



Advances in coherent network searches for gravitational-wave bursts

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Outline

- Standard Formulation of Coherent Analysis for GWBs
 - detection
 - waveform estimation
 - consistency test (GWBs vs. glitches)
 - source location
- Recent Advances (last 12 months):
 - regularized likelihoods
 - improved consistency tests
 - maximum entropy waveform estimation

Coherent Analysis for GWBs

“Standard Likelihood” Formulation

The Basic Problem & Response

- Output of $D \geq 3$ detectors with noise amplitudes σ_i :
 - Waveforms $h_+(t)$, $h_\times(t)$, source direction Ω all unknown. *How do we find them?*

$$\begin{array}{cccc}
 \text{data} & & \text{antenna responses} & \text{GWB} & \text{white} \\
 & \searrow & (\Omega \text{ unknown}) & (\text{unknown}) & \text{noise} \\
 & & \downarrow & \downarrow & \downarrow \\
 \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_D \end{bmatrix} & = & \begin{bmatrix} F_1^+(\Omega)/\sigma_1 & F_1^\times(\Omega)/\sigma_1 \\ F_2^+(\Omega)/\sigma_2 & F_2^\times(\Omega)/\sigma_2 \\ \vdots & \vdots \\ F_D^+(\Omega)/\sigma_D & F_D^\times(\Omega)/\sigma_D \end{bmatrix} & \begin{bmatrix} h^+ \\ h^\times \end{bmatrix} & + & \begin{bmatrix} n_1 \\ n_2 \\ \vdots \\ n_D \end{bmatrix}
 \end{array}$$

- **Approach:** Treat Ω and $h_+(t)$, $h_\times(t)$ as parameters to be fit by the data.
 - Scan over the sky (Ω).
 - At each sky position construct the least-squares fit to h_+ , h_\times from the data.
 - The amplitude of h_+ , h_\times (SNR) and the quality of the fit (χ^2) determine if a GWB is detected.

The Modern View

Gursel & Tinto PRD **40** 3884 (1989)

Flanagan & Hughes, PRD **57** 4566 (1998)

Follow formulation by [Rakhmanov, gr-qc/0604005](#). Adopt matrix notation:

$$\mathbf{d} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_D \end{bmatrix} \quad \mathbf{F} = \begin{bmatrix} F_1^+(\Omega)/\sigma_1 & F_1^\times(\Omega)/\sigma_1 \\ F_2^+(\Omega)/\sigma_2 & F_2^\times(\Omega)/\sigma_2 \\ \vdots & \vdots \\ F_D^+(\Omega)/\sigma_D & F_D^\times(\Omega)/\sigma_D \end{bmatrix} \quad \mathbf{h} = \begin{bmatrix} h^+ \\ h^\times \end{bmatrix} \quad \mathbf{n} = \begin{bmatrix} n_1 \\ n_2 \\ \vdots \\ n_D \end{bmatrix}$$

Dx1 Dx2 2x1 Dx1

Vector of network data values:

$$\mathbf{d} = \mathbf{Fh} + \mathbf{n}$$

Waveform Estimation by Least-Squares

For trial sky position Ω , compute $\mathbf{F}(\Omega)$ and find best-fit waveform \mathbf{h} that minimizes residual $(\mathbf{d}-\mathbf{F}\mathbf{h})^2$. Simple linear problem!

$$\mathbf{0} = \left. \frac{\partial (\mathbf{d} - \mathbf{F}\mathbf{h})^* (\mathbf{d} - \mathbf{F}\mathbf{h})}{\partial \mathbf{h}^*} \right|_{\mathbf{h} = \hat{\mathbf{h}}}$$

* = conjugate
transpose

$$\Rightarrow \hat{\mathbf{h}} = (\mathbf{F}^* \mathbf{F})^{-1} \mathbf{F}^* \mathbf{d}$$

