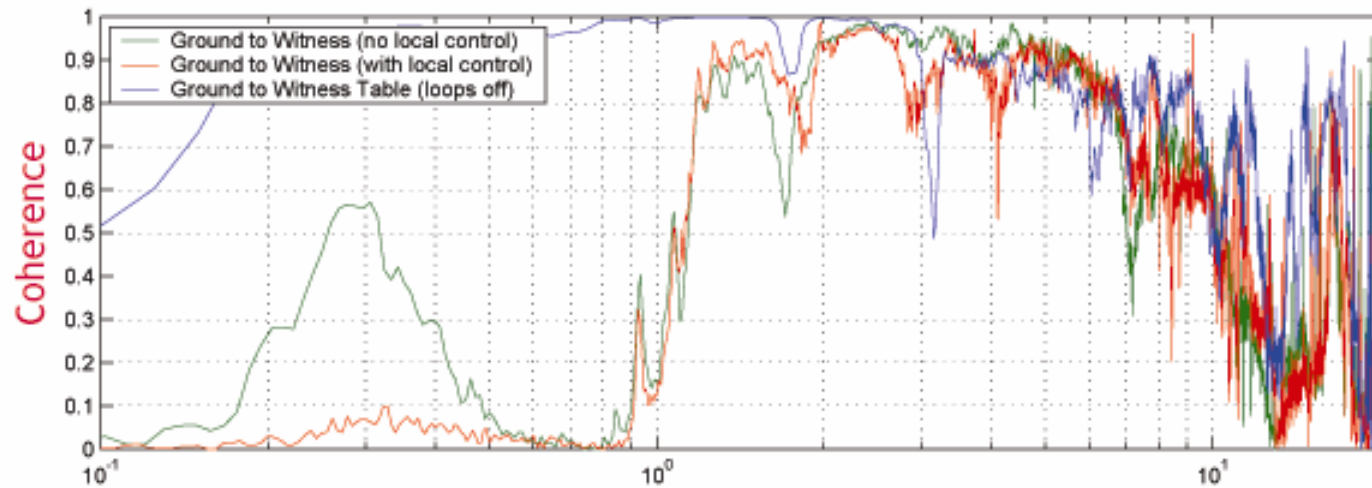
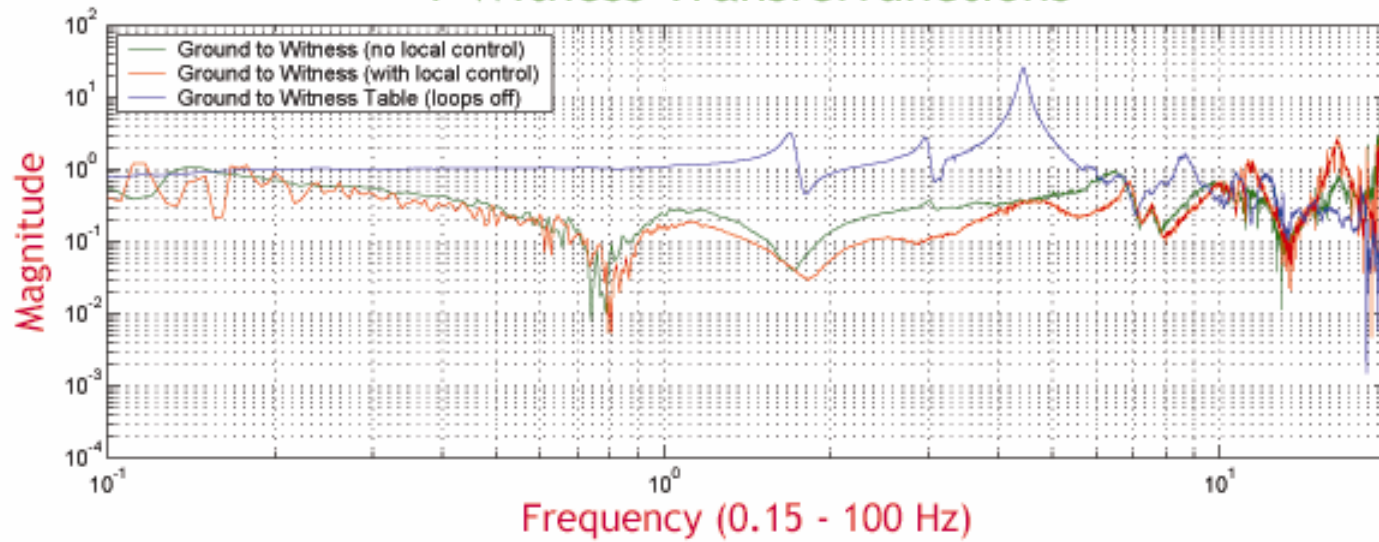
Collocated Horizontal Transfer Function:



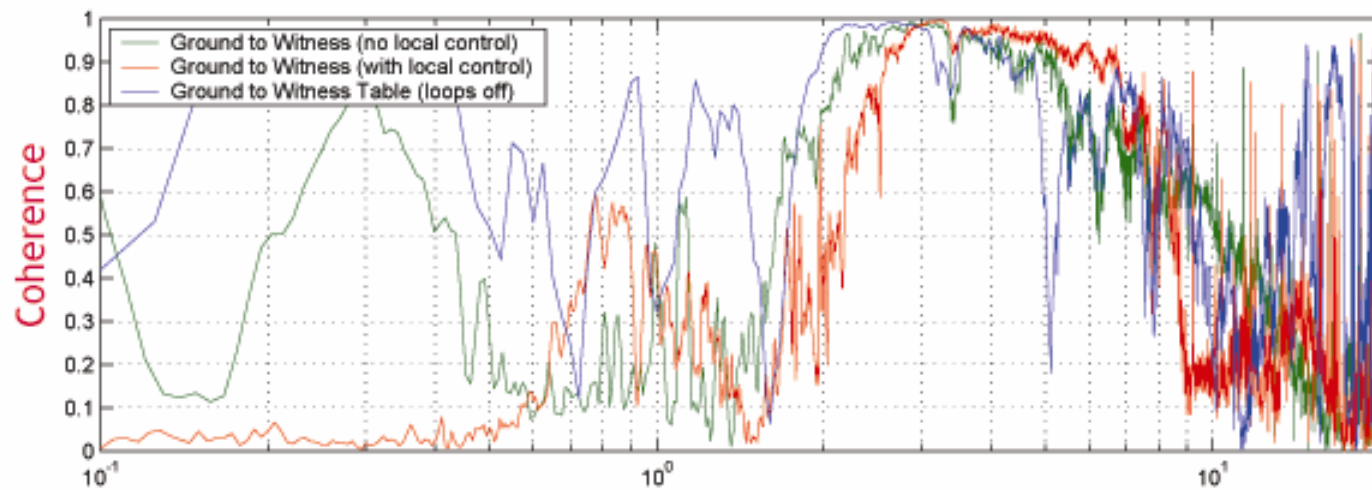
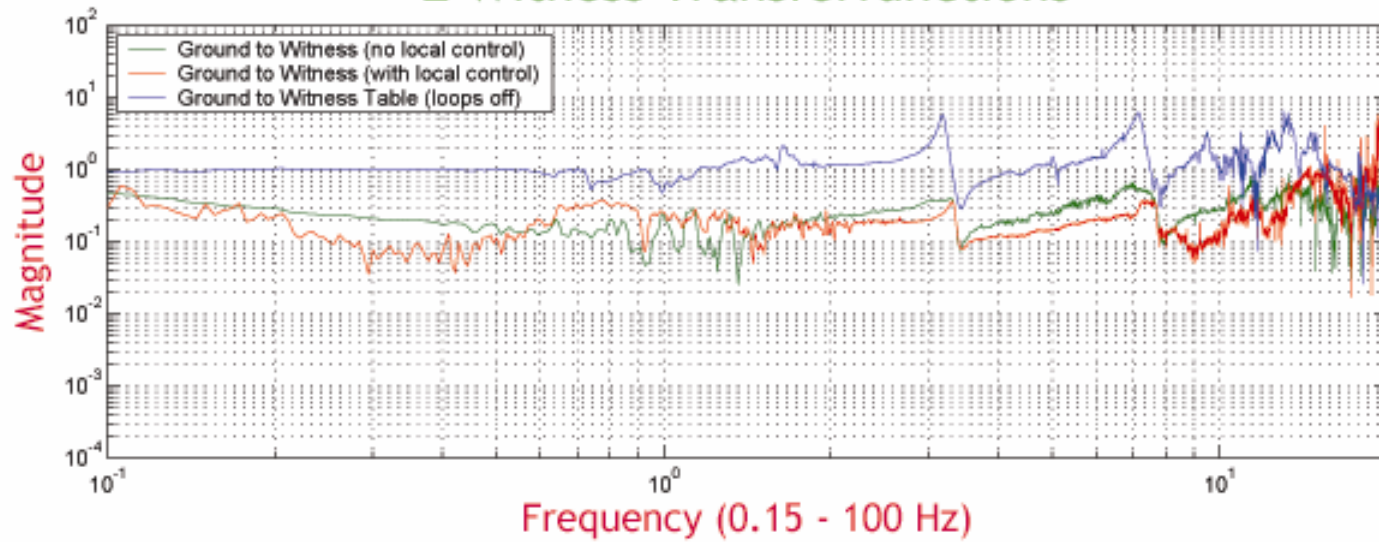
X Witness Transferfunctions



