

Interferometry for Gravity Wave Detection

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Outline of talk

- salient features of GW's for detectors
- how interferometric detectors work
- limitations to sensitivity: physics of and solutions to noise sources



Nature of Gravity Waves

Assuming General Relativity

- Any GW's impinging on earth are in weak, far field limit

$$g_{\mu\nu} \approx \eta_{\mu\nu} + h_{\mu\nu}$$

- For particular choice of gauge, h satisfies

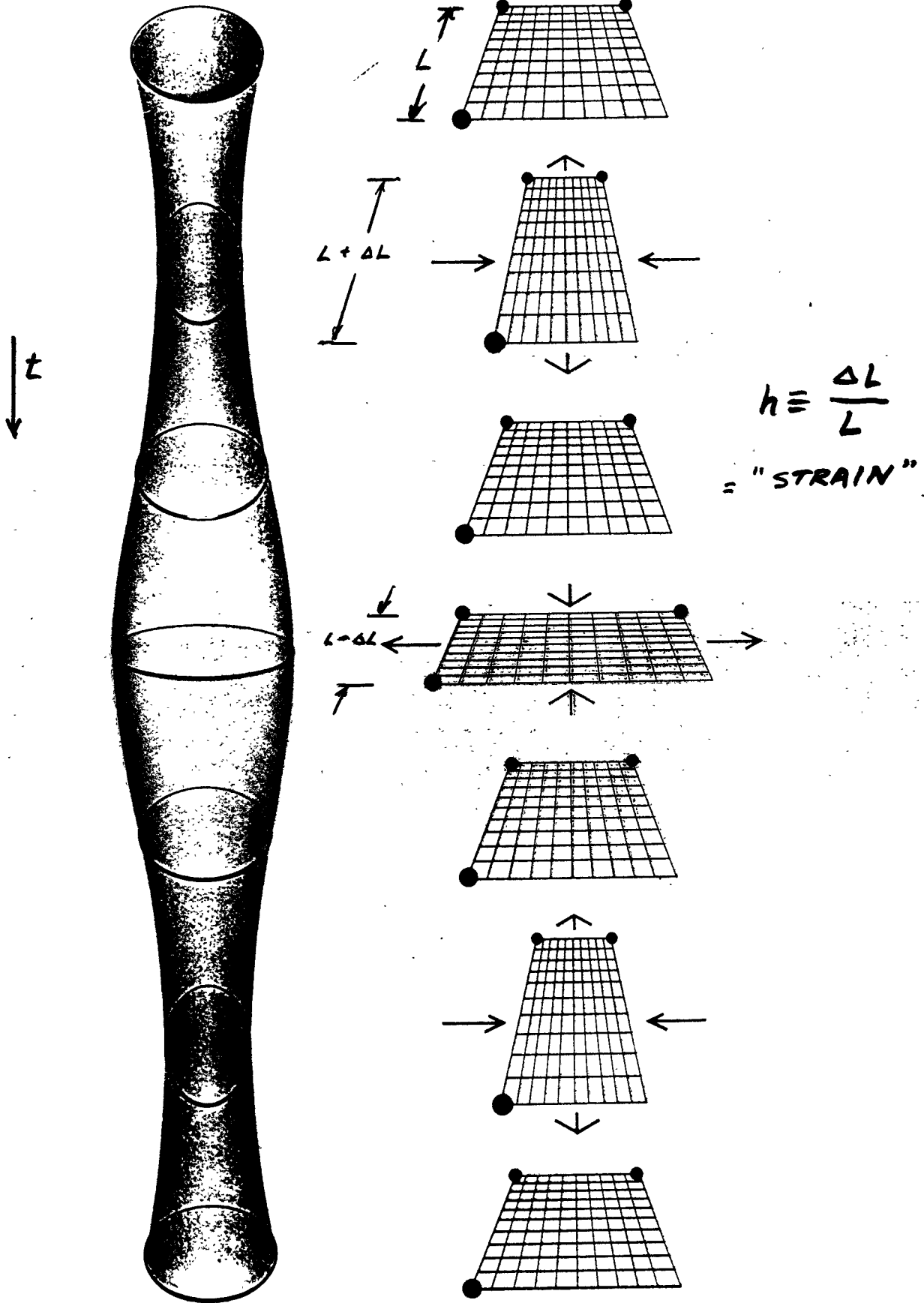
$$\left[\frac{\partial^2}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right] h(x, t) = 0, \quad h_{\mu\nu} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & h_{yy} & h_{yz} \\ 0 & 0 & h_{yz} & -h_{yy} \end{bmatrix}$$

