
LIGO In-Vacuum Sensors

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Outline

- Overview of types of geophones
- How LIGO uses its geophones
- LIGO's assembly, testing and problems for each type
- Future solutions
- Summary

Types of Geophones

□ GS-13

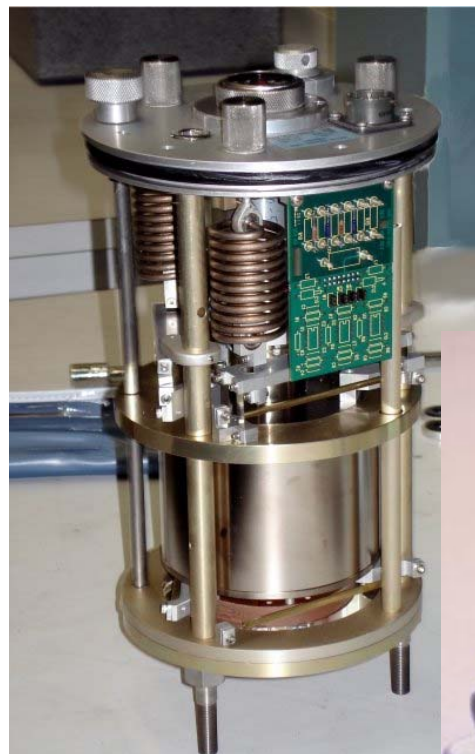
- 1-D Seismometer
- Suspended cylindrical proof mass
- Resonance: 1 Hz
- Requires mass locking

□ STS-2

- 3-D Seismometer
- 3 identical suspended masses
- Resonance: 0.08Hz (or 1Hz)
- Requires mass locking

□ L-4C

- 1-D Seismometer
- Suspended cylindrical proof mass
- Resonance: 1 or 2 Hz
- Does not require mass locking