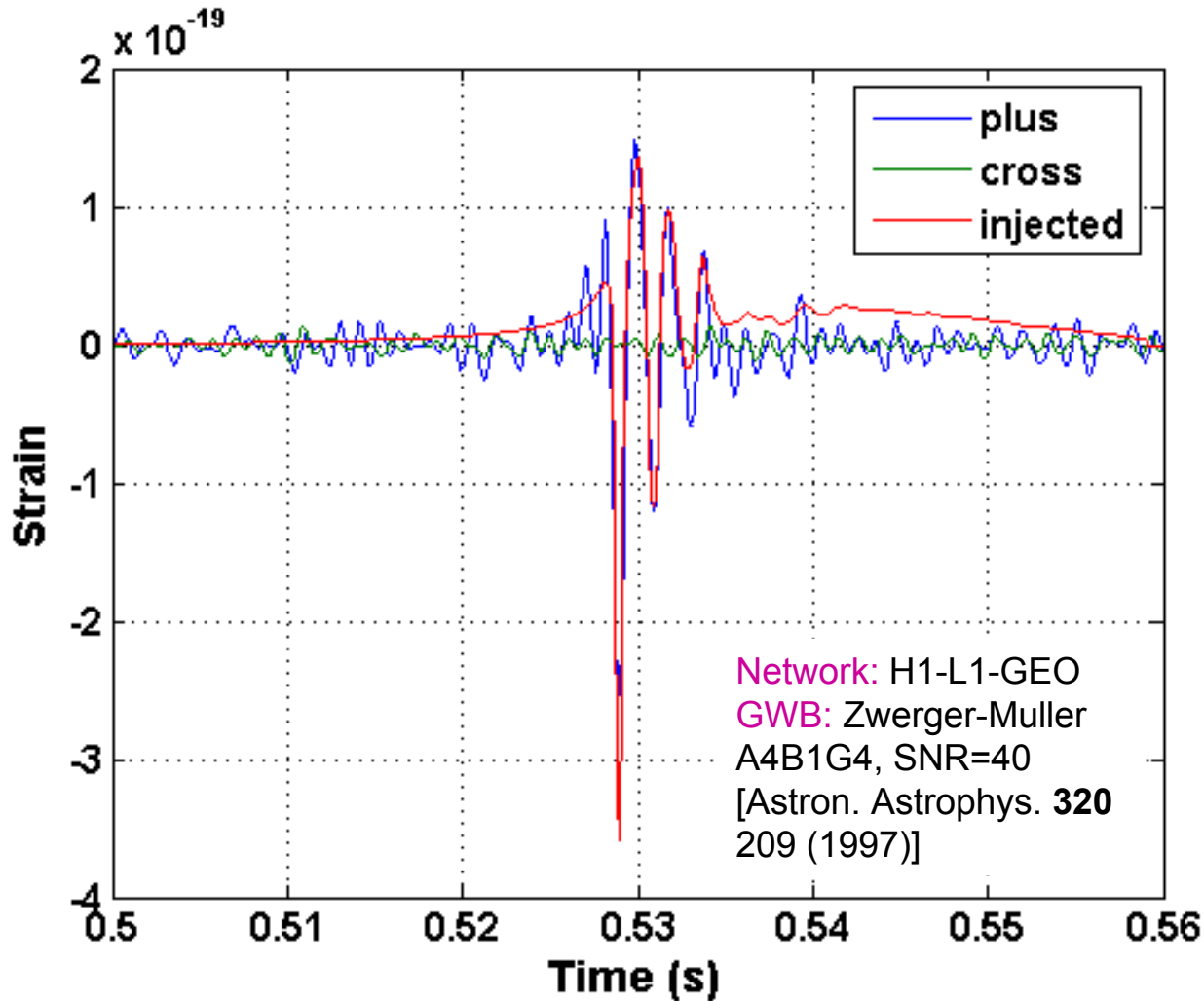
linear best-fit
solution for h_+ , h_x

“Moore-Penrose inverse” (2xD matrix) :

$$\mathbf{F}_{\text{MP}}^{-1} := (\mathbf{F}^* \mathbf{F})^{-1} \mathbf{F}^* \quad \mathbf{F}_{\text{MP}}^{-1} \mathbf{F} = \mathbf{I}$$

$$\hat{\mathbf{h}} = \mathbf{F}_{\text{MP}}^{-1}(\Omega) \mathbf{d}$$

Example: Supernova GWB Recovery



Recovered signal (blue) is a noisy, band-passed version of injected GWB signal (red)

Injected GWB signal has $h_x = 0$.

Recovered h_x (green) is just noise.

Detection from Likelihood Ratio

Is \mathbf{d} due to a GWB (\mathbf{h}) or Gaussian noise ($\mathbf{h}=0$)?

Detection statistic: threshold on maximum of the *likelihood ratio*

$$\mathbf{L} \equiv \log \frac{\mathbf{P}(\mathbf{d} | \mathbf{h})}{\mathbf{P}(\mathbf{d} | \mathbf{0})} = \frac{1}{2} \underbrace{\mathbf{d}^* \mathbf{d}}_{\text{“total energy”}} - \frac{1}{2} \underbrace{(\mathbf{d} - \mathbf{Fh})^* (\mathbf{d} - \mathbf{Fh})}_{\text{“null energy”}}$$

in original data after subtracting \mathbf{h}

Maximum value of likelihood is attained for $\mathbf{h} = \hat{\mathbf{h}}$

$$\mathbf{L}_{\max} = \mathbf{L}(\hat{\mathbf{h}}) = -\frac{1}{2} \mathbf{d}^* \mathbf{F} \mathbf{F}_{\text{MP}}^{-1} \mathbf{d} = \frac{1}{2} (\mathbf{E}_{\text{total}} - \mathbf{E}_{\text{null}}) \quad \leftarrow \text{detection if } \mathbf{L}_{\max} > \text{threshold}$$

Flanagan & Hughes, PRD **57** 4566 (1998)

Anderson *et al.* PRD **63** 042003 (2001)


Consistency Test: GWB vs. Glitch

Wen & Schutz, CQG **22** S1321 (2005)

Ajith, Hewitson & Heng, gr-qc/0604004 (2006)

Consistency: Is the transient a true GWB or a noise “glitch”? If a GWB, then residual data should be pure Gaussian noise \Rightarrow energy is χ^2 distributed:

$$\mathbf{E}_{\text{null}} \equiv (\mathbf{d} - \mathbf{F}\hat{\mathbf{h}})^* (\mathbf{d} - \mathbf{F}\hat{\mathbf{h}}) \sim \chi^2([\mathbf{D} - \mathbf{2}]\mathbf{N})$$

true GWB
  $\langle \mathbf{E}_{\text{null}} \rangle \approx [\mathbf{D} - \mathbf{2}]\mathbf{N} \left[1 \pm \mathcal{O}\left(\frac{1}{\sqrt{[\mathbf{D} - \mathbf{2}]\mathbf{N}}}\right) \right]$

If $E_{\text{null}} \gg [D-2] N$ then reject event as noise “glitch”.

Source Location

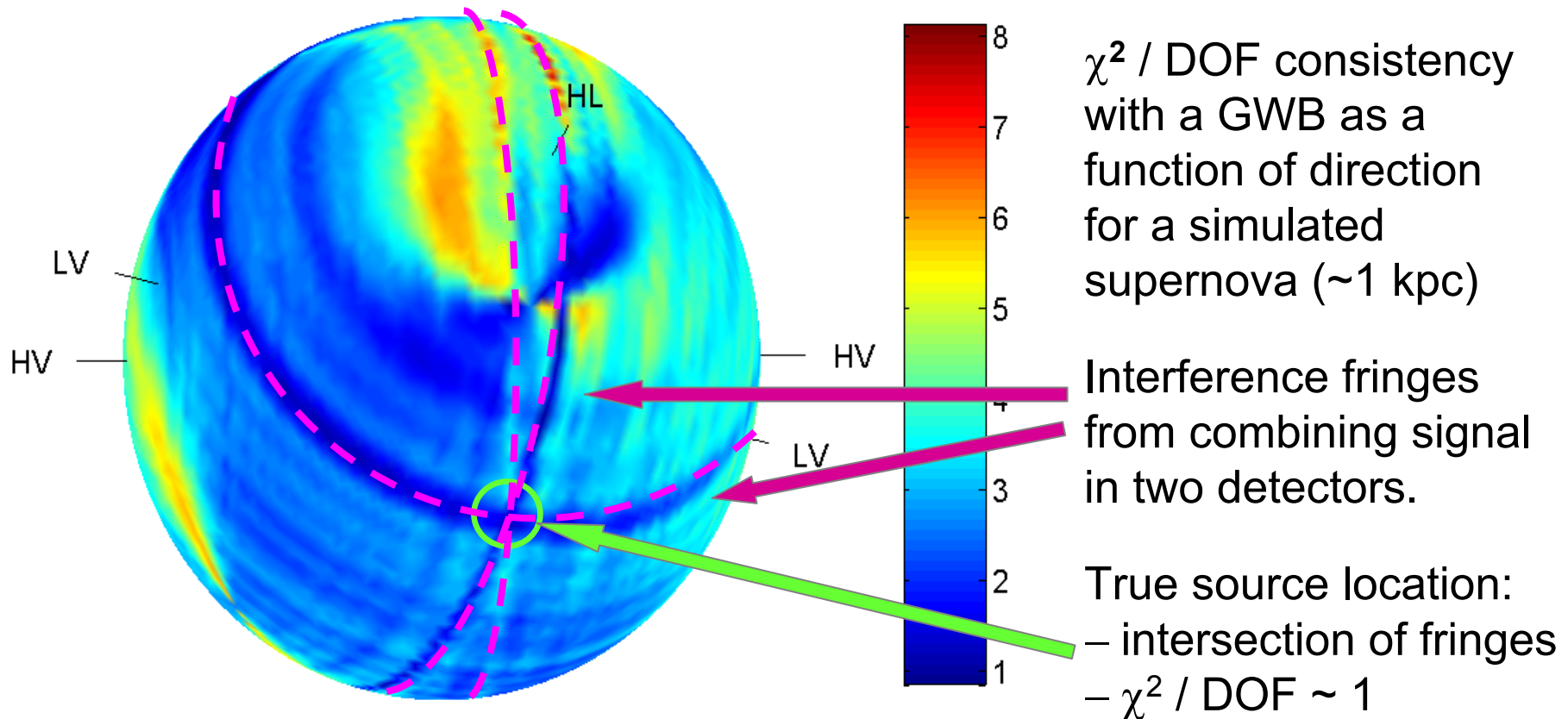
Source location: Usually we do not know the direction of the GWB source *a priori* (with exceptions: supernova, GRB, ...)