- Proper distance between two particles, $ds^2 = g_{\mu\nu} dx^\mu dx^\nu$, is perturbed according to

$$\Delta s = \int_0^{y_0} |g_{yy}|^{1/2} dy \approx \left[1 + \frac{1}{2} h \right] y_0$$

Net effect: variation in proper distance between free masses, proportional to GW amplitude and initial separation → tidal force





EFFECTS OF GRAVITATIONAL WAVES are depicted for a rubber tube floating in space (*left*) and for a set of masses in a plane (*right*). Gravitational waves should distort the shape of any region of space they travel through. Here the waves move vertically.

Simple estimate of magnitude

Lowest order radiation term: quadrupole

- field amplitude proportional to \ddot{Q} , 2nd derivative of quadrupole
- or, non-spherical part of kinetic energy $\ddot{Q} \sim M\ddot{L}^2 \sim Mv^2 \sim E_{kin}^{ns}$
- dimensional analysis leads to

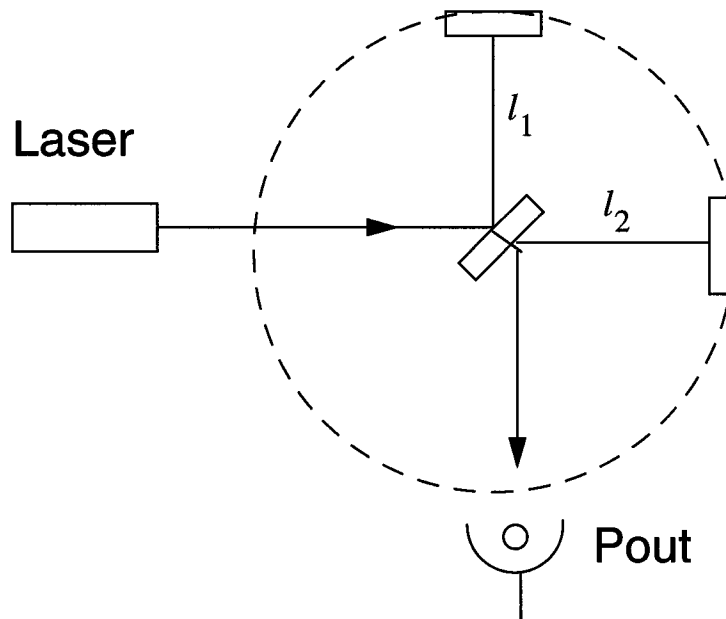
$$h \sim \frac{G}{c^4} \left(\frac{E_{kin}^{ns}}{r} \right) \sim 10^{-20} \left[\frac{E_{kin}^{ns}}{M} \right] \left[\frac{10Mpc}{r} \right]$$

- $h \sim 10^{-17}$ (our galaxy)
 - $\sim 10^{-20}$ (Virgo cluster)
 - $\sim 10^{-23}$ (cosmological distances)
- Sources
 - compact binary coalescence
 - supernovae
 - spinning neutron stars (pulsars)
 - cosmological: cosmic strings, early universe phase transitions
 - THE UNKNOWN



Basic idea of detection

Allow free test bodies to float inertially in space-time, & continuously monitor the time of flight of light beams bouncing between them to sense changes in their proper separations