Y Witness Transferfunctions

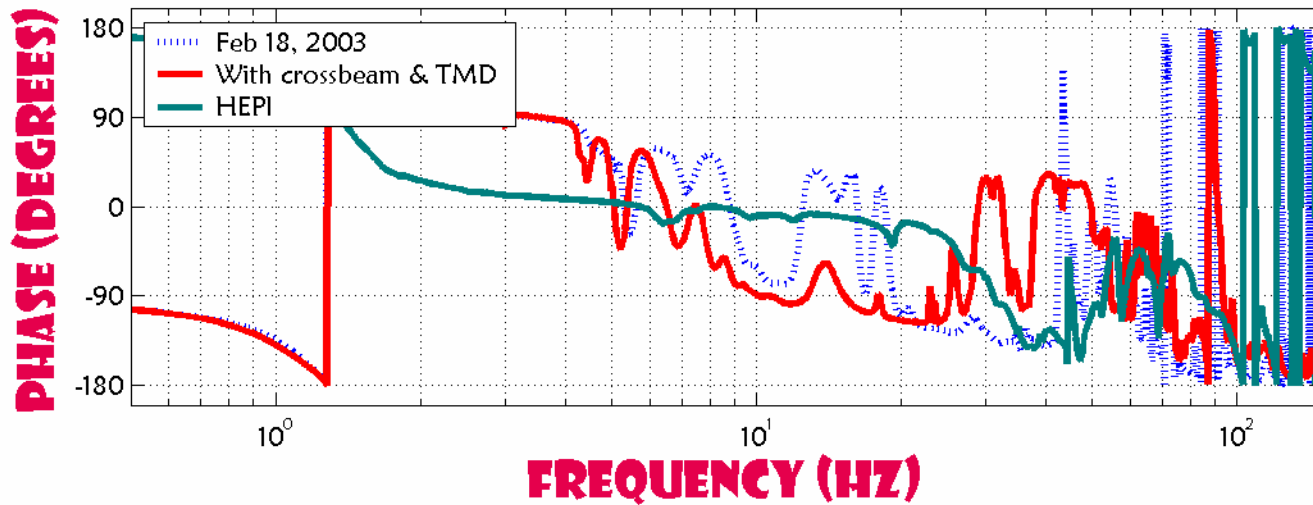
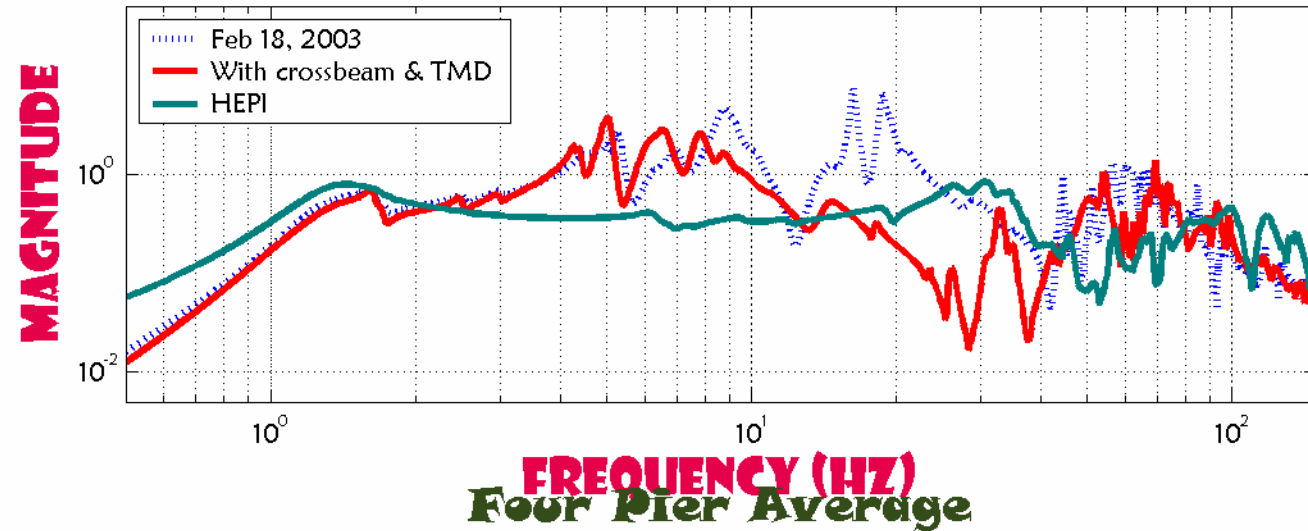