Simplest solution: Moore-Penrose inverse depends on sky position:

$$\mathbf{F}_{\text{MP}}^{-1} = \mathbf{F}_{\text{MP}}^{-1}(\boldsymbol{\Omega})$$

Test over grid of sky positions. Estimate $\boldsymbol{\Omega}$ as sky position with lowest χ^2 .

Example: Supernova GWB



GWB: Dimmelmeier et al. A1B3G3 waveform, *Astron. Astrophys.* 393 523 (2002), SNR = 20

Network: H1-L1-Virgo, design sensitivity

Pros and Cons

- This standard approach is known as the “**maximum likelihood**” or “**null stream**” formalism.
- Very powerful:
 - Can detect, distinguish from noise, locate, and extract GWB waveform with no *a priori* knowledge of the waveform!
- Standard approach also has significant weaknesses:
 1. Need 3 detector sites at a minimum to fit out 2 waveforms!
 2. Very expensive on data (squanders statistics). Use up 2 detectors just fitting h_+ , h_x . (*More on next slide.*)
 3. Can break down at some sky positions & frequencies (\mathbf{F} becomes singular, so \mathbf{F}_{MP}^{-1} does not exist).

Cost in Statistical Power compared to Templated Searches

Consistency: If a GWB, then residual energy should be χ^2 distributed:

$$\langle \mathbf{E}_{\text{null}} \rangle \equiv \frac{1}{2} (\mathbf{d} - \mathbf{F}\hat{\mathbf{h}})^* (\mathbf{d} - \mathbf{F}\hat{\mathbf{h}}) \sim \chi^2 ([\mathbf{D} - 2]\mathbf{N})$$

D: number of detectors ~ 3

N: number of data samples per detector ~ 100

[D-2]N, not DN: Lose 2 data streams to make best-fit h_+ , h_x . Very expensive loss of data and loss of statistical power for the consistency test!

Compare to, e.g., matched filter for binary neutron-star inspiral signal:

- Templates have only 2 parameters to be fit to the data (mass of each star).
- Consistency test: $3N-2$ instead of N degrees of freedom.

Not a replacement for templated searches (if you have a good template)!

Post-Modernism

- Over the past year, several groups have rediscovered the maximum likelihood formalism and have extended and improved it.
- Advances on all fronts of coherent analyses:
 - detection
 - consistency / veto
 - source location (Wen's talk)
 - waveform extraction
- Also some amelioration of weaknesses on previous slide.
- Rest of talk: walk through examples from each area.

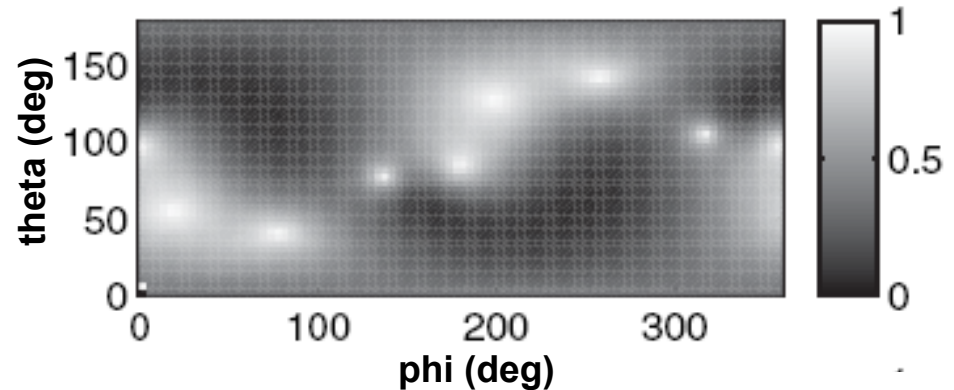
Breakdown of standard approach

Moore-Penrose inverse can be singular (ill-conditioned) for sky positions where network has poor sensitivity to one or both GW polarizations.

Klimenko et al., PRD **72** 122002 (2005): can choose polarization gauge (“**dominant polarization frame**”) such that

$$\mathbf{F}_{\text{MP}}^{-1} = \frac{1}{g} \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{\varepsilon} \end{pmatrix} \mathbf{F}^*$$

Alignment factor ε for LIGO-GEO-Virgo network



For some Ω , $\varepsilon(\Omega) \ll 1$. Estimated waveform for that polarization becomes noise dominated:

$$\hat{\mathbf{h}} \equiv \mathbf{F}_{\text{MP}}^{-1} \mathbf{d} = \mathbf{h} + \mathbf{F}_{\text{MP}}^{-1} \mathbf{n}$$

$\sim \mathbf{n}/\varepsilon$ for one polarization

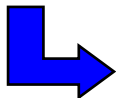
Regularization Schemes

- Breakdown of Moore-Penrose inverse explored in several recent papers:
 - Klimenko, Mohanty, Rakhmanov, & Mitselmakher: PRD **72** 122002 (2005), J. Phys. Conf. Ser. **32** 12 (2006), gr-qc/0601076
 - Rakhmanov gr-qc/0604005
- Key advance: [Regularization of Moore-Penrose inverse](#).
 - Effectively impose penalty factor for large values of h_+ , h_x .
 - Important side benefit: allows application to 2-detector networks.