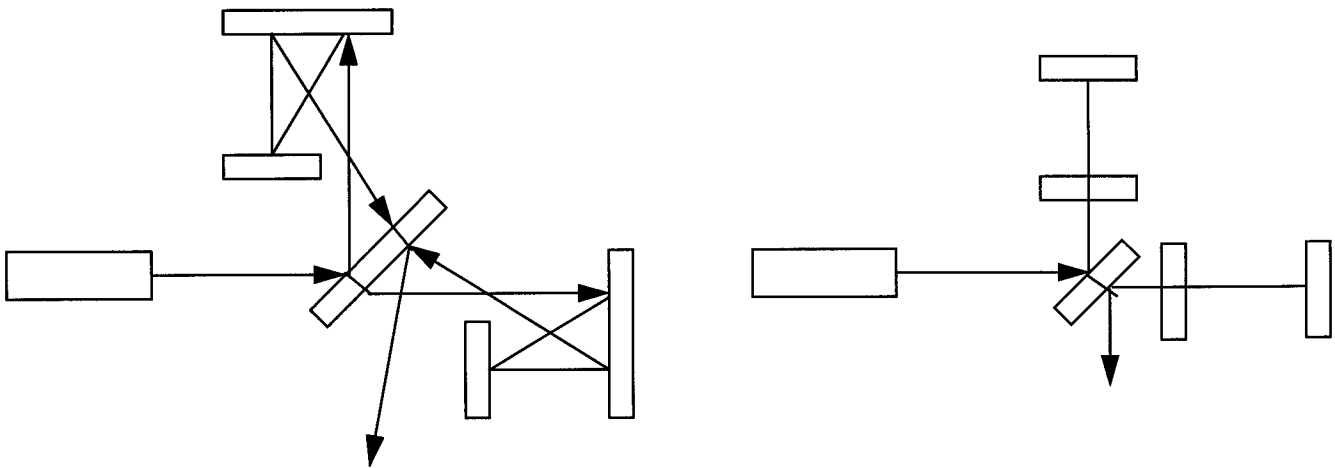


- Laser -illuminated Michelson interferometer is an ideal tool
 - broadband response to GWs of varying frequency, polarization, direction
- Obstacles:
 - free fall not practical
 - small absolute displacement, $\Delta x \sim 10^{-18}$ m, 10^{-12} of laser λ

More on interferometry

Interaction time with the GW

- signal δl , $\delta\phi$ grows as length of interferometer L grows, in the limit where $L \gg \lambda_{\text{GW}}$. $\rightarrow L$ up to about 100 km
- not practical to make 100km straight path, so fold it; for the same δl , increase $\delta\phi$ by optical storage:



- Delay line
 - › conceptually simple, but requires large mirrors
- Fabry-Perot
 - › compact, but imposes modes, resonance constraints on system
- 1 msec storage time for initial ground-based system
 - › gives optimum sensitivity around 100 Hz

Detector frequency response

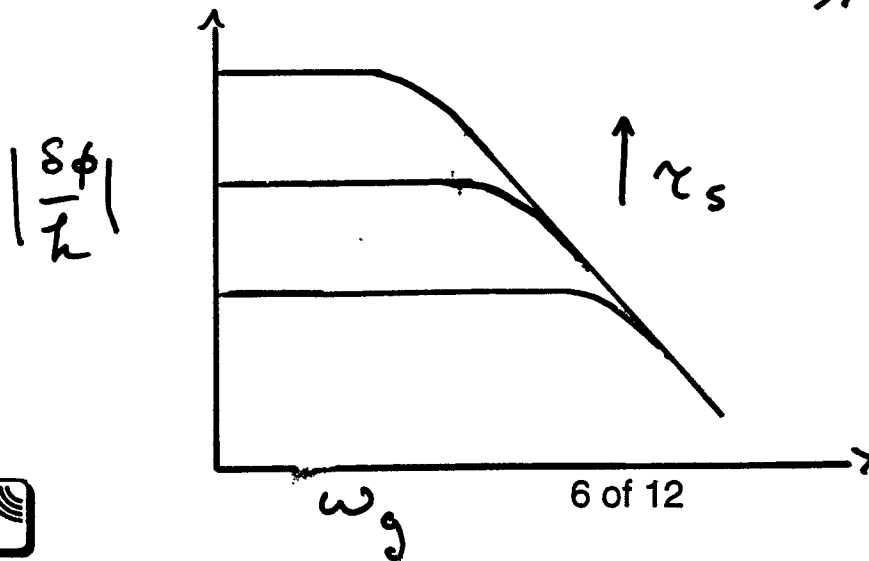
When storage time is longer than half the GW period, the phase shift built up during one half-cycled is reduced during the next half-cycle