LIGO System Uses In vacuum pods

Instruments in vacuum pods



STS-2



L-4C



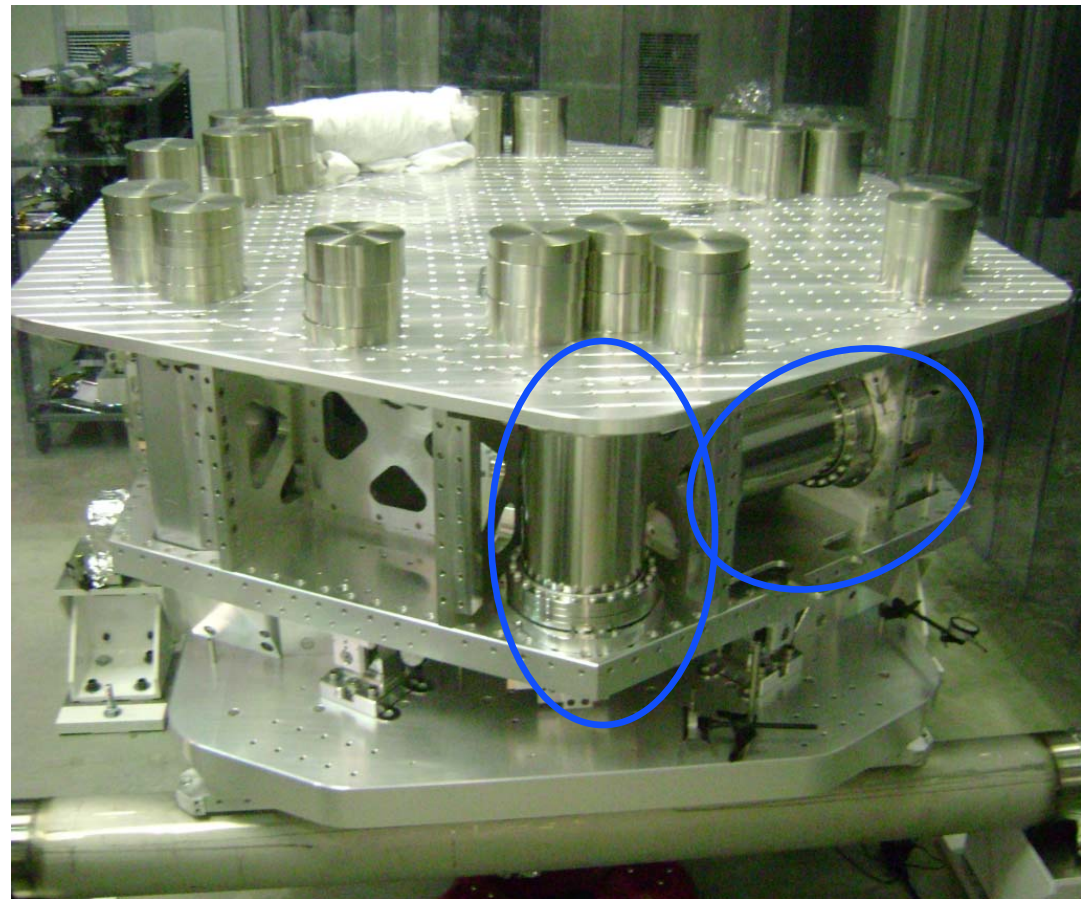
GS-13

- ❑ Dirty seismometers need to go in clean vacuum systems
- ❑ Solution: Instruments are mounted to a base-plate, then enclosed inside a vacuum-sealed pod.
- ❑ Assembled pod mass
 - GS-13: 71 lbs.
 - STS-2: 110 lbs.
 - L-4C: 18 lbs.
- ❑ GS-13 and STS-2 need to be locked and unlocked once in vacuum, one has to do this remotely.

□ Single Stage seismic isolation platform

□ Needs (HAM-ISI):

- 6 GS-13 pods per HAM ISI (108 total!)
- Additional 6 if a LASTI HAM-ISI is built