Z Witness Transferfunctions

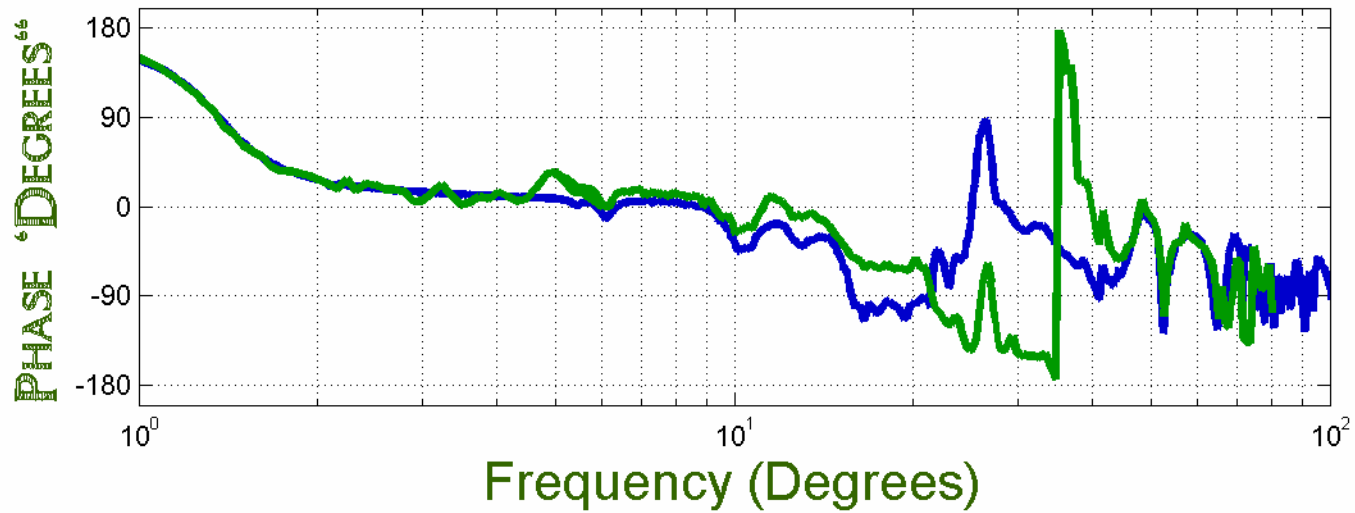
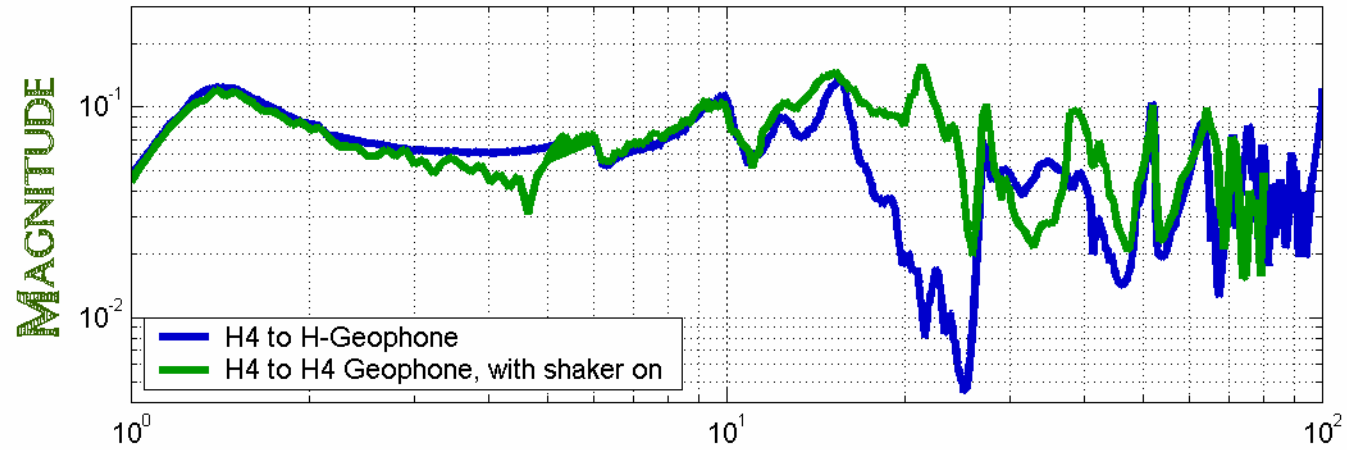