One Example: Constraint Likelihood

- Klimentenko, Mohanty, Rakhmanov, & Mitselmakher: PRD **72** 122002 (2005), J. Phys. Conf. Ser. **32** 12 (2006).
- In dominant polarization frame:

$$L_{\max} = L_{\max,1} + L_{\max,2}$$


$$\langle L_{\max,1} \rangle \approx \frac{1}{2} (g h_1^2 + n^2)$$

$$\langle L_{\max,2} \rangle \approx \frac{1}{2} (\epsilon g h_2^2 + n^2)$$

small GWB
contribution

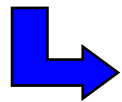
full noise
contribution

Constraint Likelihood

- Constraint likelihood: Lower weighting of less sensitive polarization “by hand”.

$$L_{\max} \Rightarrow L_{\max,1} \quad \text{“hard constraint”}$$

$$L_{\max} \Rightarrow L_{\max,1} + \epsilon L_{\max,2} \quad \text{“soft constraint”}$$



$$L_{\max,\text{hard}} \approx \frac{1}{2} (g h_1^2 + n^2)$$



zero signal and noise contribution from second polarization

$$L_{\max,\text{soft}} \approx \frac{1}{2} (g h_1^2 + \epsilon^2 g h_2^2 + [1 + \epsilon] n^2)$$



very small GWB contribution from second polarization



reduced noise contribution from second polarization

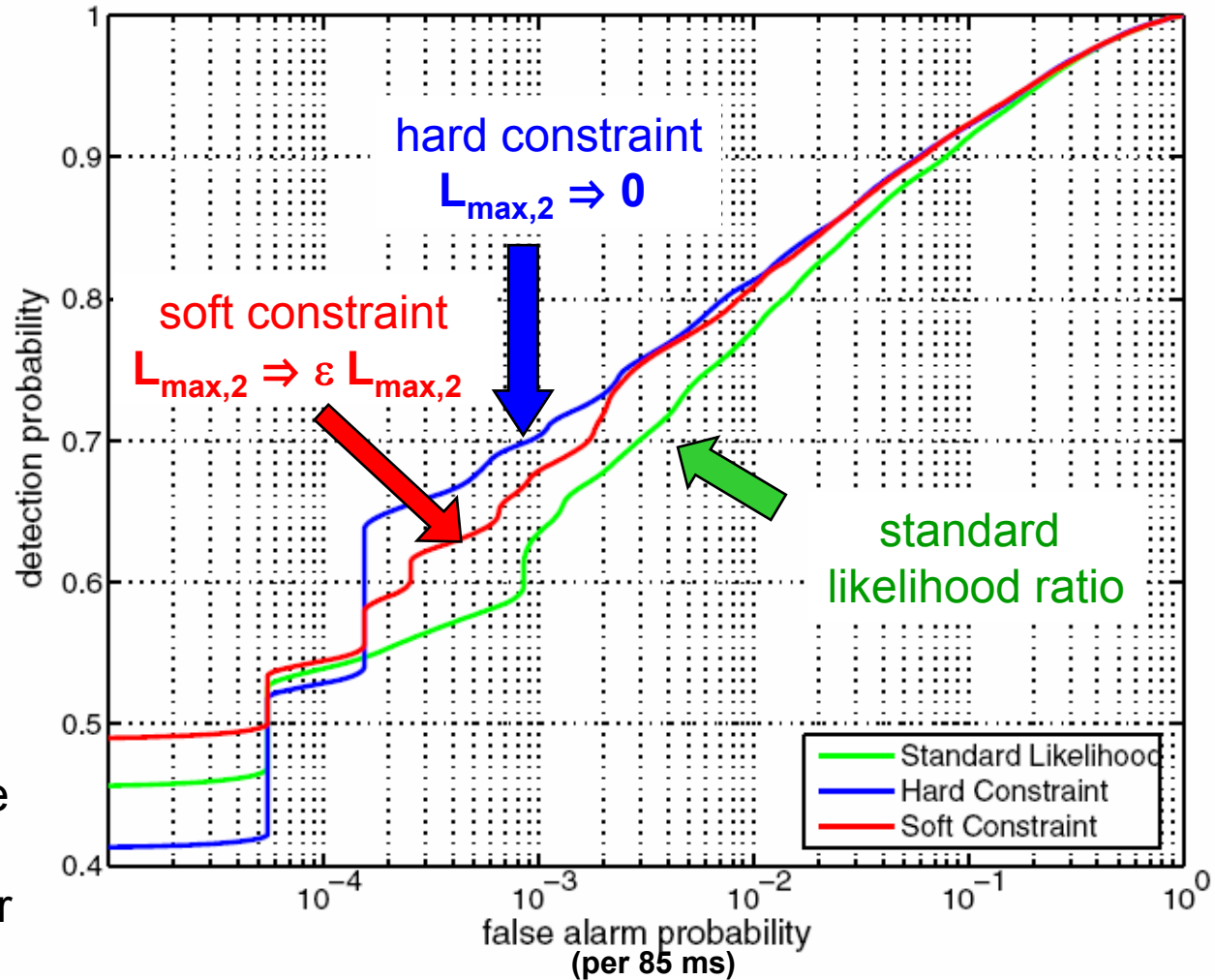
Example: ROC for Detecting Black-Hole Mergers (again)

From Klimenko et al.,
PRD **72** 122002 (2005)

Injected signal:
“Lazarus” black-hole
merger, SNR=6.9
[Baker et al., PRD **65**
124012 (2002)]

Network:
H1-L1-GEO (white
noise approximation)

Constraint likelihoods have
better detection efficiency
than standard likelihood for
some false alarm rates.



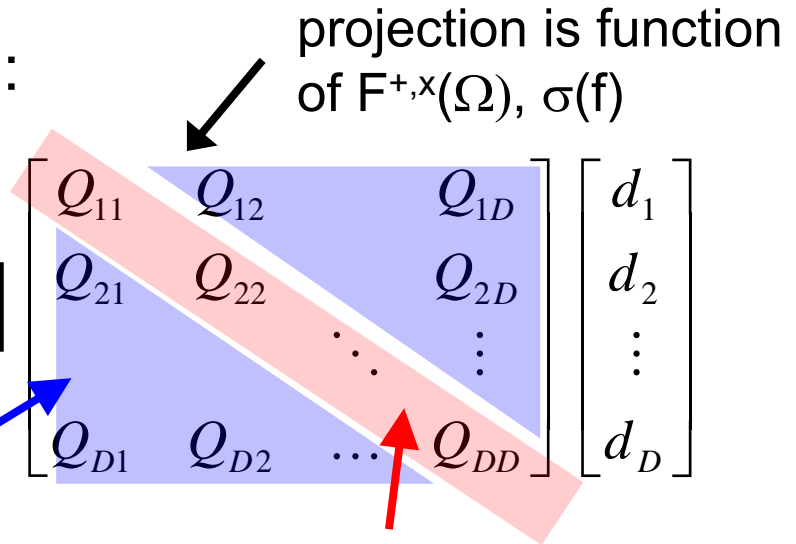
Improved Consistency / Veto Test

- Real interferometers have noise glitches.
- A χ^2 test can be fooled by, e.g., calibration errors (GWB not exactly subtracted out, so $\chi^2 > 1$), or weak glitches (so $\chi^2 \sim 1$).
- Chatterji, Lazzarini, Stein, Sutton, Searle, & Tinto, [grqc/0605002](https://arxiv.org/abs/grqc/0605002) proposed a robust consistency test.
 - Compare energy in residual (the χ^2) to that expected for *uncorrelated* glitches.