- To find response of a particular interferometer configuration to gw's of frequency f , consider that gw-induced modulation of optical phase produces *sidebands* on the light, at

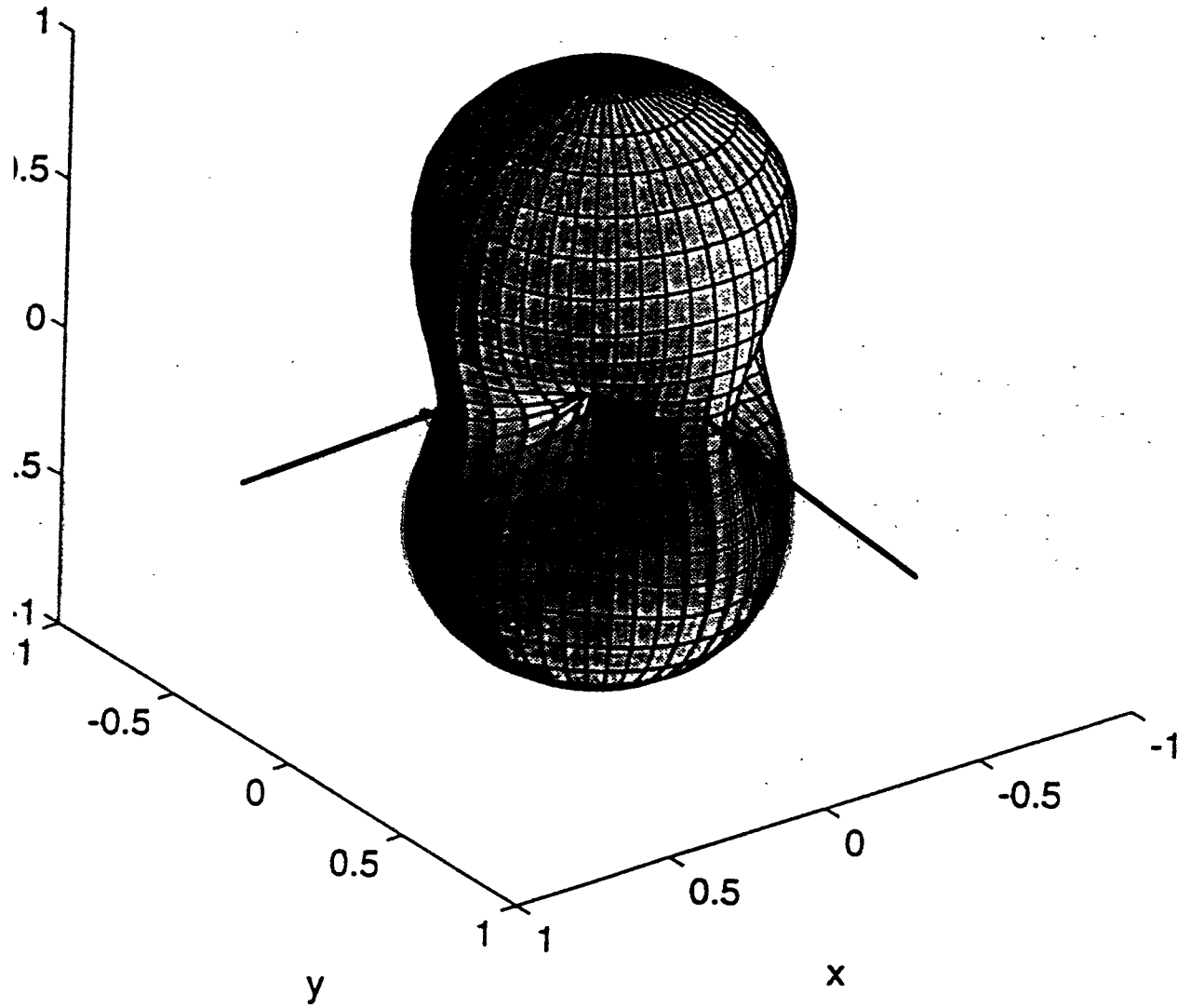
$$\omega_0 - \omega_g, \omega_0 + \omega_g$$