Hepi/Mepi

Collocated Horizontal Transfer Function:

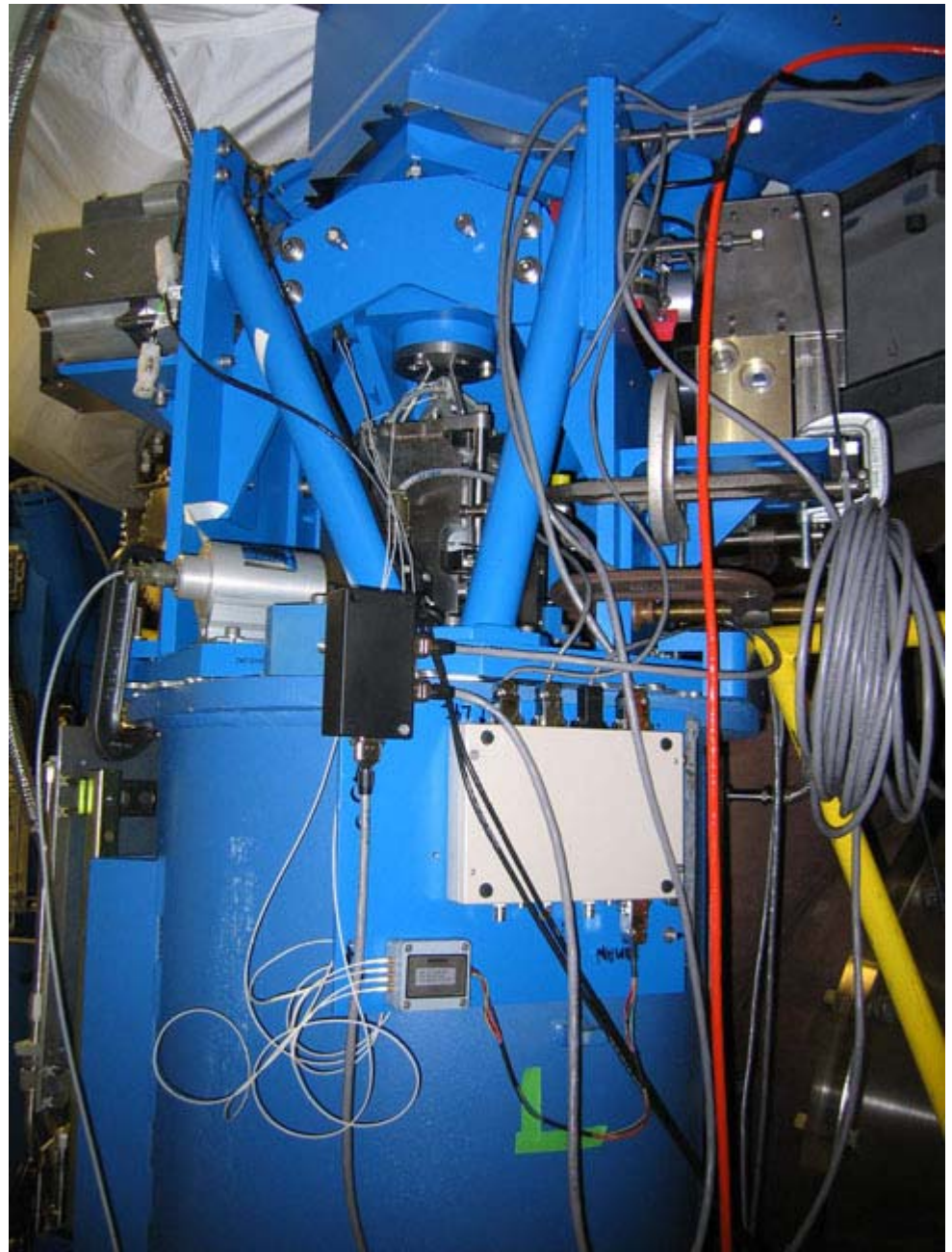


Dynamic Pier Stiffening

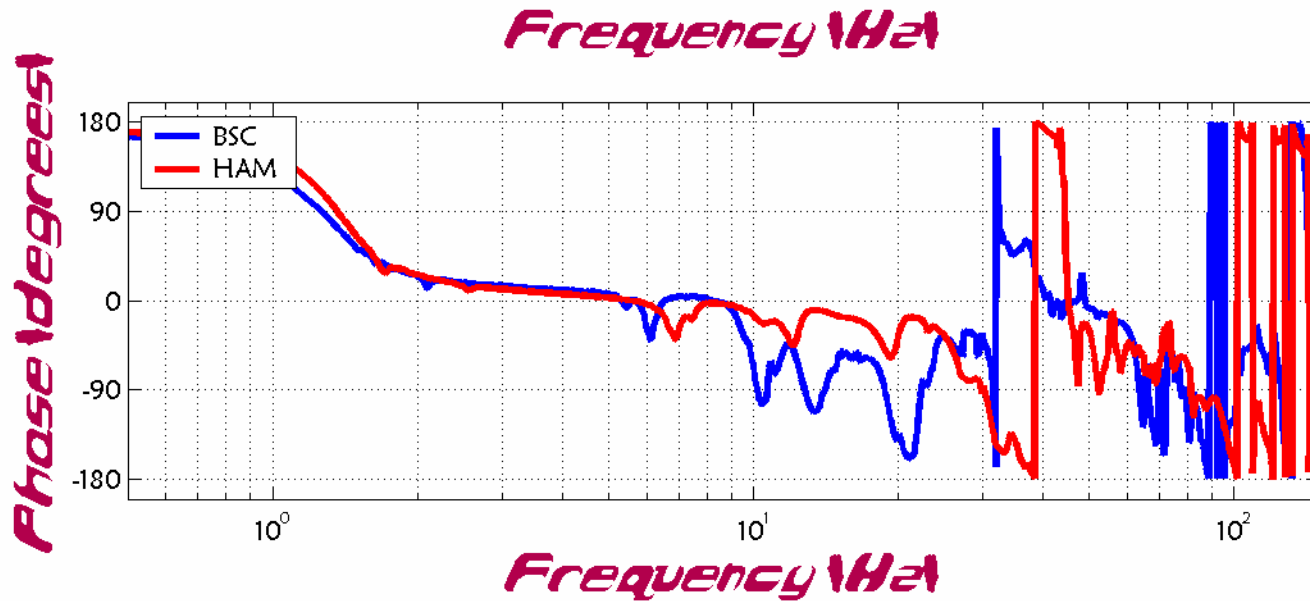
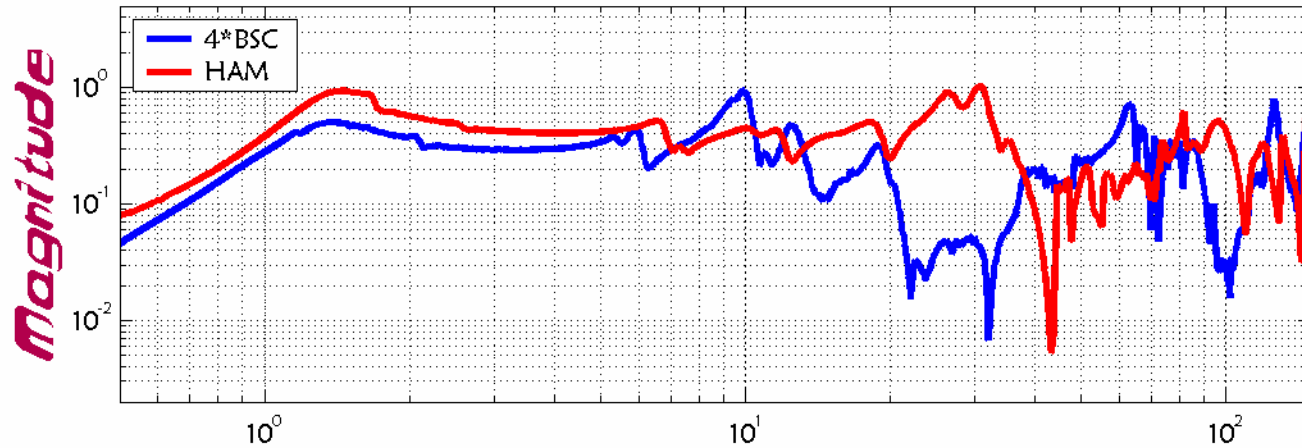


