



Pre-isolation at LIGO Livingston—status and plans

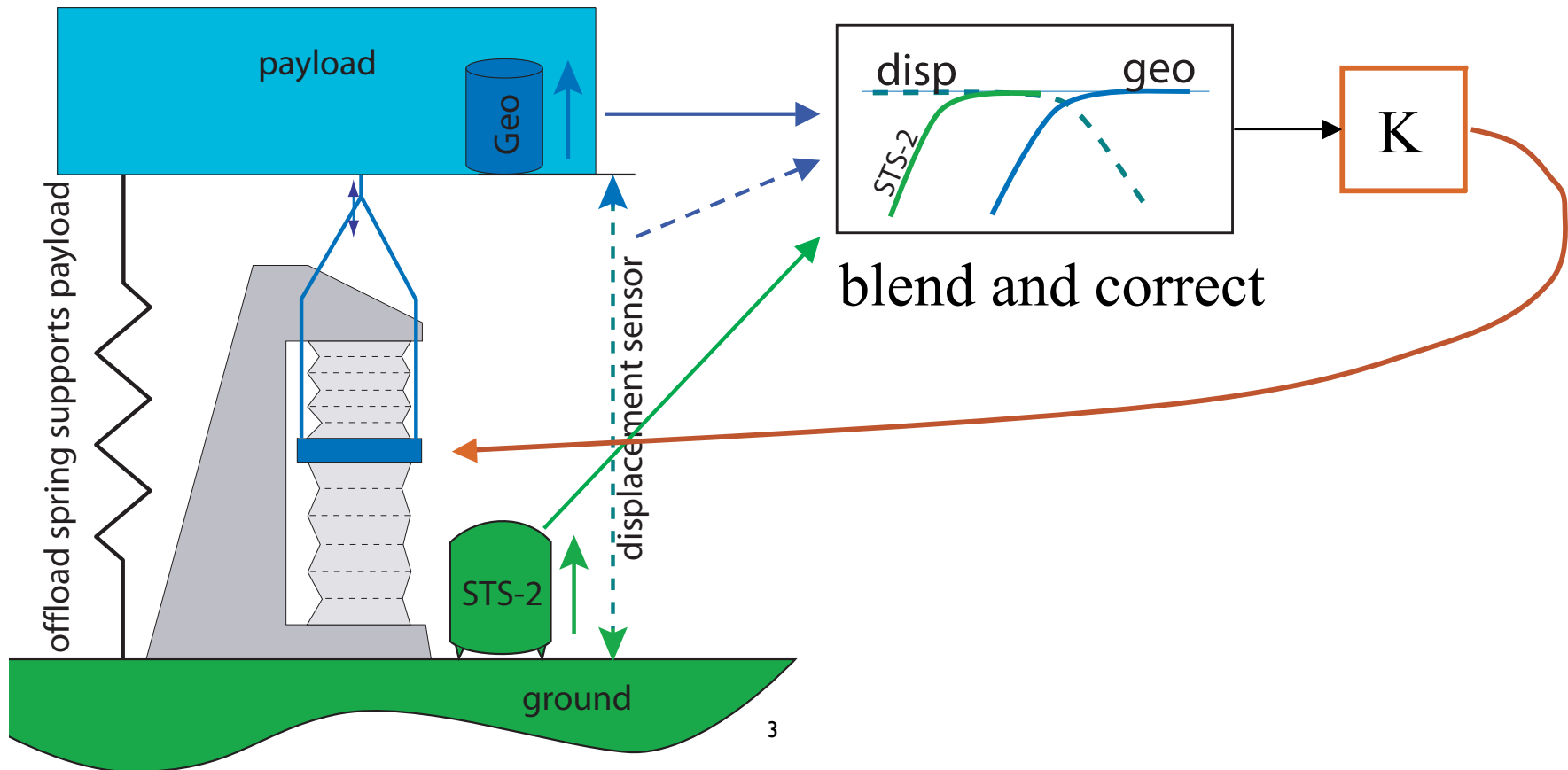
Joe Giaime, for the seismic team and LLO.

Development history

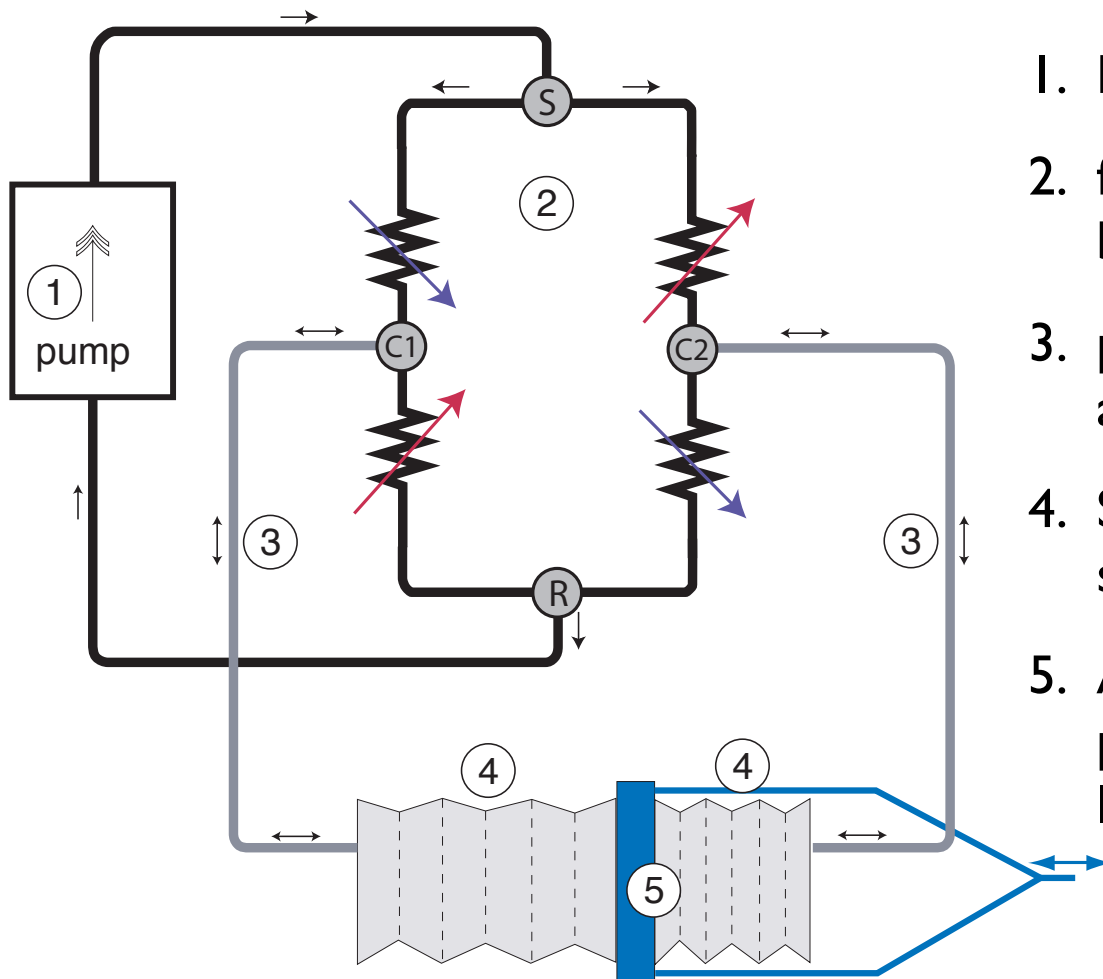
- Decades of R&D on quiet hydraulics with Dan DeBra at Stanford, focussing on use of laminar flow oil to actuate machine tool assemblies.
- Recent development & prototyping of zero-stiction balanced bellows quiet hydraulic actuators, by DeBra, Hardham, Lantz et al, intended for use in Advanced LIGO pre-isolation stage. 2-DOF test stand experiment.
- Study by Hua et al of effective control filter techniques for ‘sensor correction’ active seismic isolation at sub-hertz frequencies.
- Design of third-generation actuator, payload suspension springs, and external housing for HEPI by Hardham, Hammond, Mason, Kern, Lacour, etc.
- Tests at LASTI (ongoing) by Mason, Hardham, Coyne, Lantz, Mittleman, Ottaway, Sarin, Macinnis, etc. New ‘safe’ fluid in use, tested at CIT.
- Re-implementation of control system and electronics for LIGO/VME environment and GDS by Bork, Sarin, Abbott(s), etc.
- Mass production and installation at LLO, by Kern, Abbott, Spjeld, Lacour, Traylor, Overmier, Mailand, and many more.
- general organization by Coyne, Kern, Abbott, Lantz and Giaime.

Low-frequency pre-isolation

- At each tank corner pier, there is a sensor/actuator set, vertical and horizontal.
- Each DOF controlled with respect to HEPI displacement sensors and geophones.
- Displacement sensor corrected for floor motion as measured by Streckeisen STS-2., in x, y, z DOF's.