How much cancellation is enough?

- Look at energy in residual data:

$$\mathbf{E}_{\text{null}} = (\mathbf{d} - \mathbf{F}\hat{\mathbf{h}})^2 = [d_1^* \quad d_2^* \quad \dots \quad d_D^*]$$



cross-correlation terms
“correlated energy”

glitch: ~ 0

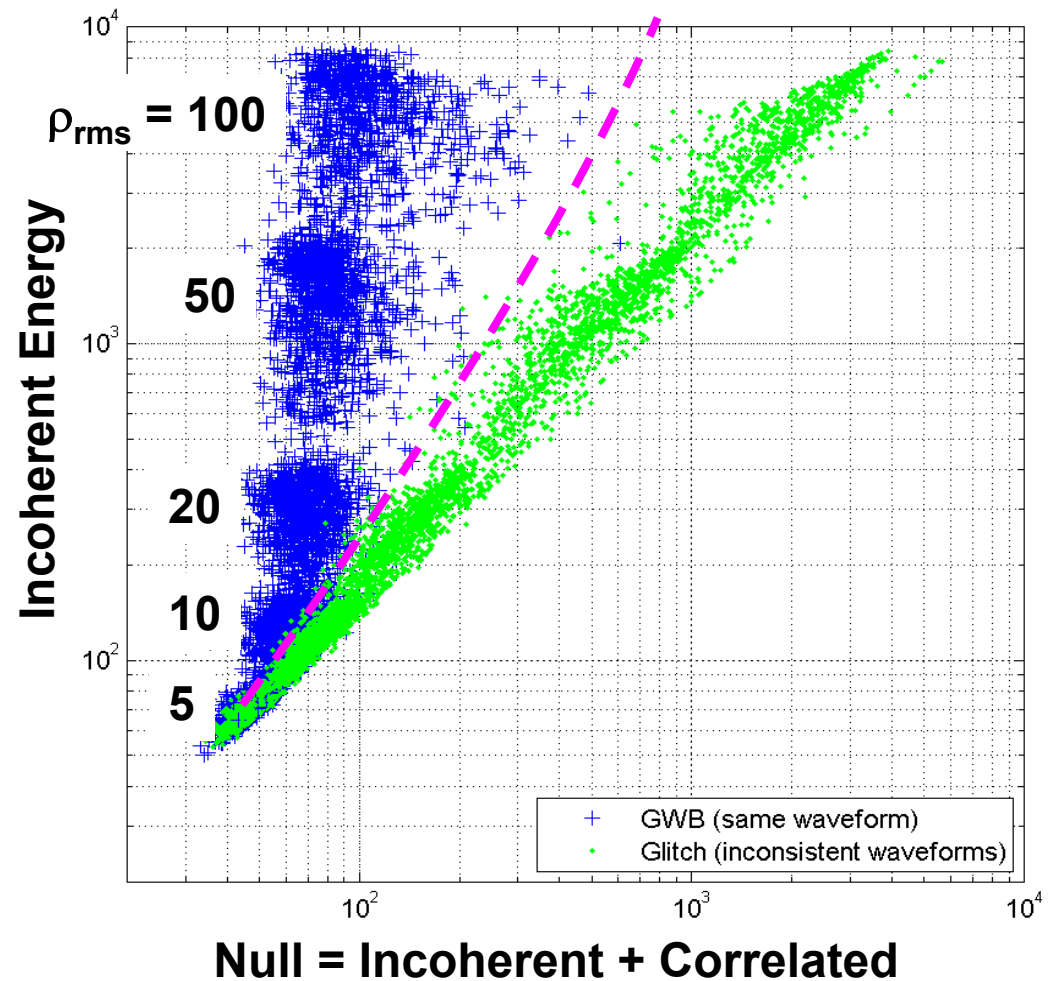
GWB: = -1 x incoherent energy

auto-correlation terms
“incoherent energy”

$$\text{cancellation measure} \equiv \frac{\text{null energy } \mathbf{E}_{\text{null}}}{\text{incoherent energy } \mathbf{E}_{\text{inc}}} = \begin{cases} \ll 1 & \text{GWB} \\ \sim 1 & \text{glitch} \end{cases}$$