BSC Pier

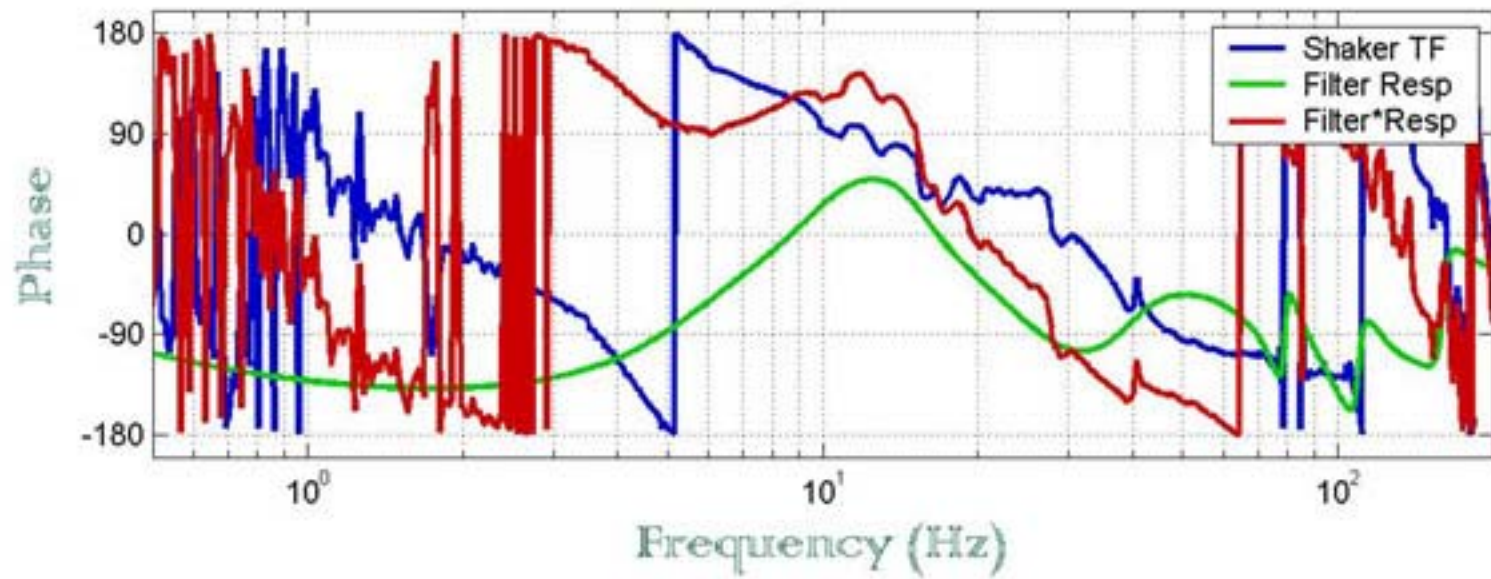
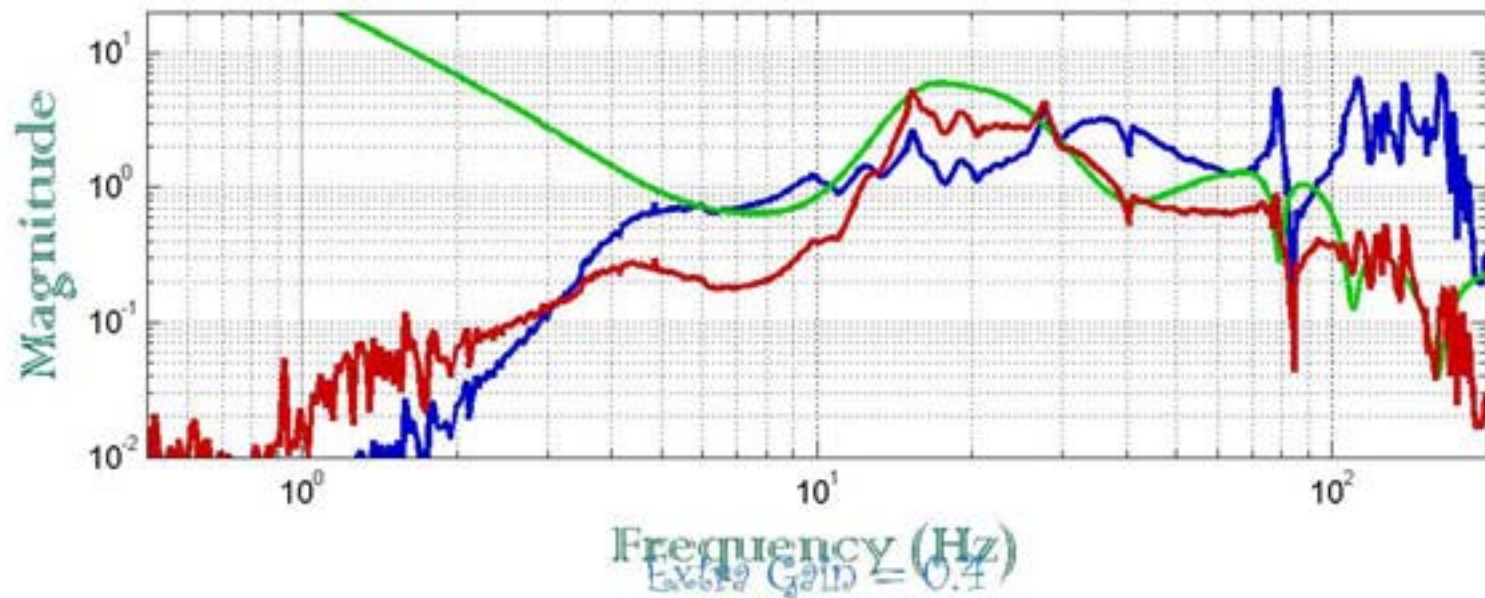
We have tried to
dynamically stiffen the
BSC piers