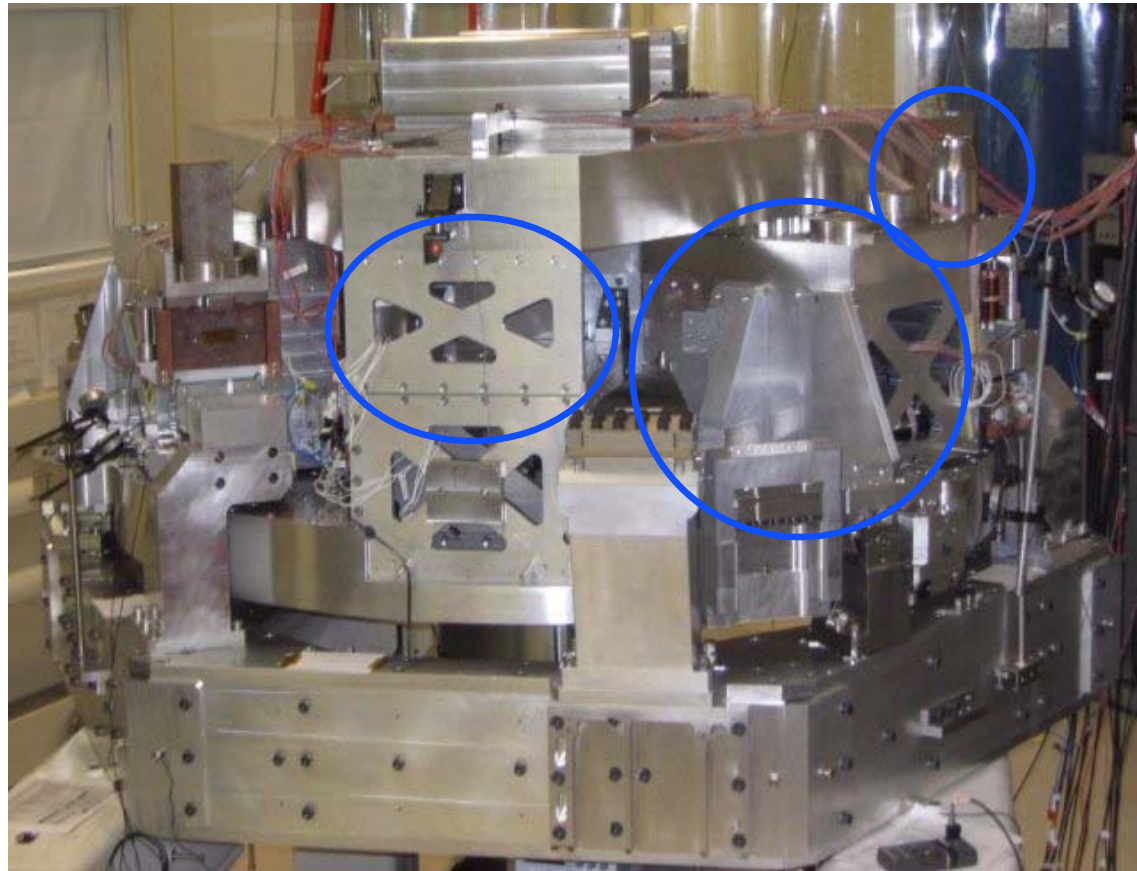


The HAM ISI mid-assembly

- ❑ Double Stage suspended seismic isolation platform

- ❑ Needs (per BSC ISI):
 - 6 GS-13 pods (96 total)
 - 3 STS-2 pods (48 total)
 - 6 L-4C Pods per BSC ISI (96 total)

**Advanced LIGO
needs 354 in-vacuum
seismometers if we
include prototypes.**

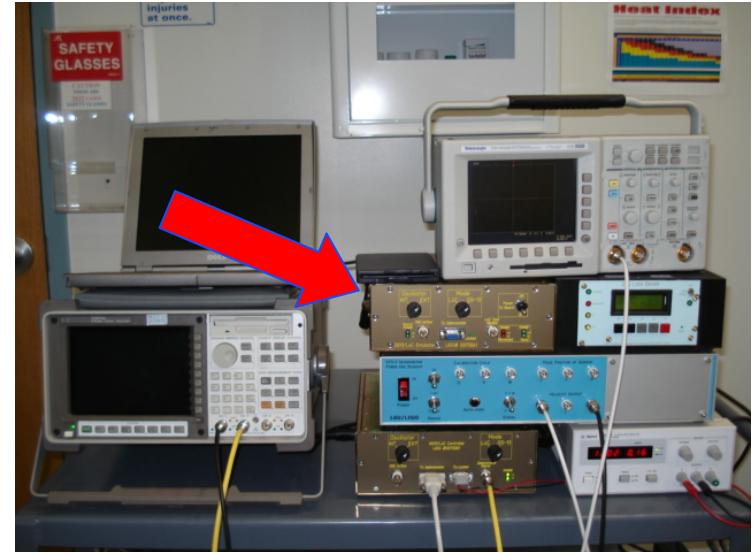


The BSC ISI mid-assembly at LASTI

- ❑ Secure calibration coil using RTV and better chamfered set screws
- ❑ Modify locking mechanism to include electronically controlled 12V motor
- ❑ Replace internal circuit board with LIGO fabricated Pre-Amp board that includes
- ❑ Add bushing to top plate where locking rod exits to prevent precision of locking rod



Red arrow points
at emulator



Emulator

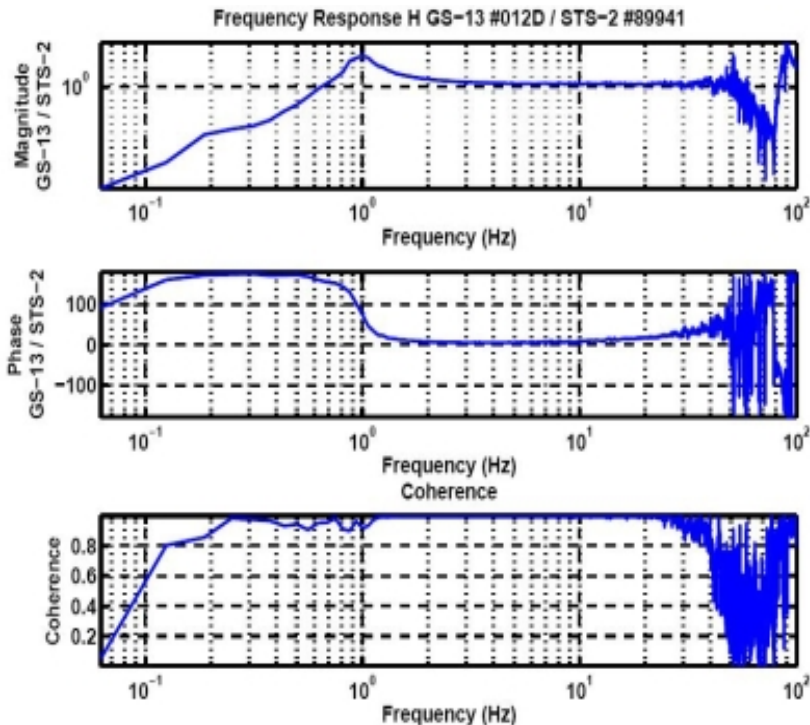
- Electronics box meant to simulate a podded GS-13
- Used to test all cabling up to the point where it is connected to the pod to prevent incorrect pinning



