

Intensity Stabilization in Advanced LIGO

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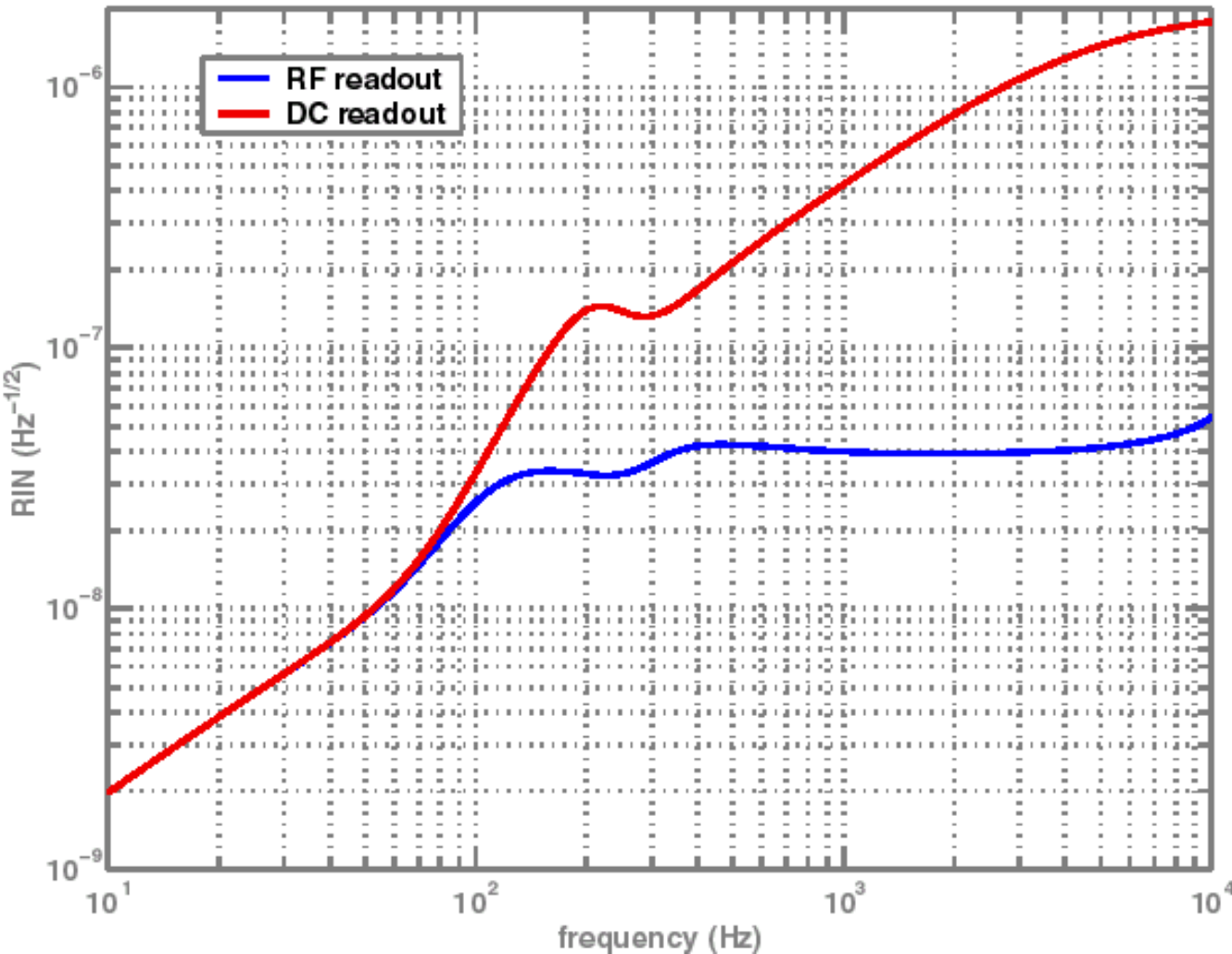
LIGO-G040198-00-Z

Outline

- ; Intensity Noise in Advanced LIGO
- ; The Pre-stabilized laser
- ; PSL Current Actuators
- ; Low-noise, High-power Photodiode
- ; Intensity Stabilization Servo
- ; Results