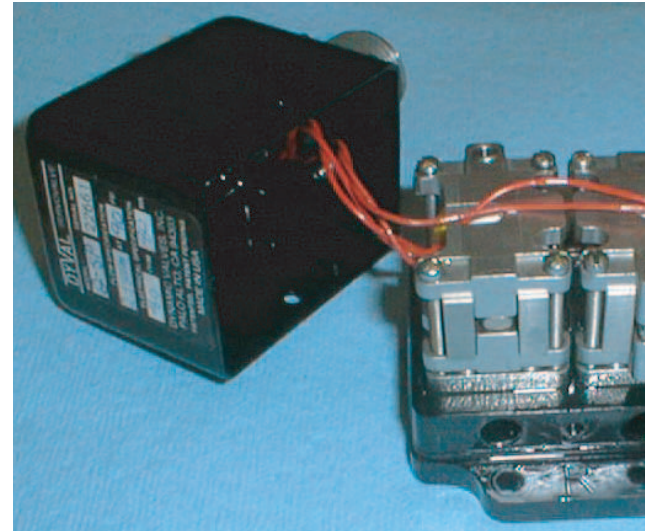
Hydraulic bridge actuation



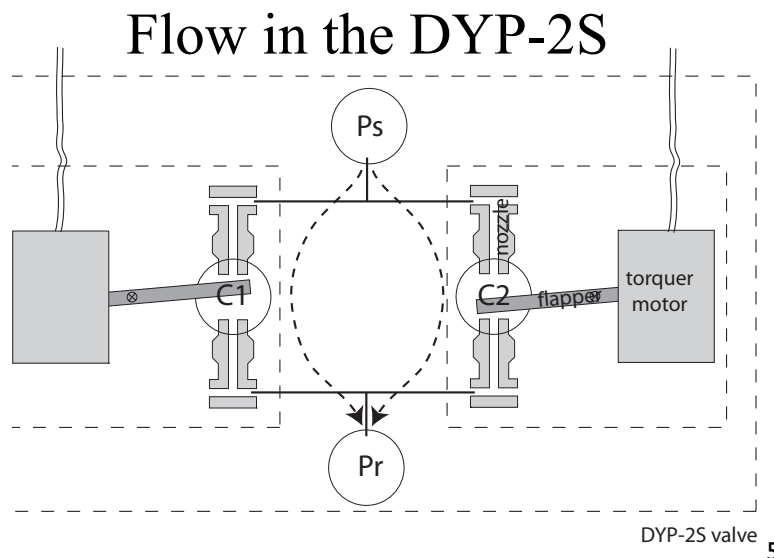
1. Pressure-stabilized pump.
2. four-valve flow-resistance bridge.
3. pipes connect bridge to actuator.
4. Stiction-free bellows on each side of actuated plate.
5. Actuated plate connected to payload through I-DOF linkage.

Valve modification

- Hardham, Lantz, DeBra designed new nozzles for valve, to allow laminar flow and large linear bridge response.
- New nozzles procured, but need to be installed and adjusted by hand.



Parker DYP-2S valve



The new nozzle

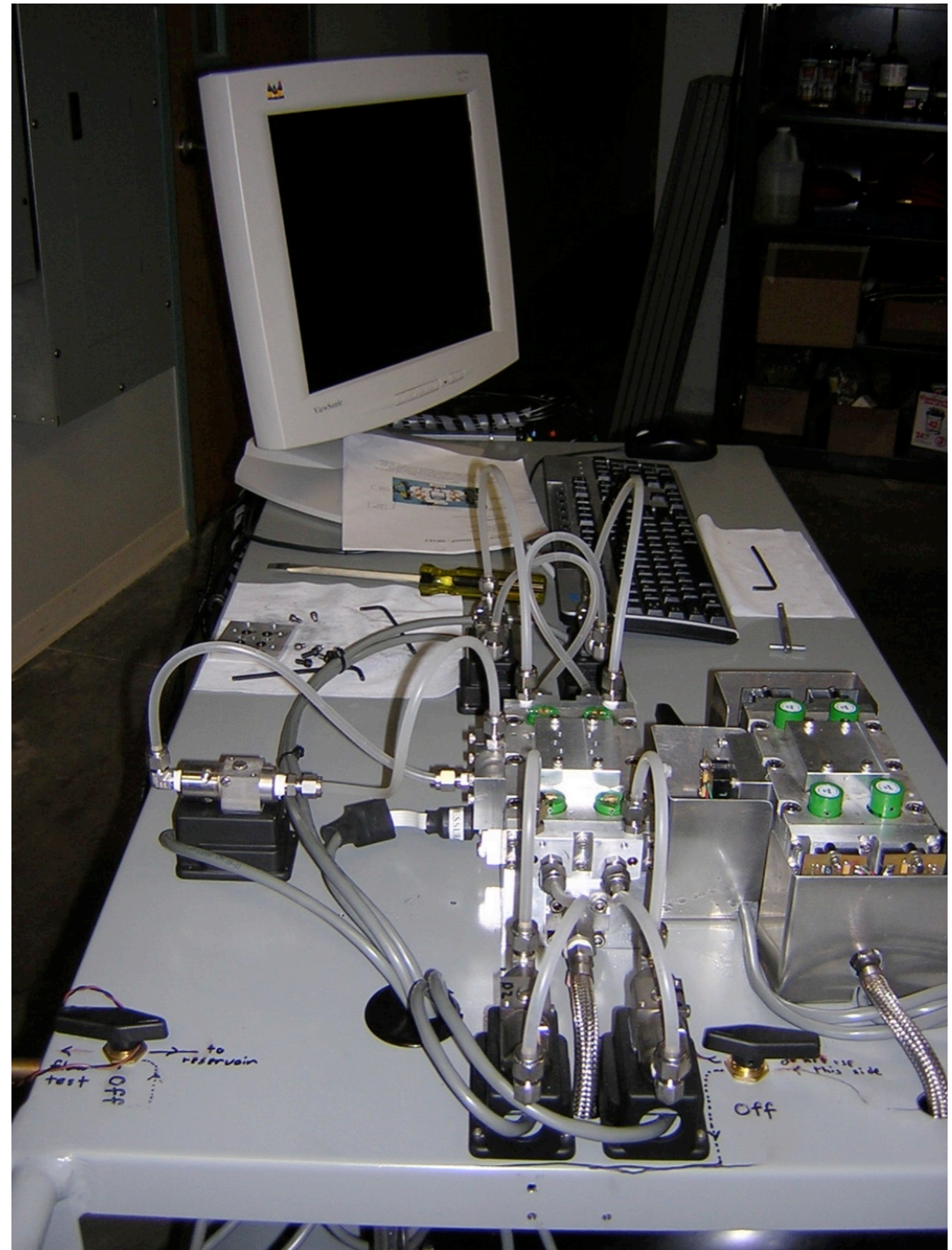


original

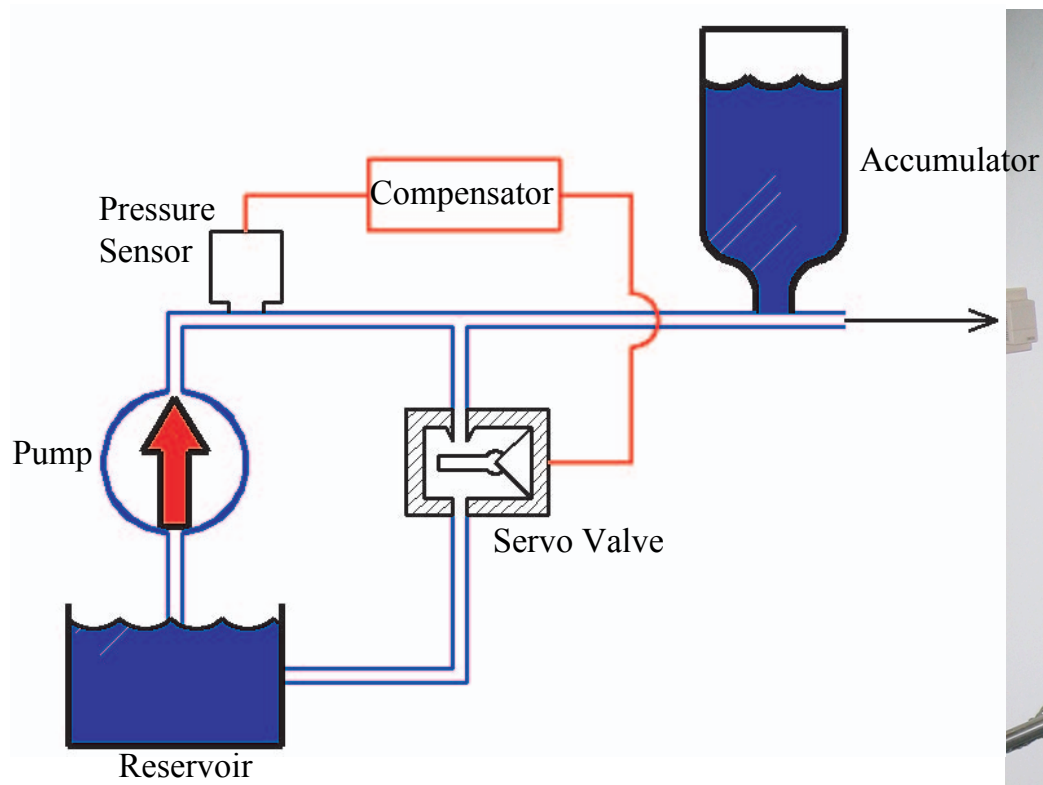
new

Valve calibration stand

- Valve adjustment jig designed at Stanford by Ganguli and Campbell.
- Replicated at LLO by Kern, Sellers, Abbot and Carter.
- Reworked after new 'safe' fluid destroyed the pressure sensors, and other surprises.
- 40 valves completed so far, by Carter & Evans.