Counter
mechanism

Locking-Unlocking Cycle test

- Locking mechanism cycled 10+ times
- Counted using multi-directional rotational counter mounted to locking rod



□ Huddle Test

- Frequency response taken against STS-2, including power spectra of both
- Taken on 3x4 ft. level granite block
- Taken before and after podding

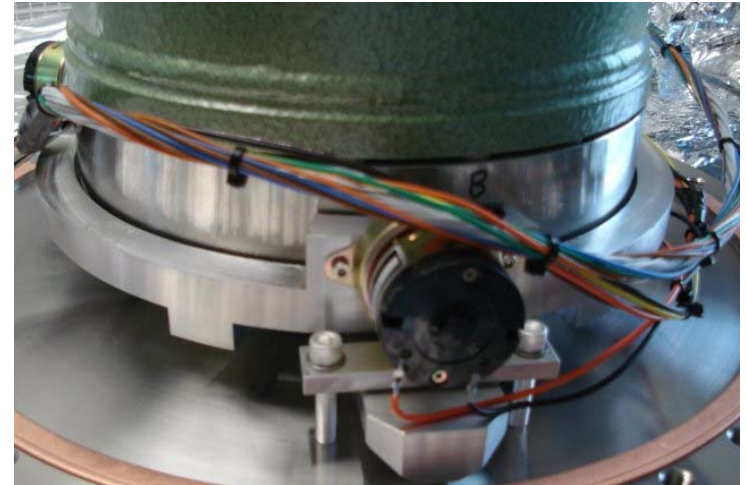
□ Rigorous visual inspection

- Document all results in “Inspection Checklist,” in seismic log, in IFO iLog, and travelers
- After all this testing (and and a few repairs) we still see problems at LLO

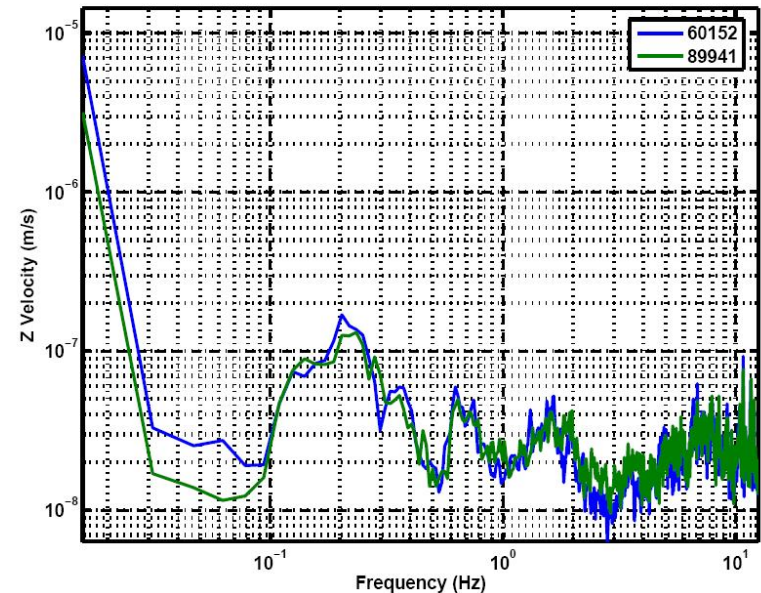
- ❑ Mass does not unlocked because mechanism is jammed but double locking or too high of a voltage signal
- ❑ Mass does not unlock because not enough voltage reaches motor from cable from to racks
- ❑ Locking mechanism disengages, but mass remains frozen in container ring or falls too far
 - GS-13 is not level because of baseplate mounting mechanism or sheered skeleton (i.e. shoddy craftsmanship)
- ❑ Spectra looks like signal is not getting out
- ❑ Mass is slow to “fall off” container ring