X Mode Transfer Function

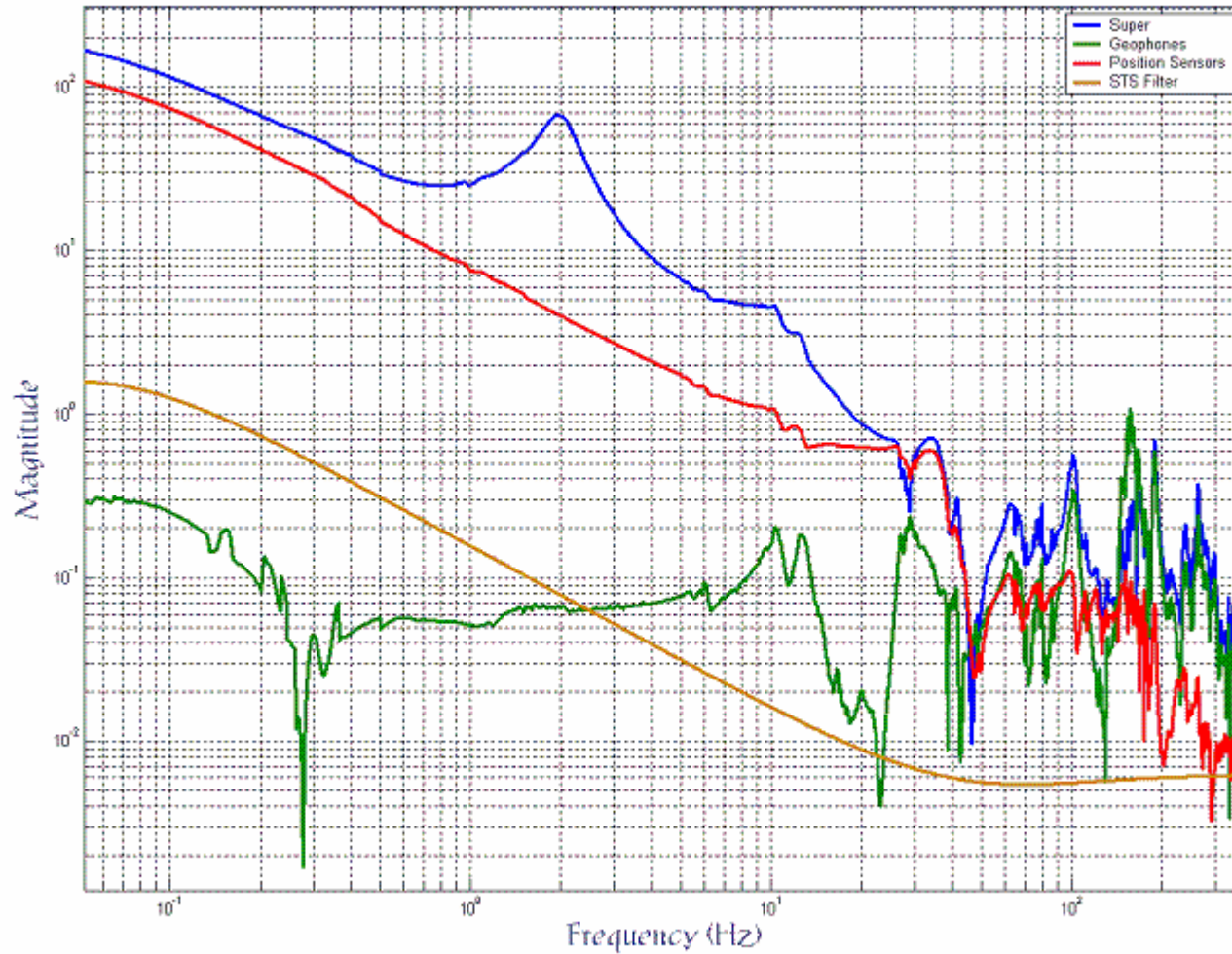


SHAKER FILTERING



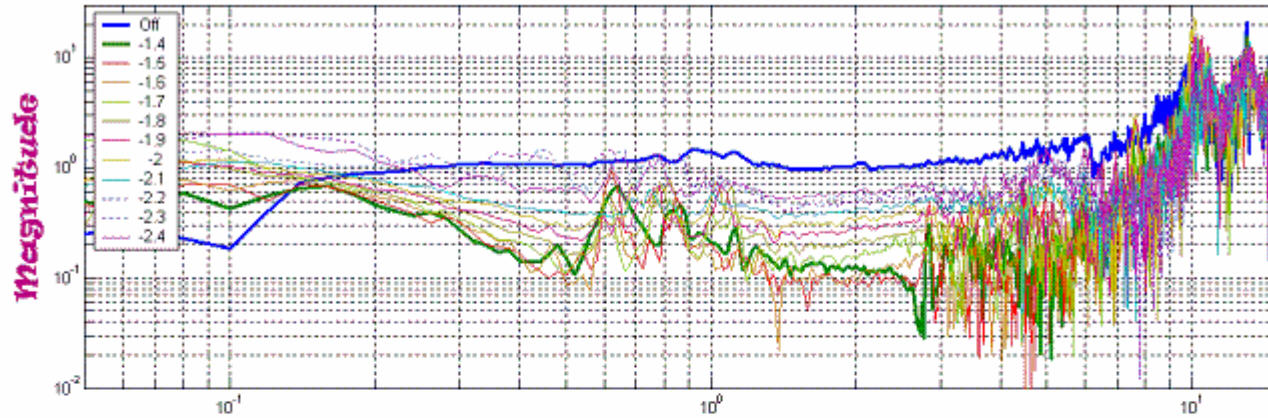
BSC X Filters

* MODE LOOP GAIN AND FILTERS

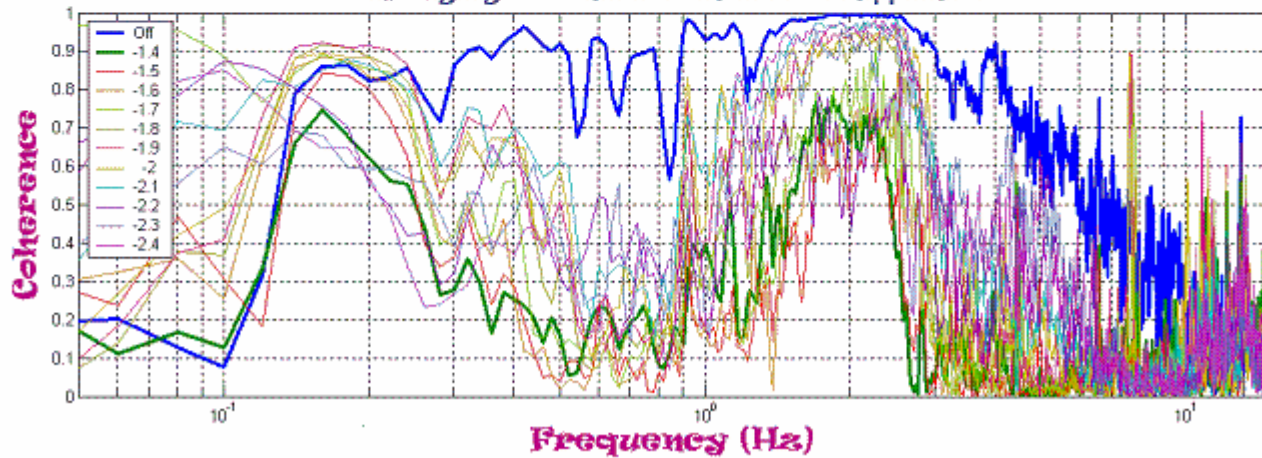


BSC Isolation (X)