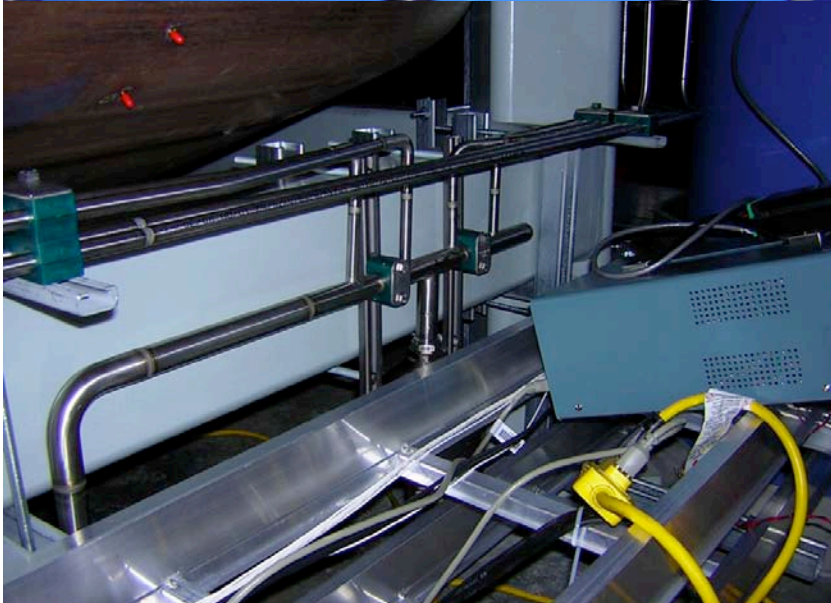
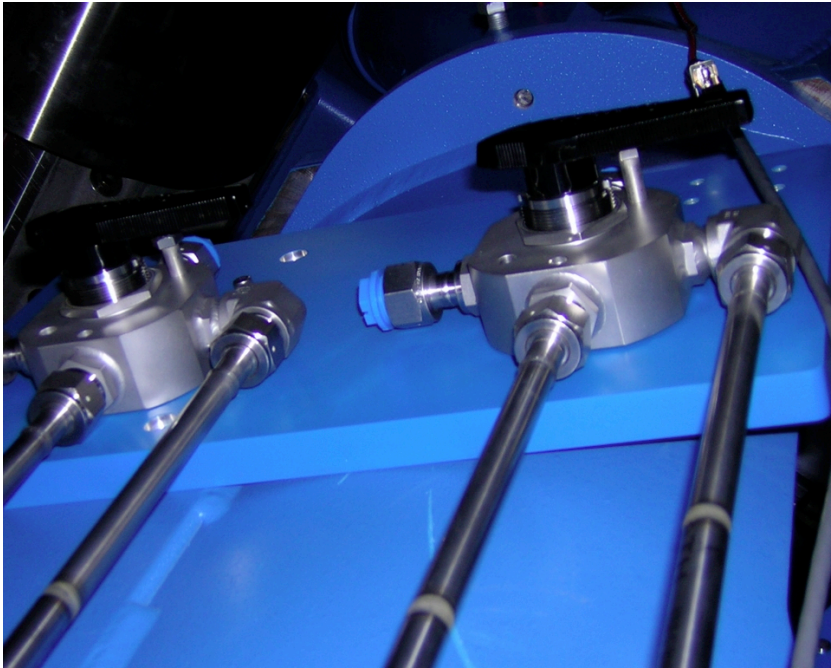
Pump stand



Design by Ken Mailand



Plumbing and wiring.



Abbots,
Kern,
Excel,
Hanson,
8 etc.



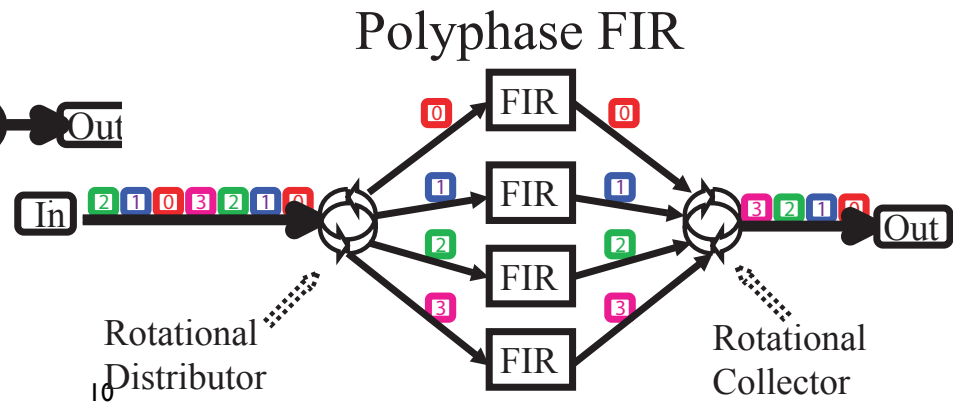
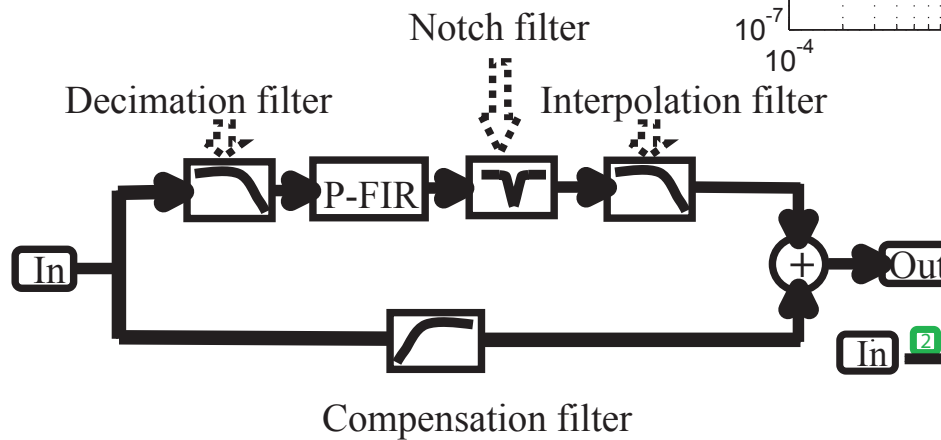
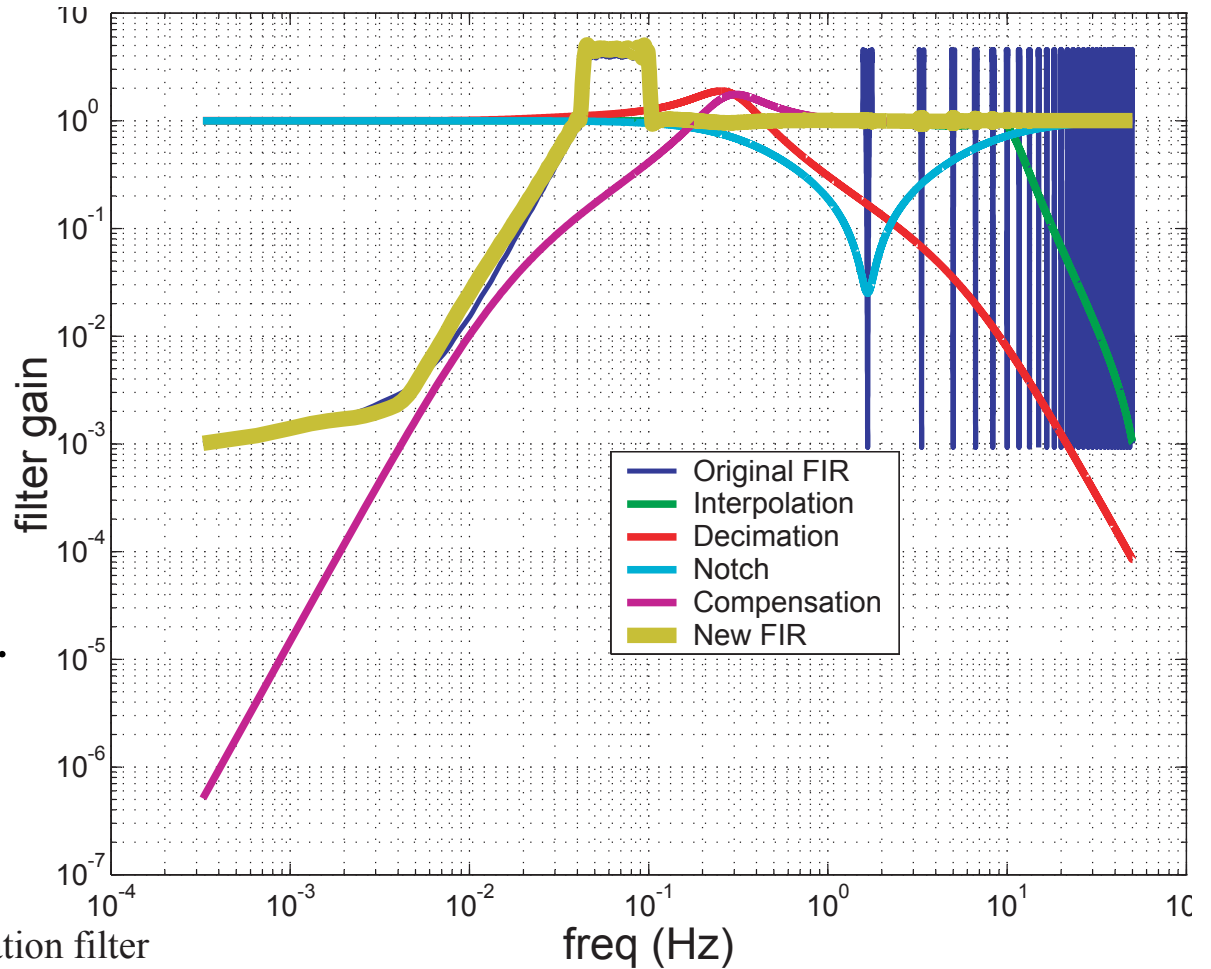
Mass production