Advanced LIGO

Intensity Noise Requirement

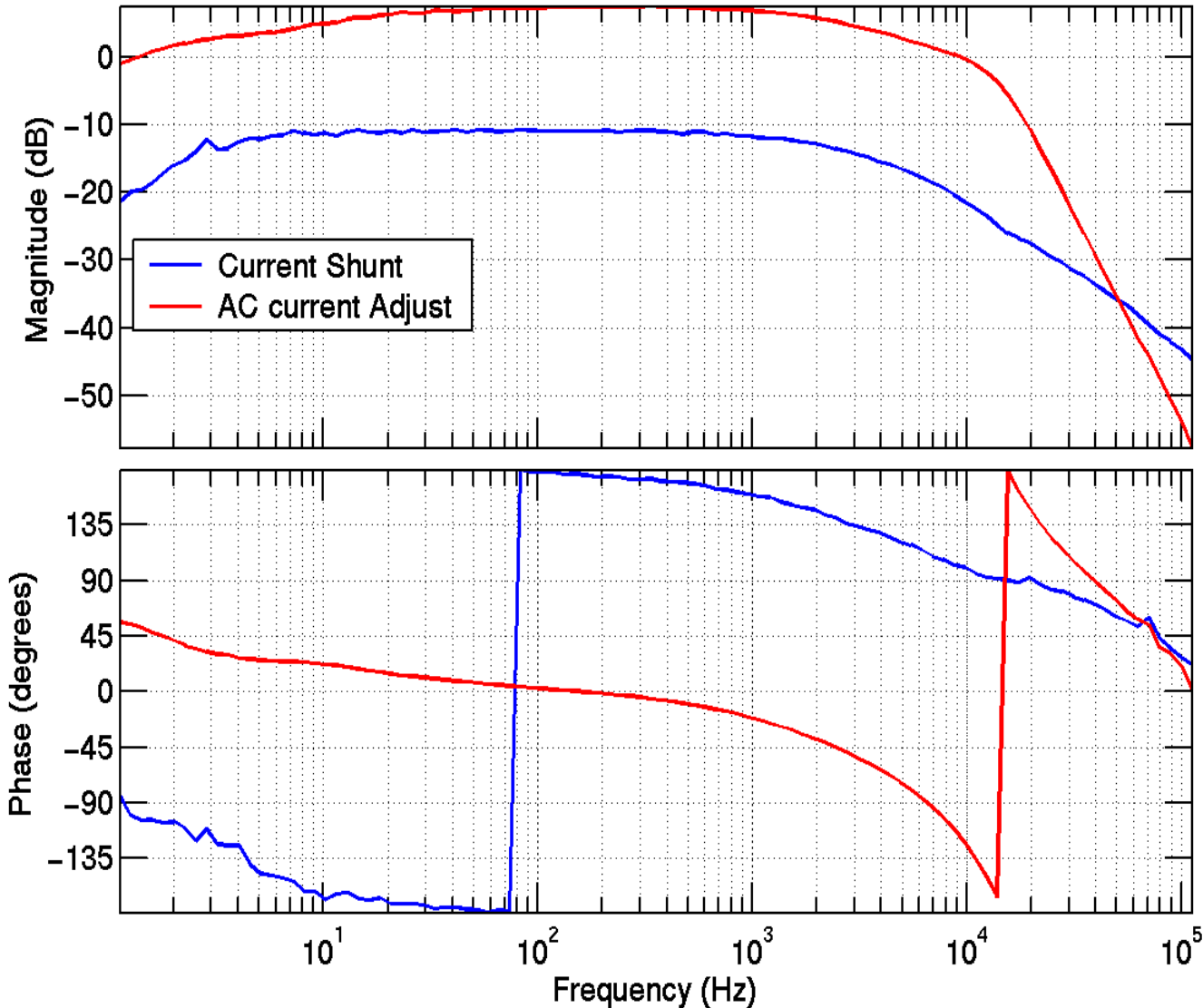


- ; Radiation pressure on test masses with 1% arm power mismatch
- ; RIN: $2 \times 10^{-9}/\text{rtHz}$ @ **10Hz**
- ; Requirement based in part on readout scheme at high frequency

The Pre-stabilised Laser

- ; For experiments, used LIGO-1 10 Watt MOPA
- ; Pre-modecleaner
 - Spatial filter for modes higher than TEM:00
 - Filter for very high-frequency intensity noise
 - ; pole at cavity half-width/half-max (25MHz)
 - Reduces beam jitter
- ; Frequency stabilized

PSL Current Actuators



; AC current adjust

» ± 2.5 Amps/Volt

» poles:

□ 4 @ 10kHz

; Current shunt

» ± 250 mAmps/Volt

» Poles:

□ 1 @ 3kHz

□ more > 200kHz

Low-noise, High-power Photodiode

; Design considerations:

» Very Low noise

- First stage input voltage noise $< 7 \text{ nVrms}/\sqrt{\text{Hz}}$ @ 10Hz,
 $< 3 \text{ nVrms}/\sqrt{\text{Hz}}$ @ 100Hz

» High-power

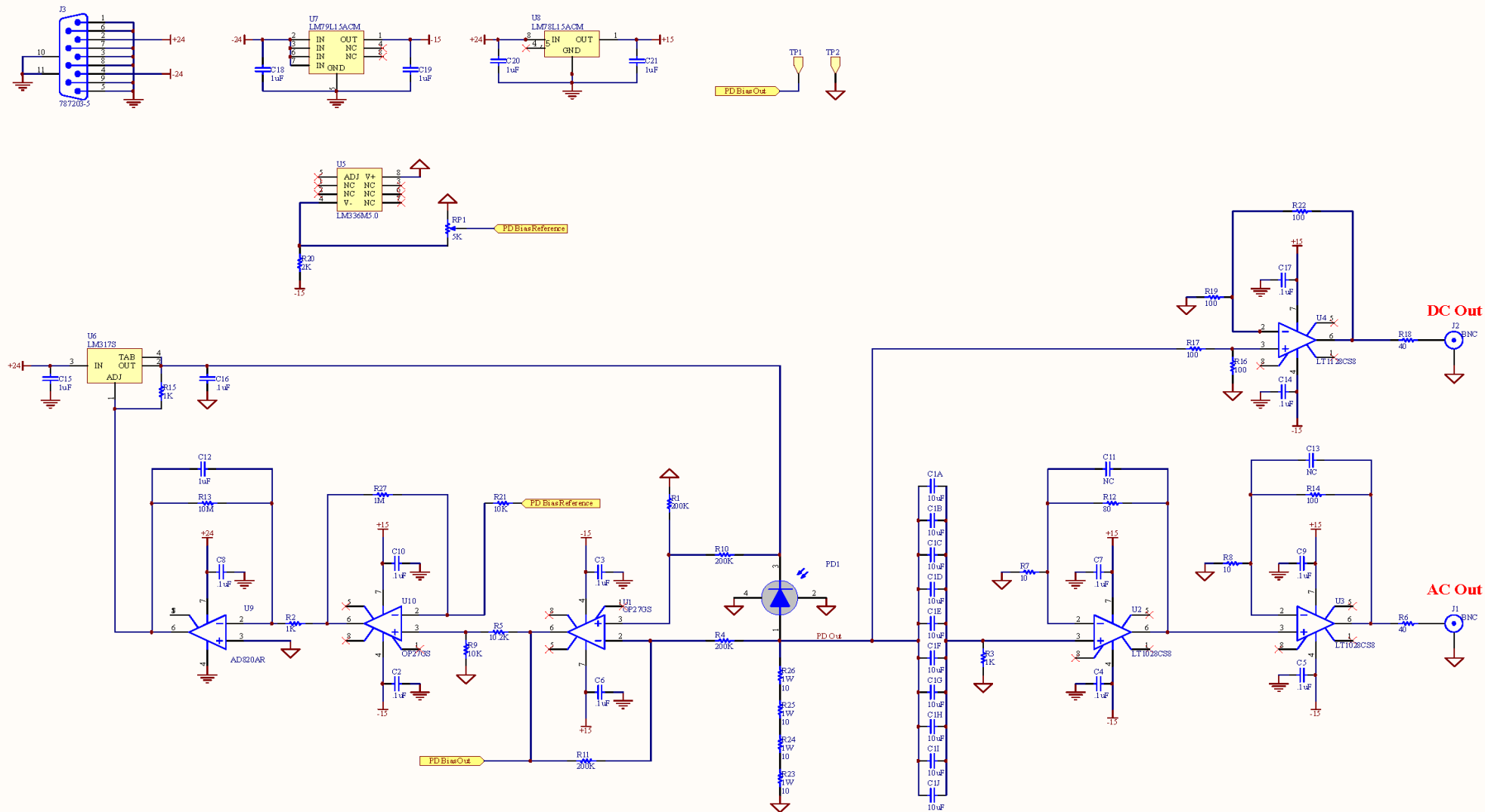
- Photocurrents $\sim 300 \text{ mA}$
- Heat dissipation a problem --> lots of heat sinking
- Use low bias voltages ($< 5\text{V}$) --> ***Bias feedback control circuit***