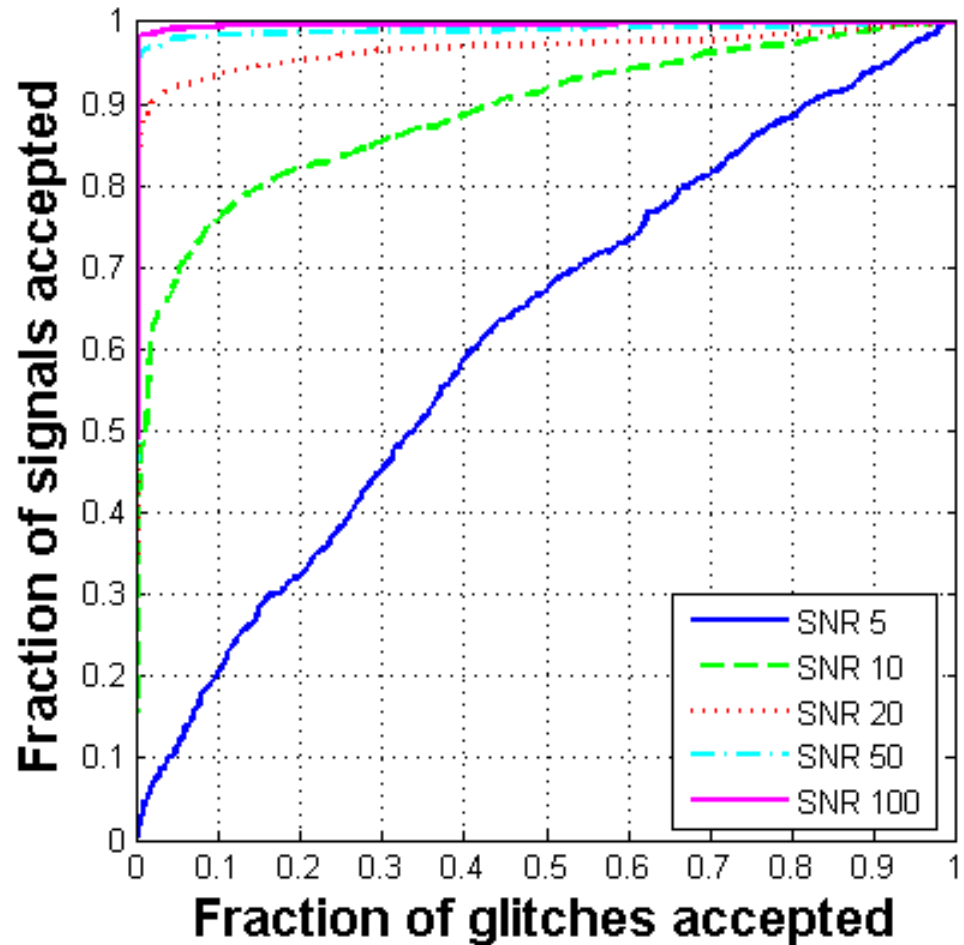
Example: 5000 GWBs vs. 5000 Glitches

- One point from each simulation.
 - sky position giving strongest cancellation
- GWB and glitch populations clearly distinguished for $\text{SNR} > 10$ -20.
 - Similar to detection threshold in LIGO.



ROC: Distinguishing GWBs from Glitches

- Good discrimination for $\text{SNR} > 10-20$.
 - Similar to detection threshold in LIGO.



Maximum Entropy Waveform Estimation

- *This section: work by Summerscales, Ph.D. Thesis, Pennsylvania State University (2006).*
- Another way to regularize waveform reconstruction and minimize fitting to noise.
- Add entropy prior $P(\mathbf{h})$ to maximum-likelihood formulation:

$$P(\mathbf{h} | \mathbf{d}, I) \propto P(\mathbf{d} | \mathbf{h}, I) P(\mathbf{h} | I)$$

standard
likelihood

prior on GWB
waveform

I : model

Maximum Entropy Cont.

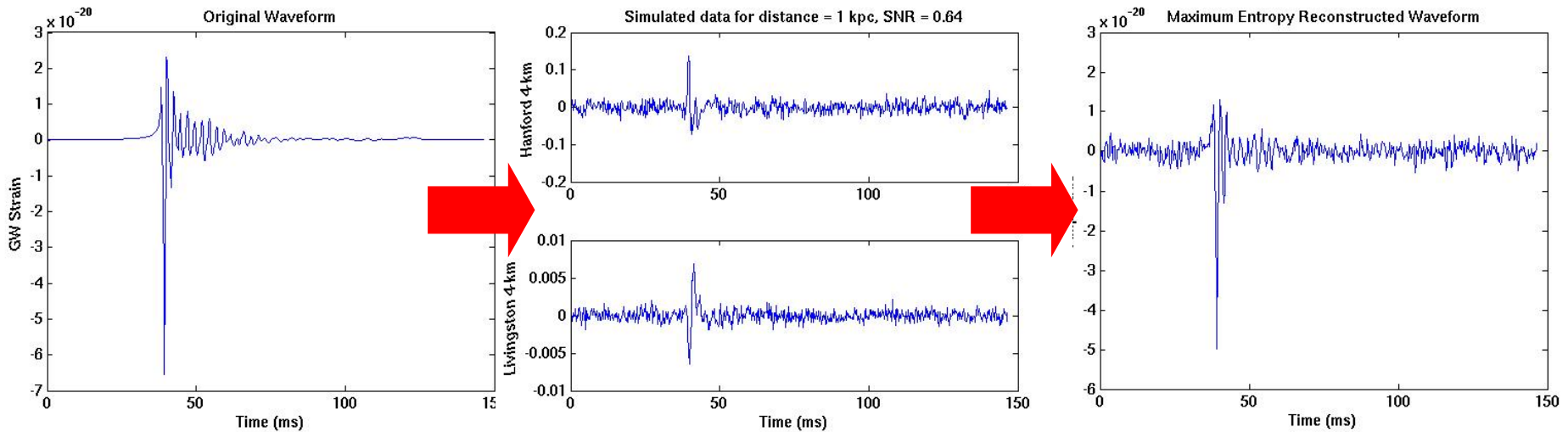
- Choice of prior:

$$P(\mathbf{h} | I) = \exp[\alpha S(\mathbf{h}, \mathbf{m})]$$

$$S(\mathbf{h}, \mathbf{m}) = \sum_{\text{time } i} \left(4m_i^2 + h_i^2\right)^{1/2} - 2m_i - h_i \log \frac{\left(4m_i^2 + h_i^2\right)^{1/2} + h_i}{2m_i}$$

- S: Related to Shannon Information Entropy (or number of ways quanta of energy can be distributed in time to form the waveform).
 - Not quite usual $\rho \ln \rho$ form of entropy because h can be negative.
 - [Hobson and Lasenby MNRAS 298 905 \(1998\)](#).
- Model m_i : Mean number of “positive” or “negative” quanta per time bin i .
 - Determined from data \mathbf{d} using Bayesian analysis.
- α is a Lagrange parameter that balances being faithful to the signal (minimizing χ^2) and avoiding overfitting (maximizing entropy)