9 LLO & 2 LASTI tanks, lots of parts!

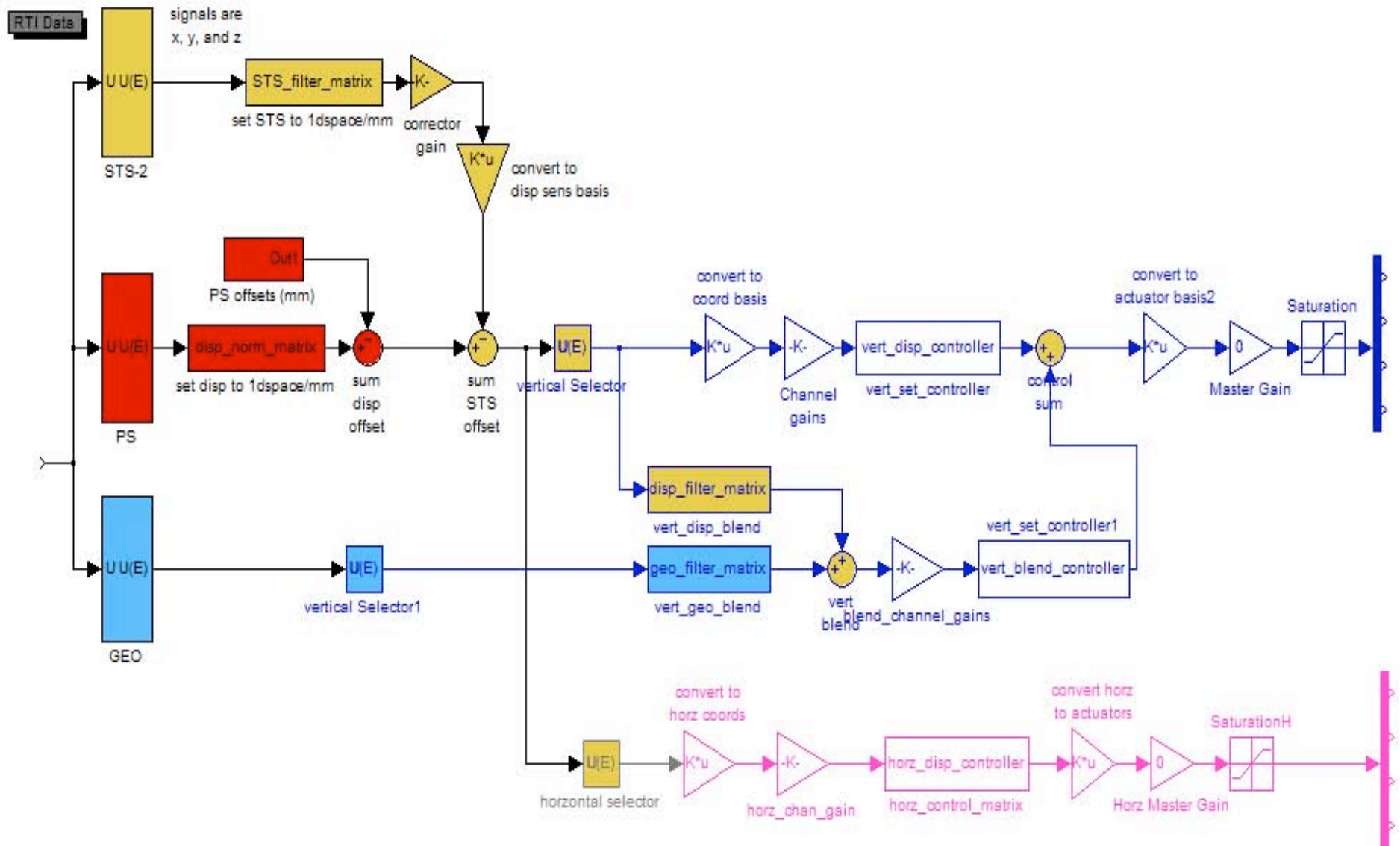


Efficient polyphase FIR (W. Hua)

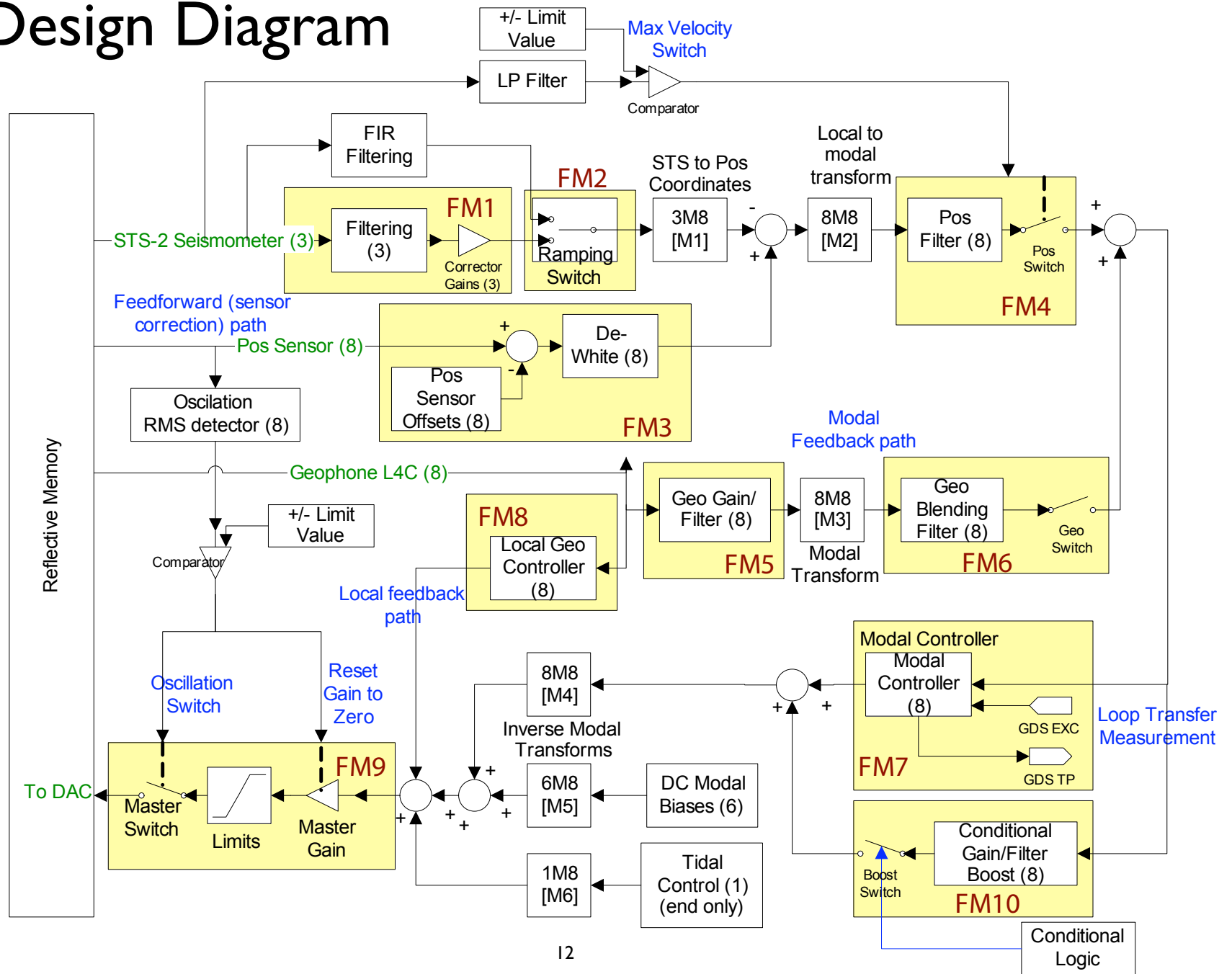
- Eliminates low-frequency noise and artifacts from sensor correction signal.
- Avoids excessive phase and amplitude mismatch in band.
- Computationally efficient.