- Calculate response of optical system to all three frequencies to determine frequency response to GWs
- For a Michelson with Fabry-Perot cavities in the arms, this leads to

$$\left| \frac{\delta\phi}{h} \right| = \frac{4\omega_0\tau_s}{\sqrt{1 + (2\omega_g\tau_s)^2}} \xrightarrow{\omega_g\tau_s \gg 1} \frac{2\omega_0}{\omega_g}$$



ANGULAR RESPONSE



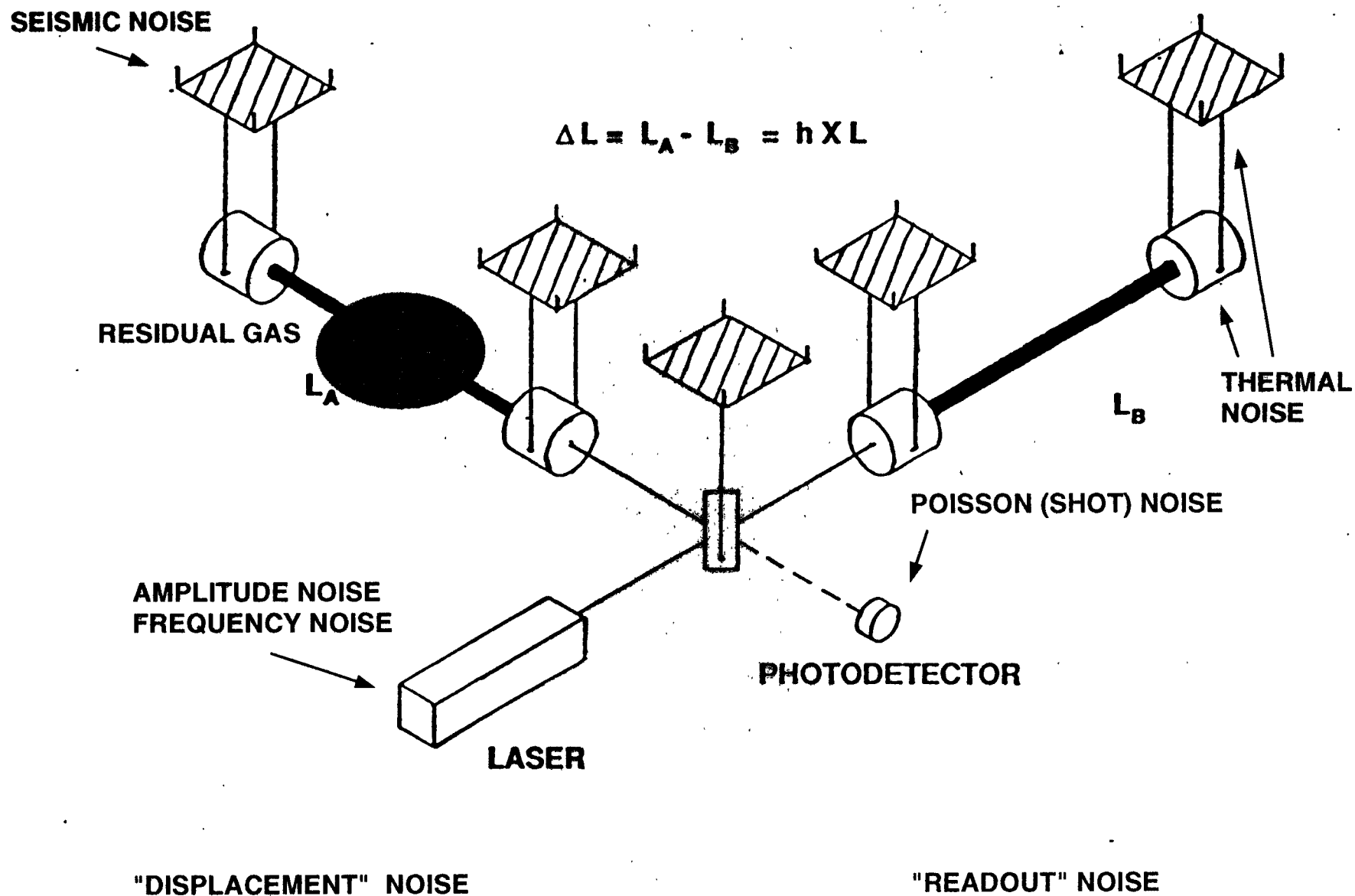
Limitations: types of noise

Sensitivity to GW depends on conversion of h to ϕ , and on ability to measure ϕ

Noise sources:

- natural division into
 - sensing noise (generally optical sources)
 - displacement noise (forces on test masses)
- fundamental vs. technical
- statistical characteristics:
 - stationary noise
 - quasi-stationary noise, changes on time scales of seconds