Maximum Entropy Performance, Weak Signal



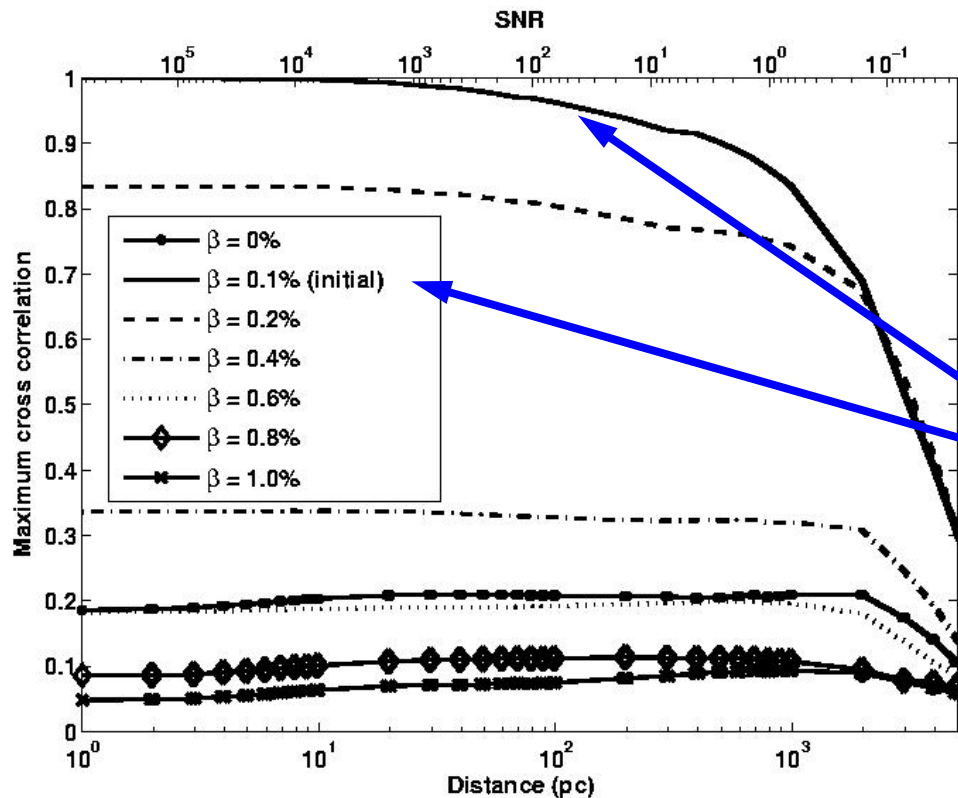
input GWB signal

noisy data from
two detectors

recovered GWB signal

[Summerscales, Finn, Ott, & Burrows \(in preparation\)](#): study ability to recover supernova waveform parameters (rotational kinetic energy, degree of differential rotation, equation of state polytropic index).

Extracting Rotational Information



- Cross correlations between reconstructed signal and waveforms from models that differ only by rotation parameter β (rotational kinetic energy).
- Reconstructed signal most closely resembles waveforms from models with the same rotational parameters

Summary

- Coherent analysis is a powerful technique for studying GWBs.
 - Matched-filter-like analysis with no *a priori* knowledge of waveform!
- The past year has seen rapid advances in coherent analysis techniques:
 - Regularization of data inversion
 - Improved detection efficiency, can apply to 2-detector networks
 - Exploration of priors on GWB waveforms (e.g. entropy)
 - Tests of ability extract physics from GWBs (supernovae)
 - Improved tests for discriminating GWBs from background noise
 - Much more work remains to be done (e.g., source localization)
- The first application of fully coherent techniques to real data is in progress
 - Constraint likelihood applied to LIGO S4 data from 2005 (stay tuned!).

Supplemental Slides

The Global Network

Several km-scale detectors, bars now in operation

Network gives:

Detection confidence

Direction by triangulation

Waveform extraction



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Waveform Estimation by Least-Squares

For trial sky position Ω , compute $\mathbf{F}(\Omega)$ and find best-fit waveform \mathbf{h} that minimizes residual $(\mathbf{d}-\mathbf{Fh})^2$. Simple linear problem!

$$\mathbf{0} = \frac{\partial(\mathbf{d}-\mathbf{Fh})^*(\mathbf{d}-\mathbf{Fh})}{\partial \mathbf{h}^*} \bigg|_{\mathbf{h}=\hat{\mathbf{h}}} = \mathbf{F}^*(\mathbf{d}-\mathbf{F}\hat{\mathbf{h}}) \quad * = \text{conjugate transpose}$$

$$\hat{\mathbf{h}} = (\mathbf{F}^*\mathbf{F})^{-1}\mathbf{F}^*\mathbf{d} \quad \leftarrow \text{linear best-fit solution for } h_+, h_x$$

“Moore-Penrose inverse” (2xD matrix) :

$$\mathbf{F}_{\text{MP}}^{-1} := (\mathbf{F}^*\mathbf{F})^{-1}\mathbf{F}^* \quad \mathbf{F}_{\text{MP}}^{-1}\mathbf{F} = \mathbf{I}$$

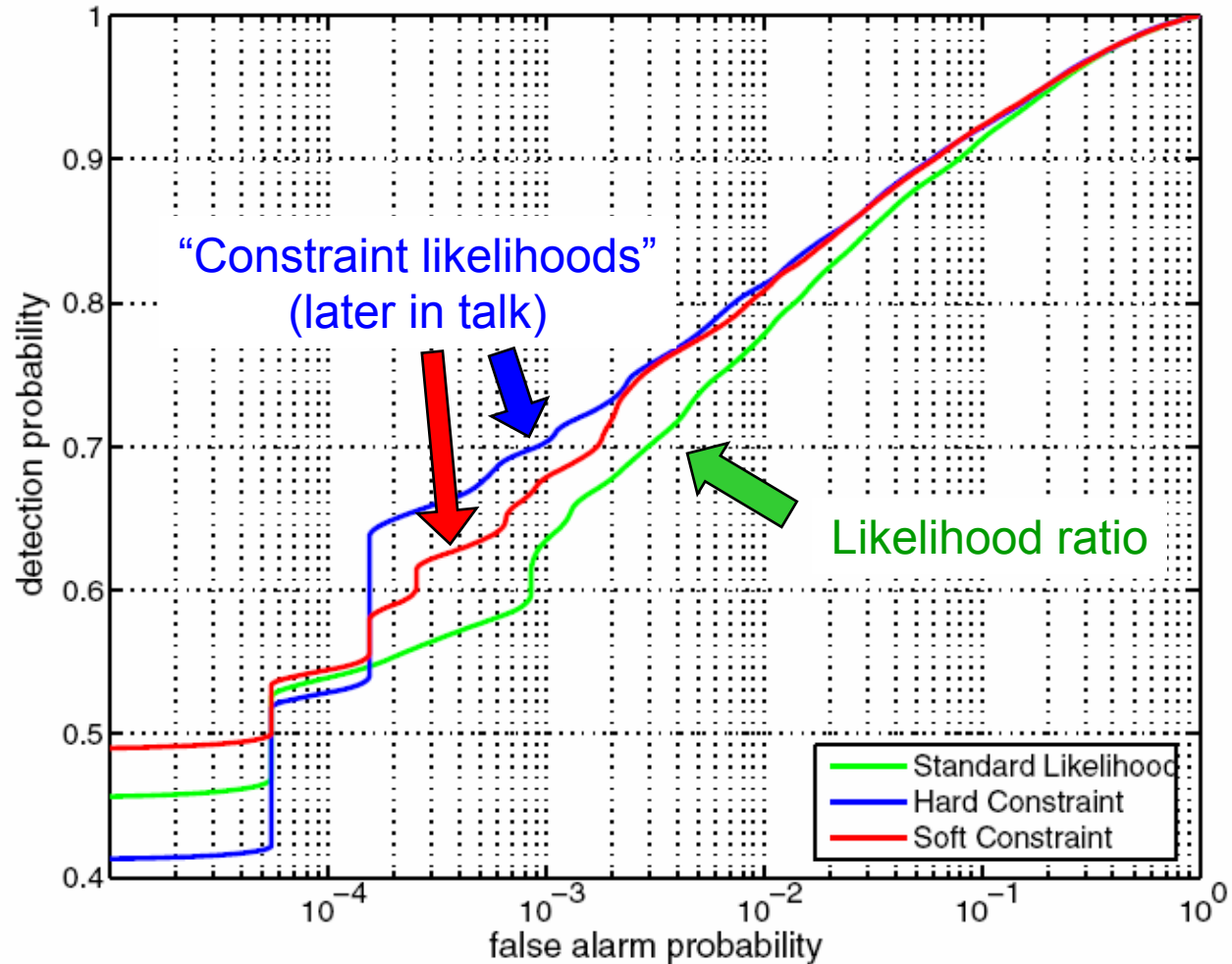
$$\hat{\mathbf{h}} = \mathbf{F}_{\text{MP}}^{-1}(\Omega)\mathbf{d}$$