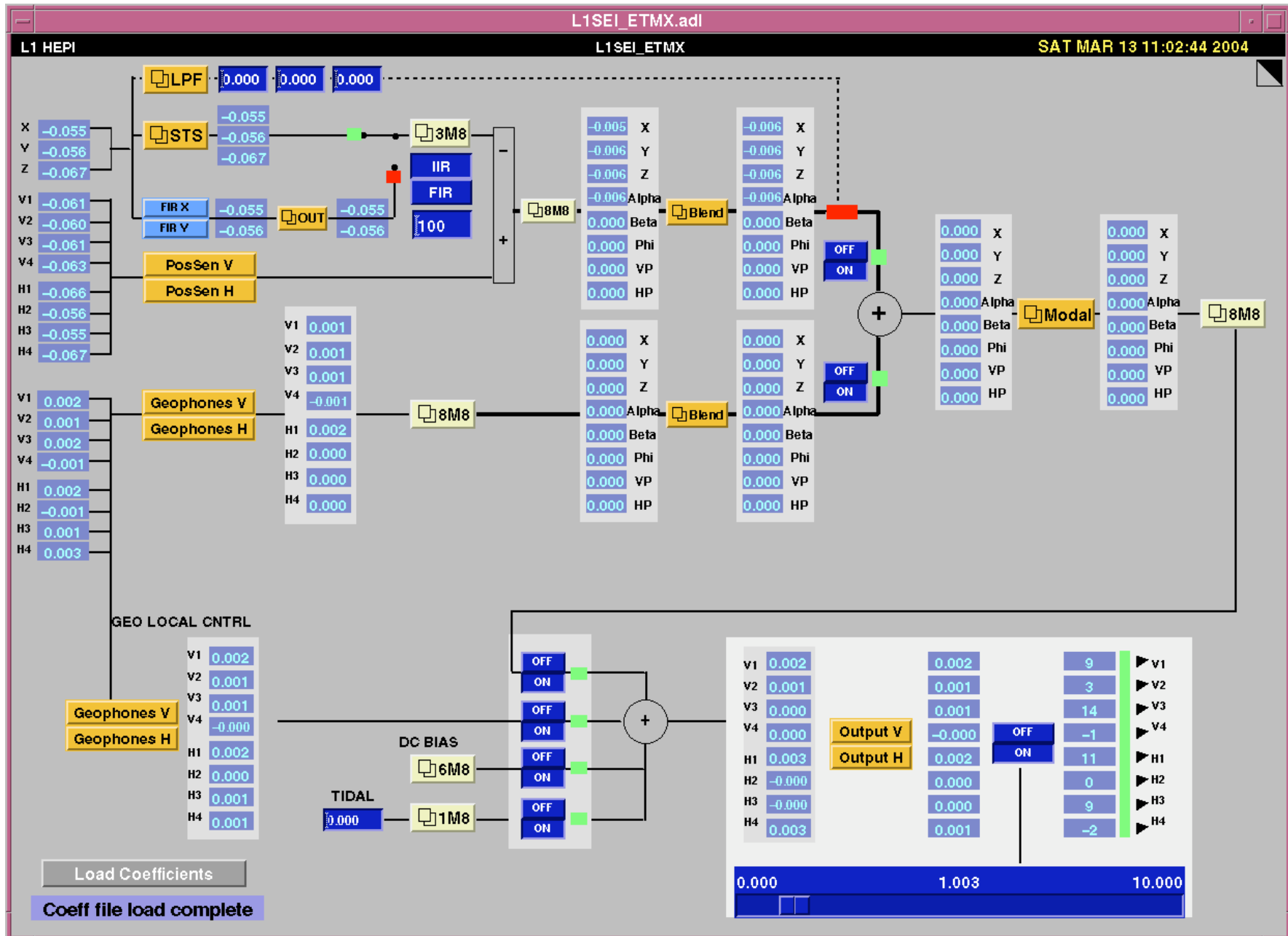
Simulink block diagram from LASTI



Design Diagram



EPICS control panel at LLO



EPICS control panel at LLO

L1 HEPI L1SEI-ETMX_FIR_X_DETAIL SAT MAR 13 11:20:37 2004 CDT

FIR_X_DF

EXCMON 0.000 EXC

INMON -0.055 IN1 ON/OFF

IN2 OFFSET 0.0

CLEAR HISTORY LOAD COEFFICIENTS

FL1 FM2 FM3 FM4 FM5

FM6 FM7 FM8 FM9 FL10

LIMIT 0.0

OUT

DECIMATION

HOLD OUTPUT

OUT1 16 -0.055

OUTPUT -0.055

OUTMON -360.0

FIR FILTER X

LIMIT 0.000 Clear History

OFFSET 0.000

ON/OFF

FIR_X_UP

EXCMON 0.000 EXC

INMON 0.000 IN1 ON/OFF

IN2 OFFSET 0.0

CLEAR HISTORY LOAD COEFFICIENTS

FL1 FM2 FM3 FM4 FM5

FM6 FM7 FM8 FM9 FL10

LIMIT 0.0

OUT

DECIMATION

HOLD OUTPUT

OUT1 16 0.000

OUTPUT 0.000

OUTMON 0.0

FIR_X_CF

EXCMON 0.000 EXC

INMON -0.055 IN1 ON/OFF

IN2 OFFSET 0.0

CLEAR HISTORY LOAD COEFFICIENTS

FL1 FM2 FM3 FM4 FM5

FM6 FM7 FM8 FM9 FL10

LIMIT 0.0

OUT

DECIMATION

HOLD OUTPUT

OUT1 16 -0.055

OUTPUT -0.055

OUTMON -360.0

H1 0.003 Output H 0.002

H2 -0.000 0.000

H3 -0.000 0.000

H4 0.003 0.001

0.000 1.003 10.000

Load Coefficients

Coeff file load complete

TIDAL 0.000 6M8 1M8

ON OFF

DMT-based sys-id (Sarin)

- System identification needs to be carried out on 9 HEPI systems, each with 8 actuators and 16 sensors.
- Previous sys-id was done with dSpace-based code written by Hua.
- At LLO, it is better to use existing DMT environment, so Sarin wrote new application for DMT DTT suite.
- Efficient swept sine and band-limited white noise modes
- Built-in watchdog monitoring of user-defined channels, to permit unattended operation.

Input Measurement Excitation Result

Measurement

- Fourier Tools
 Swept Sine Response
 Sine Response
 Triggered Time Response
 System ID

Measurement Channels

- Channels 0 to 19
 Channels 20 to 39
 Channels 40 to 59
 Channels 60 to 79
 Channels 80 to 99

0 <input type="checkbox"/>	<input type="text"/>	5 <input type="checkbox"/>	<input type="text"/>	10 <input type="checkbox"/>	<input type="text"/>	15 <input type="checkbox"/>	<input type="text"/>
1 <input type="checkbox"/>	<input type="text"/>	6 <input type="checkbox"/>	<input type="text"/>	11 <input type="checkbox"/>	<input type="text"/>	16 <input type="checkbox"/>	<input type="text"/>
2 <input type="checkbox"/>	<input type="text"/>	7 <input type="checkbox"/>	<input type="text"/>	12 <input type="checkbox"/>	<input type="text"/>	17 <input type="checkbox"/>	<input type="text"/>
3 <input type="checkbox"/>	<input type="text"/>	8 <input type="checkbox"/>	<input type="text"/>	13 <input type="checkbox"/>	<input type="text"/>	18 <input type="checkbox"/>	<input type="text"/>
4 <input type="checkbox"/>	<input type="text"/>	9 <input type="checkbox"/>	<input type="text"/>	14 <input type="checkbox"/>	<input type="text"/>	19 <input type="checkbox"/>	<input type="text"/>

System ID

SweptSine | BL White Noise

- Use Swept Sine Method

Start: Hz Stop: Hz Points: Settling Time: %

Measurement Time: cycles sec Averages:

Sweep Type: Linear Logarithmic User Format:

Safety Channels

- Chn 0-4
 Chn 5-9
 Chn 10-14
 Chn 15-19

0 <input type="checkbox"/>	<input type="text"/>	Trigger at: <input type="text" value="0.0"/> %
1 <input type="checkbox"/>	<input type="text"/>	Trigger at: <input type="text" value="0.0"/> %
2 <input type="checkbox"/>	<input type="text"/>	Trigger at: <input type="text" value="0.0"/> %
3 <input type="checkbox"/>	<input type="text"/>	Trigger at: <input type="text" value="0.0"/> %
4 <input type="checkbox"/>	<input type="text"/>	Trigger at: <input type="text" value="0.0"/> %

Start Time

- Now

GPS: sec nsec

Date/time: dd/mm/yy hh:mm:ss UTC

In the future: hh:mm:ss

In the past: hh:mm:ss

Slow down: sec/avg.