FAILURE RATE: 3 of the 14 eLIGO GS-13s have been deemed “unusable until further investigation.”

- ❑ No major modifications, just locking motor system and readout cable
- ❑ Testing regime similar to GS-13 (includes huddle test and motor cycle test)
- ❑ No need for internal visual inspection



STS-2 Huddle Test: Z-Direction



- ❑ Frozen or sticky locking screws maybe do to “gunk” from opening shield
- ❑ Internal moisture contamination, and defective electrolytic capacitors known to be problems do to age
- ❑ Those used for HEPI have had troubles as well, may be due to power outages on site
- ❑ Permanently railed velocity signal from initial cabling issues

FAILURE RATE: 6 of 17 STS-2 in LIGO have been sent to Quanterra for repair

□ Assembly / Modifications

- No modifications to speak of other than insertion into vacuum pod

□ Testing

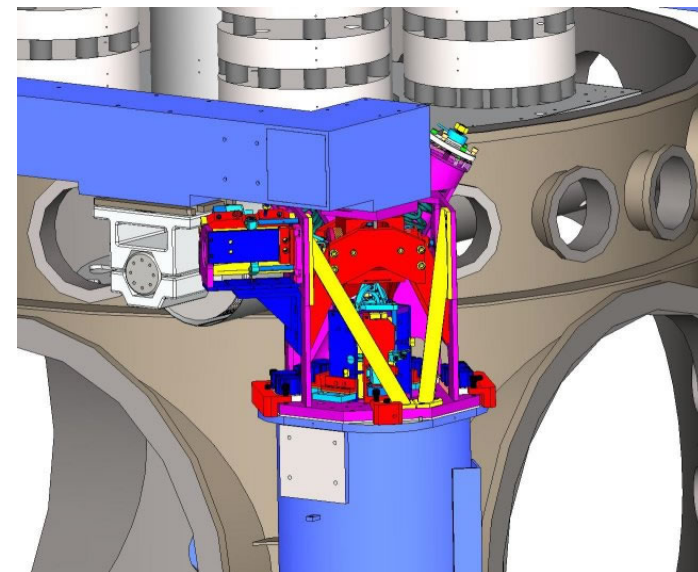
- No rigorous testing up to date, but 72 L-4Cs were used on L1's HEPI, and we have not seen any failures in 3+ years

□ Problems

- Some initial teething problems, but have worked nominally for 3+ years on HEPI



Jeff Kissel, March LSC Meeting, 03/19/08



Future Work

- ❑ **Modifying GS-13 structure to relieve locking necessity**
 - Stanford group is looking into materials, shapes, and configurations that might provide this rigidity
- ❑ **Is there a non-locking alternative? How important is the noise performance for the HAM? Should we ask around?**
- ❑ **Modify baseplate and chamber so one can see proof mass bubble through feedthrough.**
- ❑ **Need to discuss quality control with the vendor.**
- ❑ **Trillium 240**
 - Being tested at ETF.
 - No Mass Locking (“withstands 20 G half sine loading”)
 - Vendor is responsive.



Summary

- ❑ Three types of instruments with which LIGO has had years of experience
- ❑ We've seen many different problems varying in severity in all three types. GS-13s seem the worst.
- ❑ aLIGO needs over *300 more!* At least 1 person-year of labor.
- ❑ Rigorous and well documented testing procedure is in development
 - Should consider mounting instruments on a shaker table to better characterize response.
- ❑ Looking into entirely new and improving current seismometers to increase reliability and longevity of seismic subsystems of LIGO
- ❑ We should not lock ourselves in to a design which is not robust.