» AC coupled

- Eliminates need for high-current, low-noise trans-impedance stage
- Eliminates need for stable DC reference
- Requires high capacitance, => 10 surface mount capacitors

; Hamamatsu G5832-02 2mm photodiodes ($\sim .93 \text{ QE}$)

Low-noise, High-power Photodiode



Title			LIGO ISS Photodiode		
Size	Number	iss_pd		Revision	B
Tabloid					
Date:	6/3/2003		Sheet of James Rollins		
File: C:\Documents and Settings\james.rolins\My Documents\iss_photodiode_circuit2.psd					

Intensity Stabilization Servo

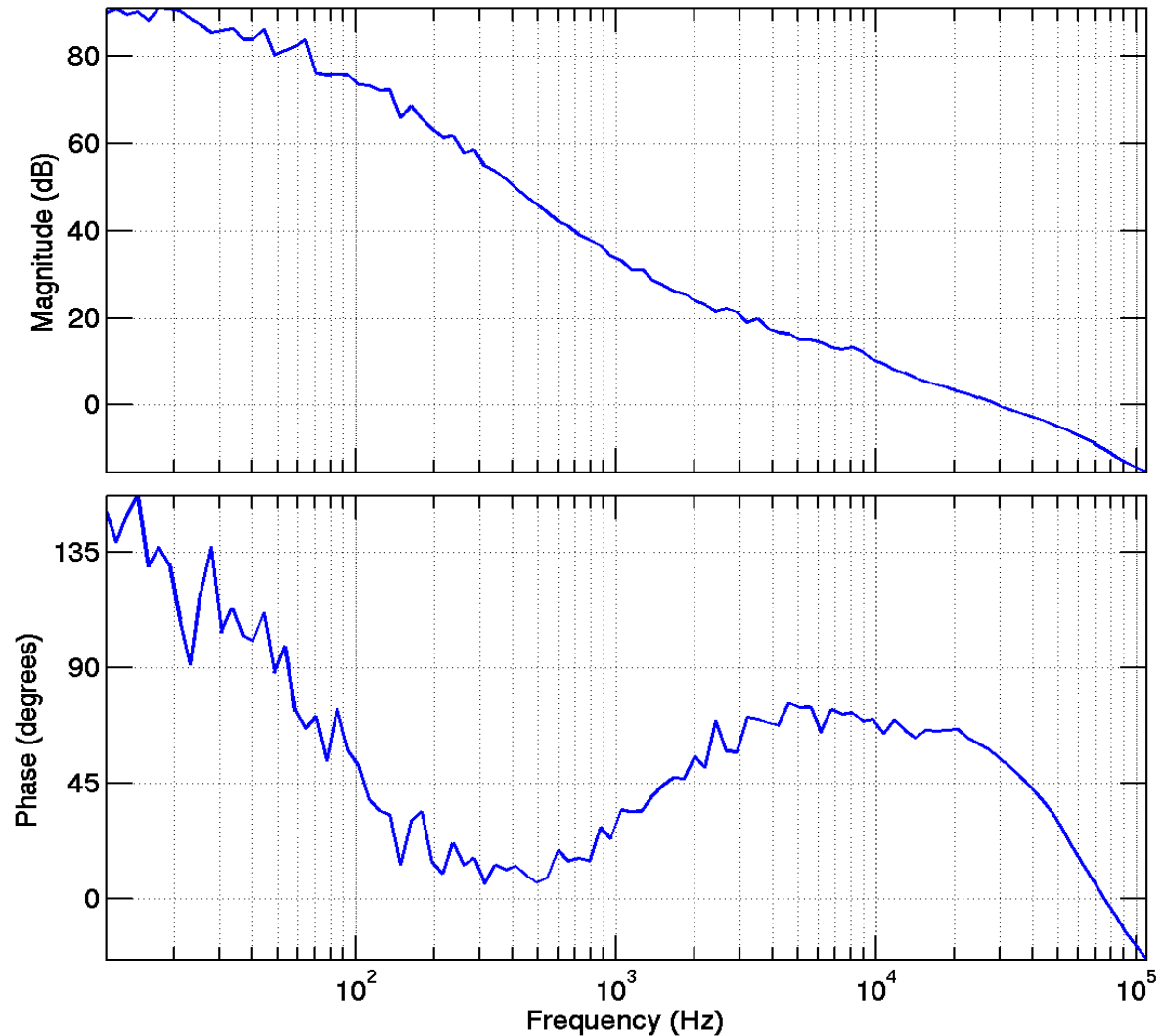
; Requirements:

- » 80dB of gain @ 10Hz
- » 10kHz unity gain
- » AC coupled

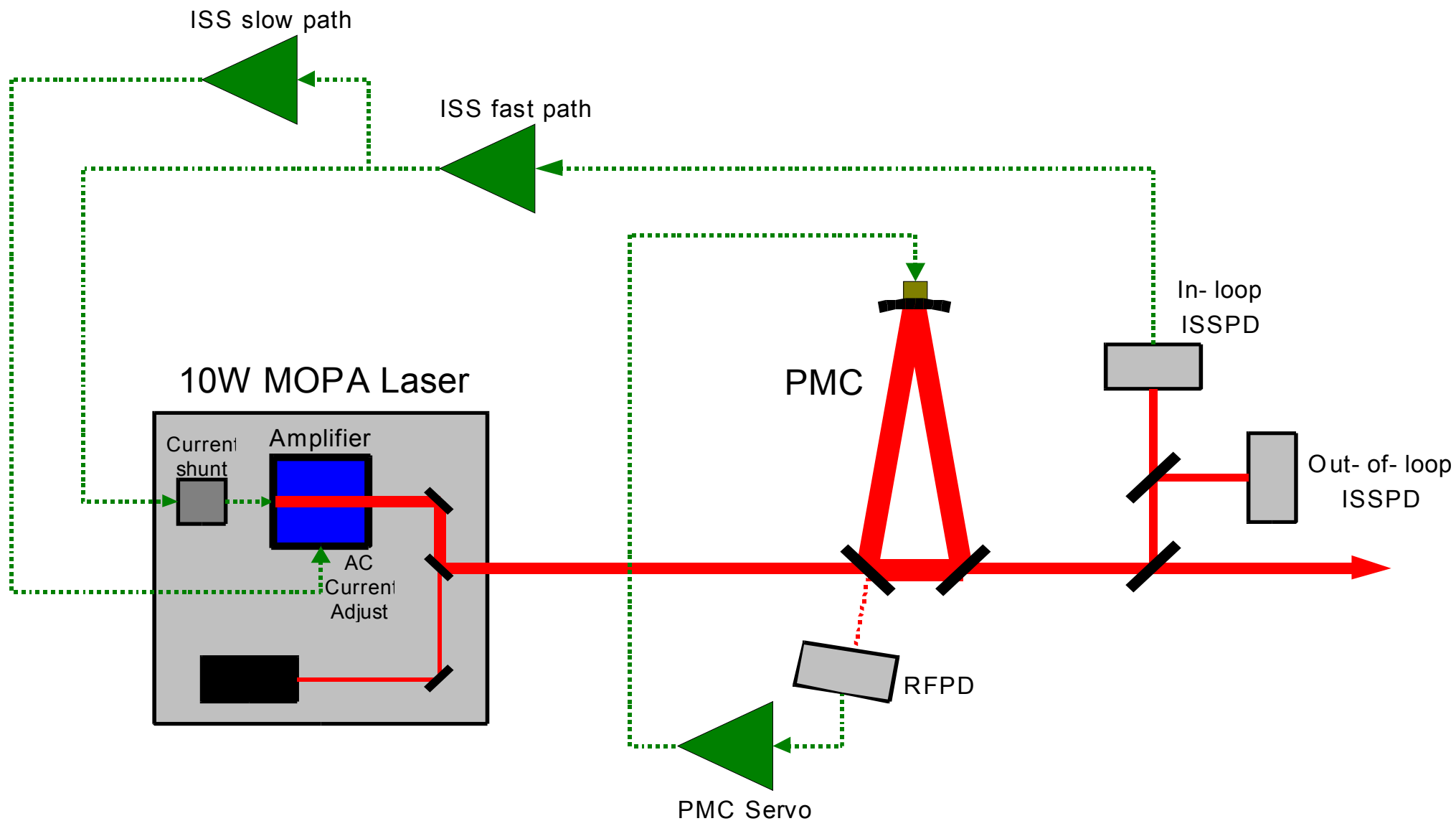
; 2-loop topology:

- » Current shunt alone did not have enough dynamic range.
- » Used high-dynamic range AC current adjust at low frequency.