Measurement Information

Measurement Time: UTC

Comment / Description:

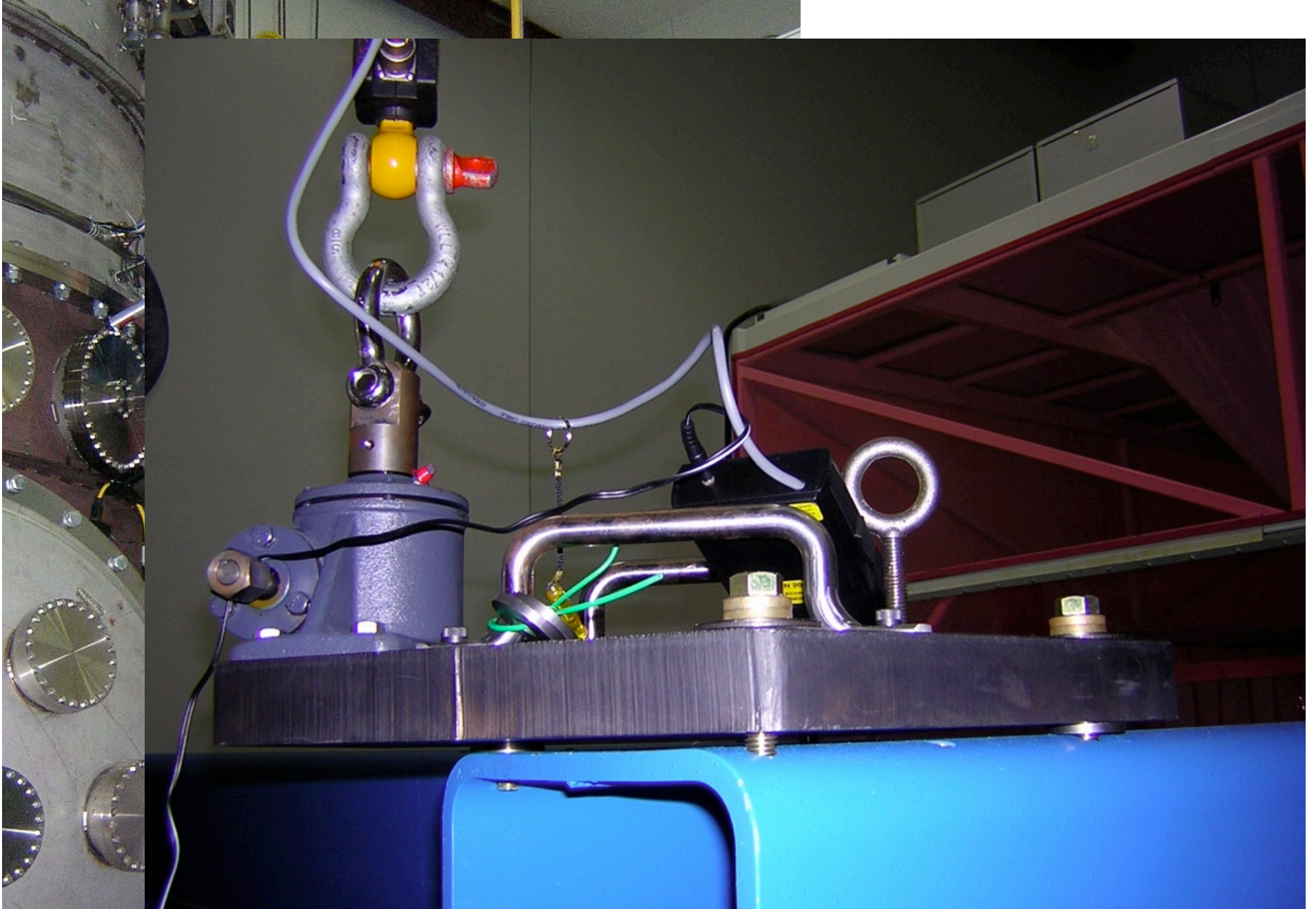
Installation

- We are replacing the old fine and coarse actuation systems in the BSCs, and the coarse actuation and piers in the HAMs.
- The payload is instrumented with 12 dial gauges and two optical lever signals, so allow exact repositioning after installation.
- Each corner is supported from directly above the spring attachment point, the coarse actuator is retracted, the HEPI package installed, and the load is transferred smoothly.
- Each actuator/housing/spring assembly aligned on the bench, then attached to the crossbeam with shimming at a single interface.
- After all 4 are in place, springs to be re-tensioned (read out by load cells) and payload returned to initial position and alignment.