 - impulsive noise: time scale of GW events or shorter
 - periodic ‘noise’
- length scaling
- frequency dependence

SCHMATIC INTERFEROMETRIC DETECTOR



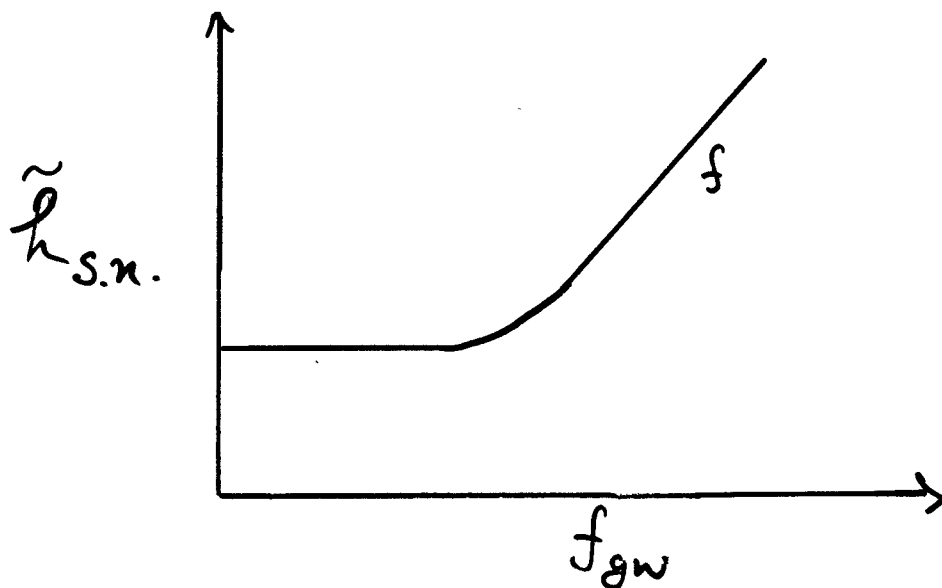
Fundamental limits

Shot or Poisson noise

- intensity at ifo output is a function of arm phase difference:

$$P_{\text{out}} = \frac{P_{\text{in}}}{2} (1 - \cos [\delta\phi])$$

- maximum slope: $\frac{dP}{d\delta\phi} = \frac{P_{\text{in}}}{2}$
- uncertainty in intensity due to counting statistics: $\tilde{\delta P}_{\text{out}} = \sqrt{2h\nu P}$
- can solve for equivalent strain: $h_{\text{shot}} = \frac{1}{|\delta\phi/h|} \sqrt{\frac{2h\nu}{P_{\text{in}}}}$
- Note: scaling with $1/\sqrt{P_{\text{in}}}$; gives requirement for laser power