GROUND X TO SUPPORT TABLE STRECKHEIMEN

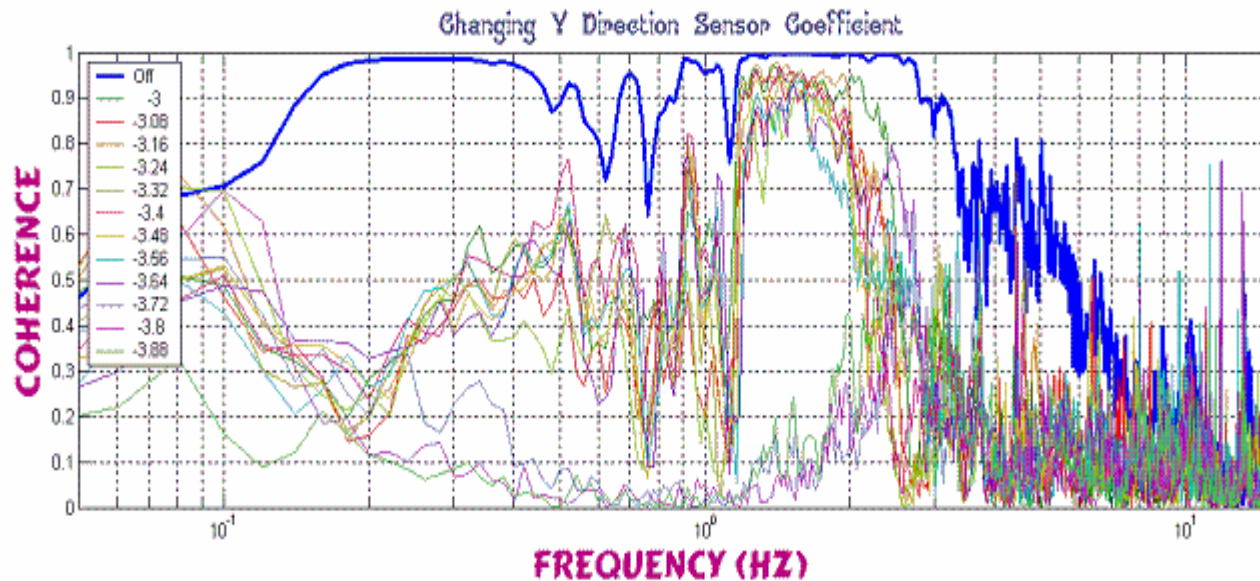
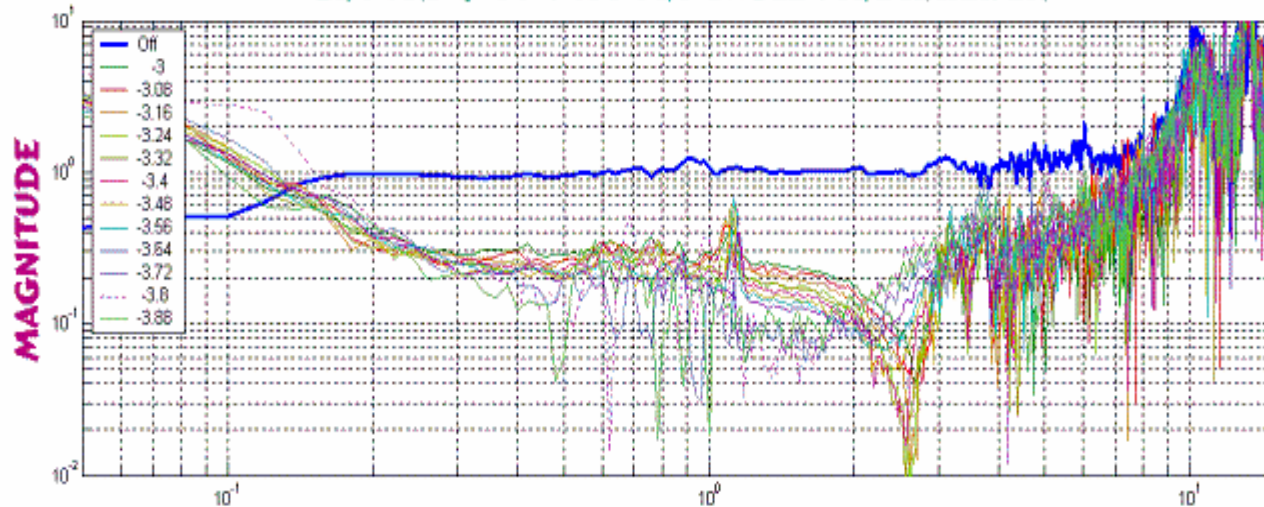


Changing X Direction Sensor Coefficient



BSC Isolation Y

GROUND Y TO SUPPORT TABLE STRECKHEIEN



Sensor Correction Response (Y-Mode)