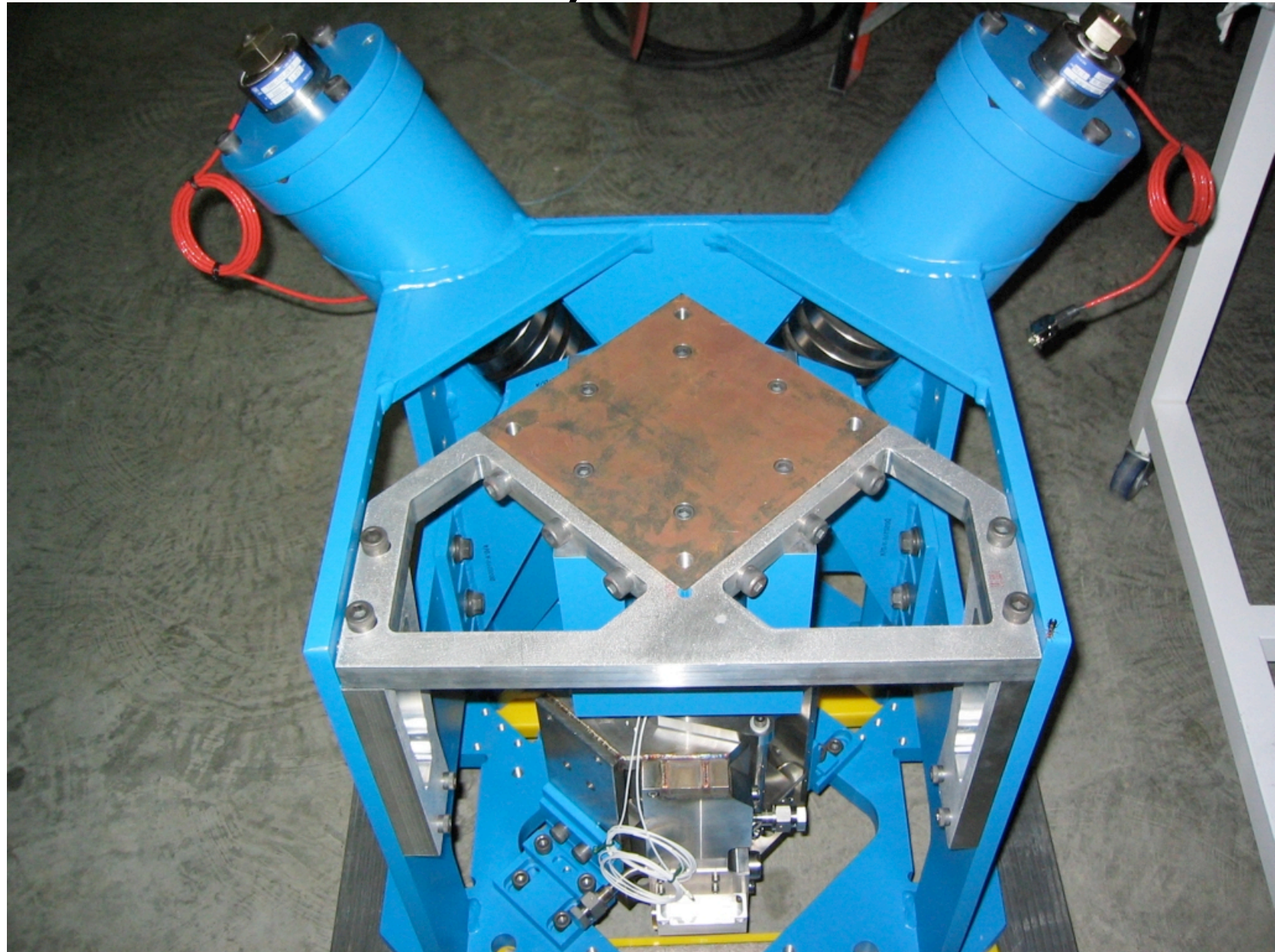
Load support



Load support



Ready to install

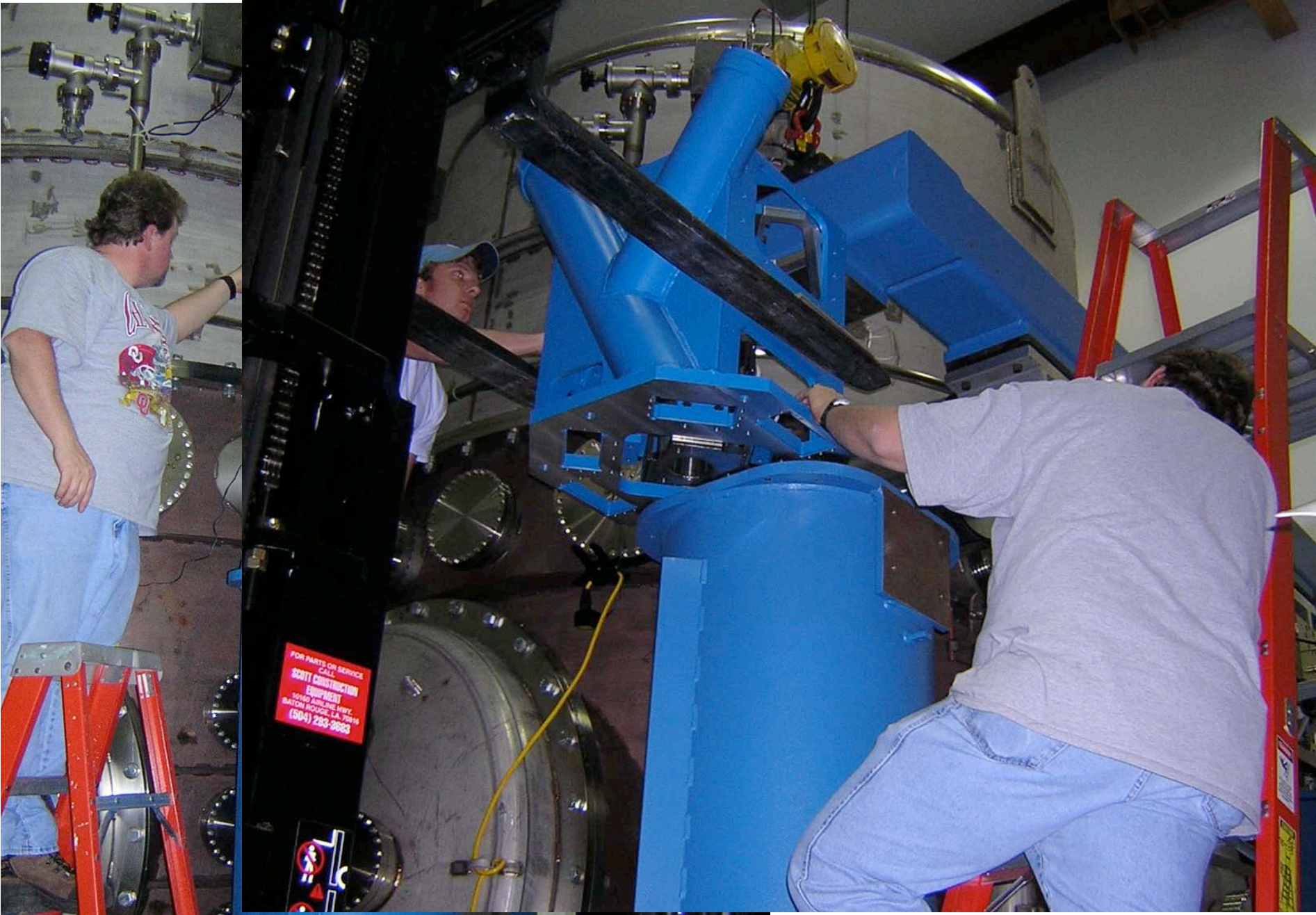


Out with the old ...

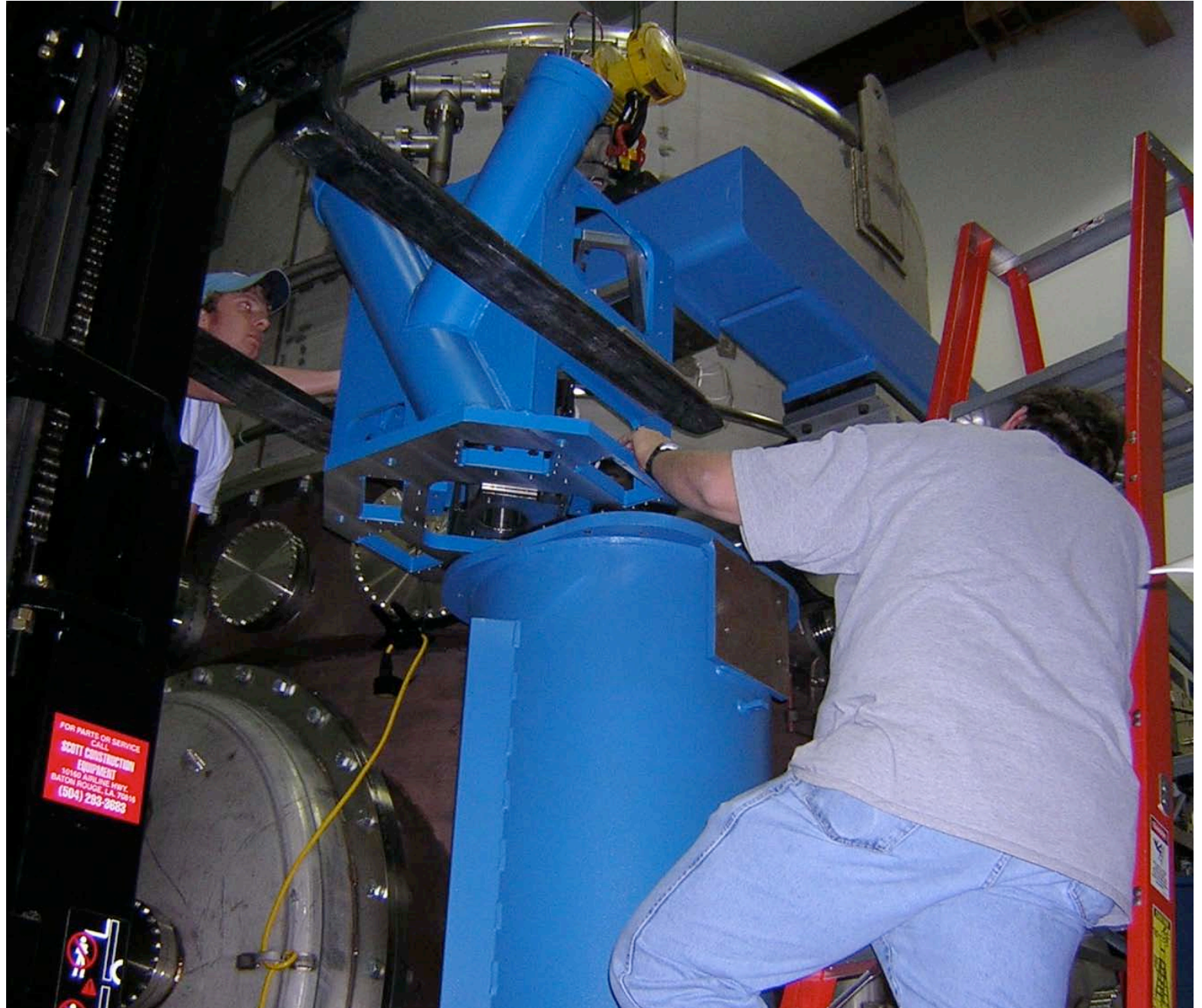


Out with the old ...

In with the new ...



In with the new ...



Schedule

- Current status:

- ◇ ETMX actuator installation nearly complete (dry)

- ◇ ETM plumbing largely complete

- ◇ ETM pump stations in place; readying for fluid circulation through bypass path. (All pump stations built.)