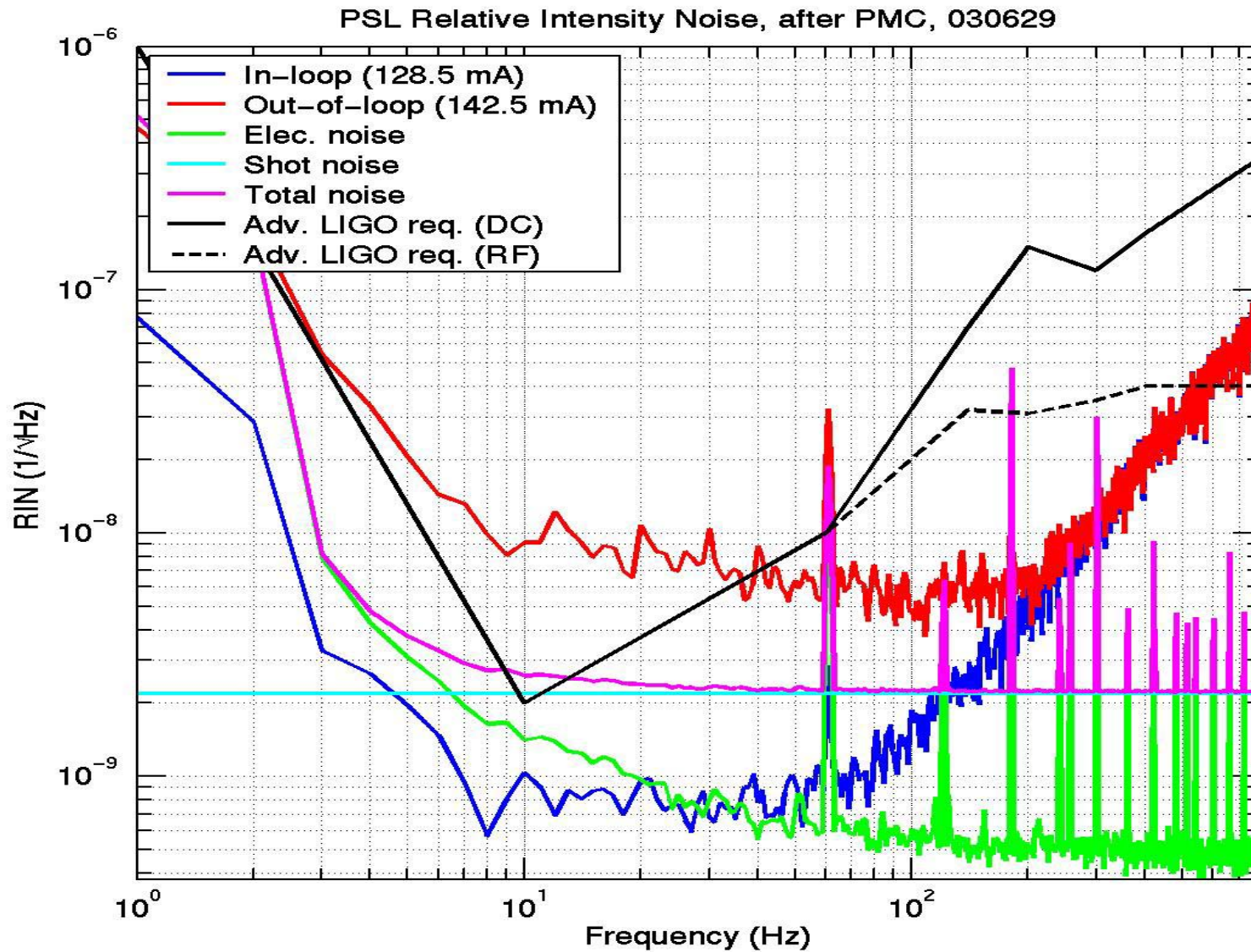
ISS Open-loop Frequency Response (derived from closed-loop)



Intensity Stabilization Servo



Results



What we have tried

; Ruled out:

- » Scatter (ND filters in front of pd's)
- » Electronics noise (in photodiode and servo)
- » High-frequency noise hitting slew-rate limits
- » Photodiode bias noise (tried fixed bias voltage)
- » Capacitive sparking
- » PMC (frequency->intensity conversion)
- » Beam Jitter
- » Polarization jitter

; Need to investigate further:

- » Another out-of-loop PD to verify that limit is actually on light (need third low-noise photodiode)
- » Beam splitter coatings
- » Try using simple reflections
- » Vacuum Compatible PDs