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Quantum noise

Radiation Pressure

- quantum-limited intensity fluctuations anti-correlated in two arms
 - › results from vacuum fluctuations entering output port

- photons exert a time varying force, with spectral density

$$\tilde{f} = \sqrt{\frac{2\pi h P_{\text{in}}}{c\lambda}}$$

- results in opposite displacements of EACH of the masses:

$$\tilde{x}(f) = \frac{1}{mf^2} \sqrt{\frac{hP_{\text{in}}}{8\pi^3 c\lambda}}, \text{ or strain } h = \frac{\delta l}{l} = \frac{2\tilde{x}}{L}$$

- NOTE: scaling with $\sqrt{P_{\text{in}}}$, and with interferometer arm length L

total readout, or quantum noise

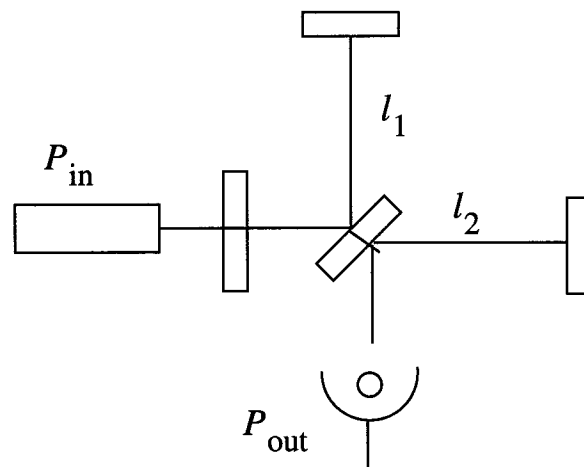
- quadrature sum $h_q = \left(h_{\text{shot}}^2 + h_{\text{rad press}}^2 \right)^{1/2}$
- frequency dependence according to ifo configuration, but
- always a minimum for a given frequency as a function of Power
- for simple Michelson, $P_{\text{opt}} = \pi c \lambda m f^2$; later limitation, not now

Lowering shot noise: recycling

Problem: insufficient laser power

- sensitivity goal requires shot noise from ~ 100 W on beamsplitter
- suitable lasers produce ~ 10 W, ~ 5 W at the ifo input

Solution: make a resonant cavity out of the interferometer and an additional mirror at the input



- ifo output port is operated at the ‘dark fringe’
- then nearly all the input power is reflected back towards laser (when optical losses are low)
- factor or ~ 30 increase in effective power possible
- improves the shot noise limited sensitivity by $\sqrt{\text{gain}} \approx 5-6$

Displacement noise

Fundamental

- Thermal noise: mechanical systems excited by thermal environment
 - ›› nearly all of each mode's kT 's worth of thermal energy is at the resonant peak, but small fraction is distributed in frequency
 - ›› lower mechanical loss \rightarrow lower thermal motion out-of-resonance
 - ›› Below resonance: internal modes of test masses
 - ›› Above resonance: pendulum suspension
- Gravity gradients
 - ›› time varying mass distributions in the vicinity of the test masses produce fluctuating forces on them
 - ›› surface seismic compressional waves, weather, moving objects (humans!)
 - ›› places limit on lowest frequencies detectable by ground based detectors of a few Hertz

Both these noise sources scale with arm length L

Thermal noise leads to LIGO 4km length



Initial LIGO sensitivity