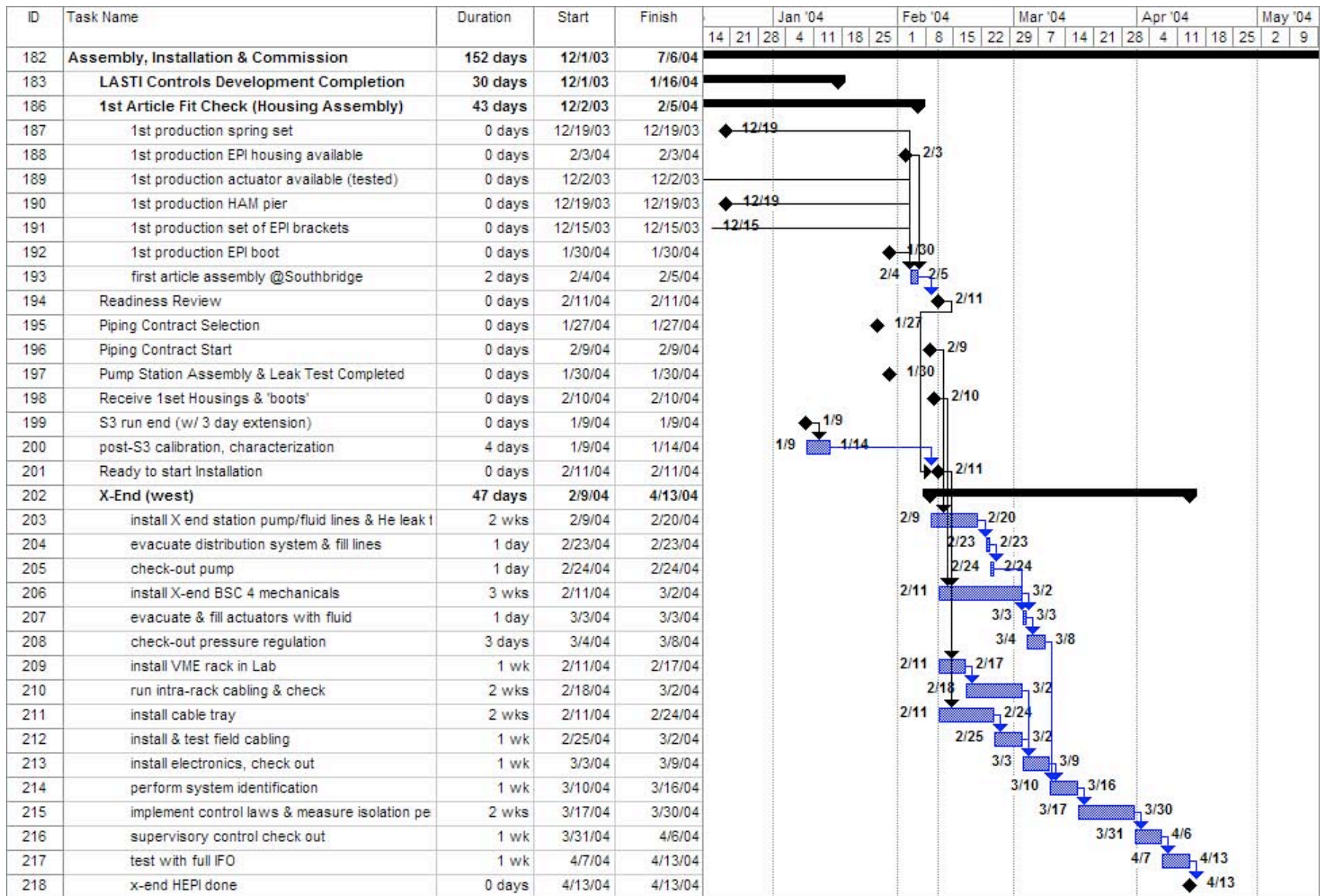
- ◇ More than half of the actuators have been delivered, and most other hardware is in-house.

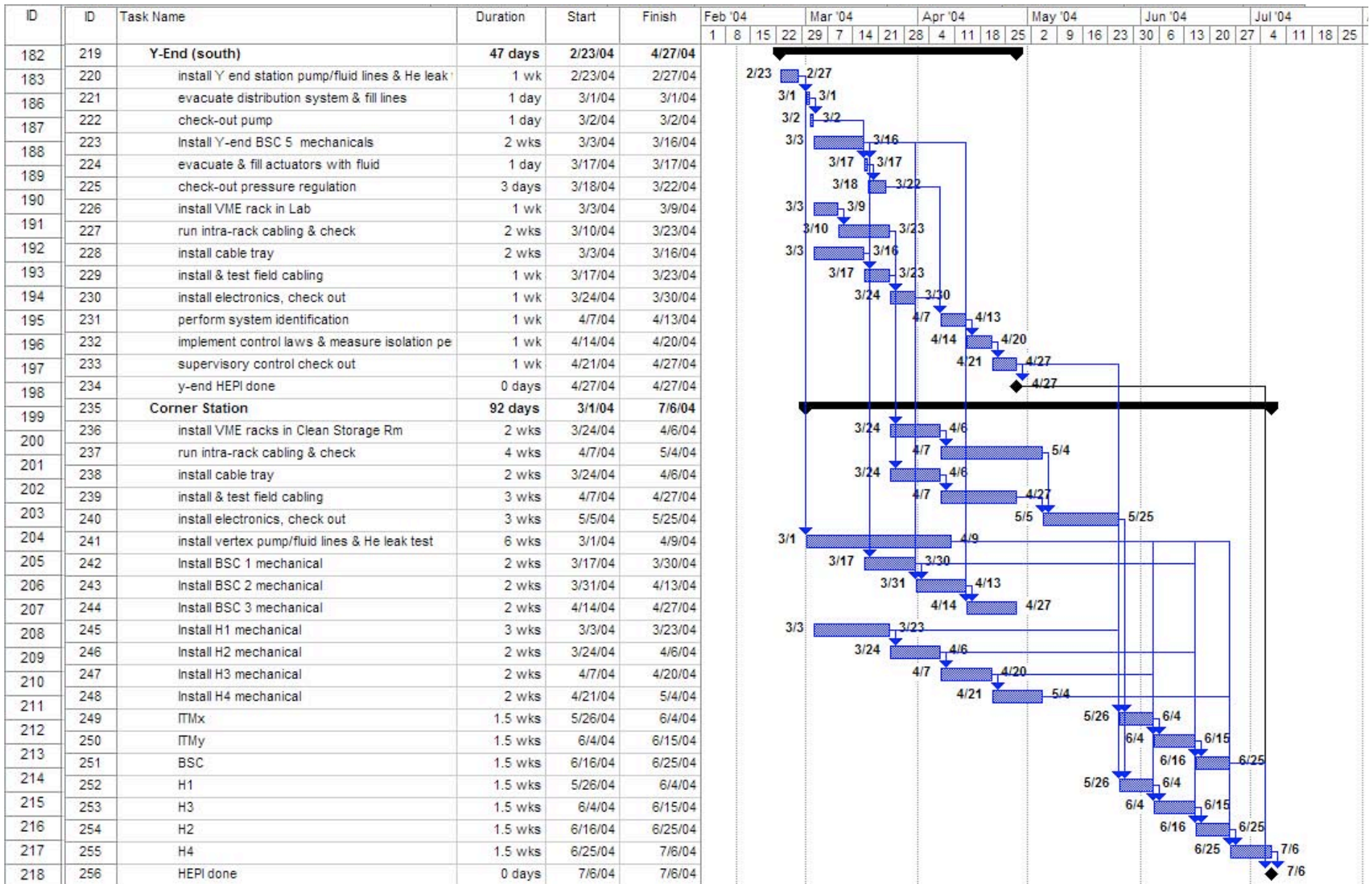
- ◇ Electronics largely ready; the balance is expected soon.

- Outlook:

- ◇ Plan was to spend 3 weeks for the first installation of each tank, then 2 weeks for subsequent ones. We began about 2 weeks late, but it looks like we may avoid schedule expansion.

- ◇ ETMX should be 'wet' next week, and sys-id may begin the following week.





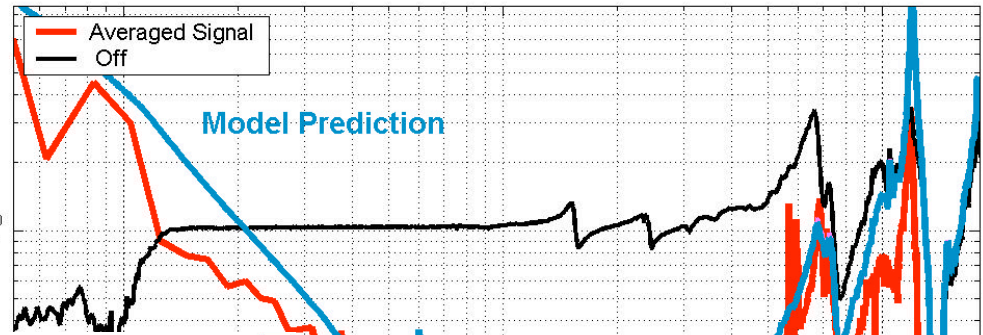
Bold, new idea: train the staff **before** new system is installed



LASTI HAM results (Mittleman)

GROUND X TO SUPPORT TABLE STRECKHEISEN X

COEFFICIENT = -0.75



GROUND Z TO SUPPORT TABLE STRECKHEISEN Z

MAGNITUDE (Z COEFFICIENT = -1)