Example: ROC for Detecting Black-Hole Mergers

From Klimenko et al.,
PRD **72** 122002 (2005)

Injected signal:
“Lazarus” black-hole
merger, SNR=6.9
[Baker et al., PRD **65**
124012 (2002)]

Network:
H1-L1-GEO (white
noise approximation)



(Brief) History of Coherent Techniques for GWBs

Ancient History

- Y. Gursel & M. Tinto PRD **40** 3884 (1989)
 - “Near Optimal Solution to the Inverse Problem for GWBs”.
- First solution of inverse problem for GWBs.
 - Source location, waveform extraction.
 - For detectors at 3 sites.
- Procedure:
 - Use 2 detectors to estimate GWB waveforms at each point on the sky.
 - Check estimated waveform for consistency with data from 3rd detector (χ^2 test).
 - Symmetrize χ^2 expression over the 3 detectors.
 - Used timing estimates to restrict region of sky to be scanned, find minimum of $\chi^2(\Omega)$.

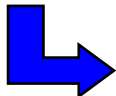
Medieval Times

- E.E. Flanagan & S.A. Hughes, PRD 57 4566 (1998)
 - *“Measuring gravitational waves from binary black hole coalescences: II. the waves' information and its extraction, with and without templates”*
 - Appendix A (!)
- Discovered maximum-likelihood formulation of detection & inverse problems.
 - Generalized to 3+ detectors, colored noise.
 - Equivalent to Gursel-Tinto for 3 detectors.

One Example: Constraint Likelihood

- Klimentenko, Mohanty, Rakhmanov, & Mitselmakher: PRD **72** 122002 (2005), J. Phys. Conf. Ser. **32** 12 (2006).
- In dominant polarization frame:

$$\mathbf{L}_{\max} = \mathbf{L}_{\max,1} + \mathbf{L}_{\max,2} \quad \mathbf{F}_{\text{MP}}^{-1} = \frac{1}{g} \begin{pmatrix} 1 & 0 \\ 0 & \frac{1}{\varepsilon} \end{pmatrix} \mathbf{F}^*$$


$$\mathbf{L}_{\max,1} = \frac{1}{2g} ([\mathbf{F}_1/\sigma]^* \mathbf{d})^2 \approx \frac{1}{2} (g h_1^2 + n^2)$$

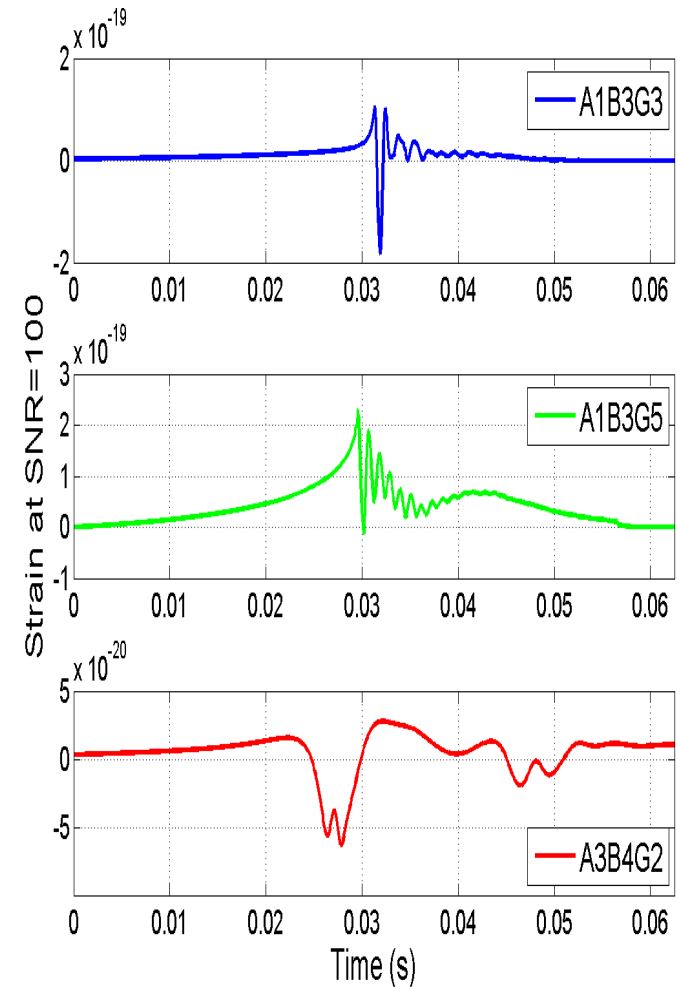
$$\mathbf{L}_{\max,2} = \frac{1}{\varepsilon} \frac{1}{2g} ([\mathbf{F}_2/\sigma]^* \mathbf{d})^2 \approx \frac{1}{2} (\varepsilon g h_2^2 + n^2)$$

small GWB
contribution

full noise
contribution

Testing the method

- GWBs:
 - 3 core-collapse supernova waveforms.
 - Dimmelmeier, Font, & Müller, A&A **393** 523-542 (2002).
 - Pick one DFM and add to each detector data stream.
- Glitches:
 - Inject a different supernova waveform into each detector
 - Use same time delays, amplitudes as a GWB. Pathological glitches!
- Detector Network:
 - LIGO-Virgo network @ design sensitivity



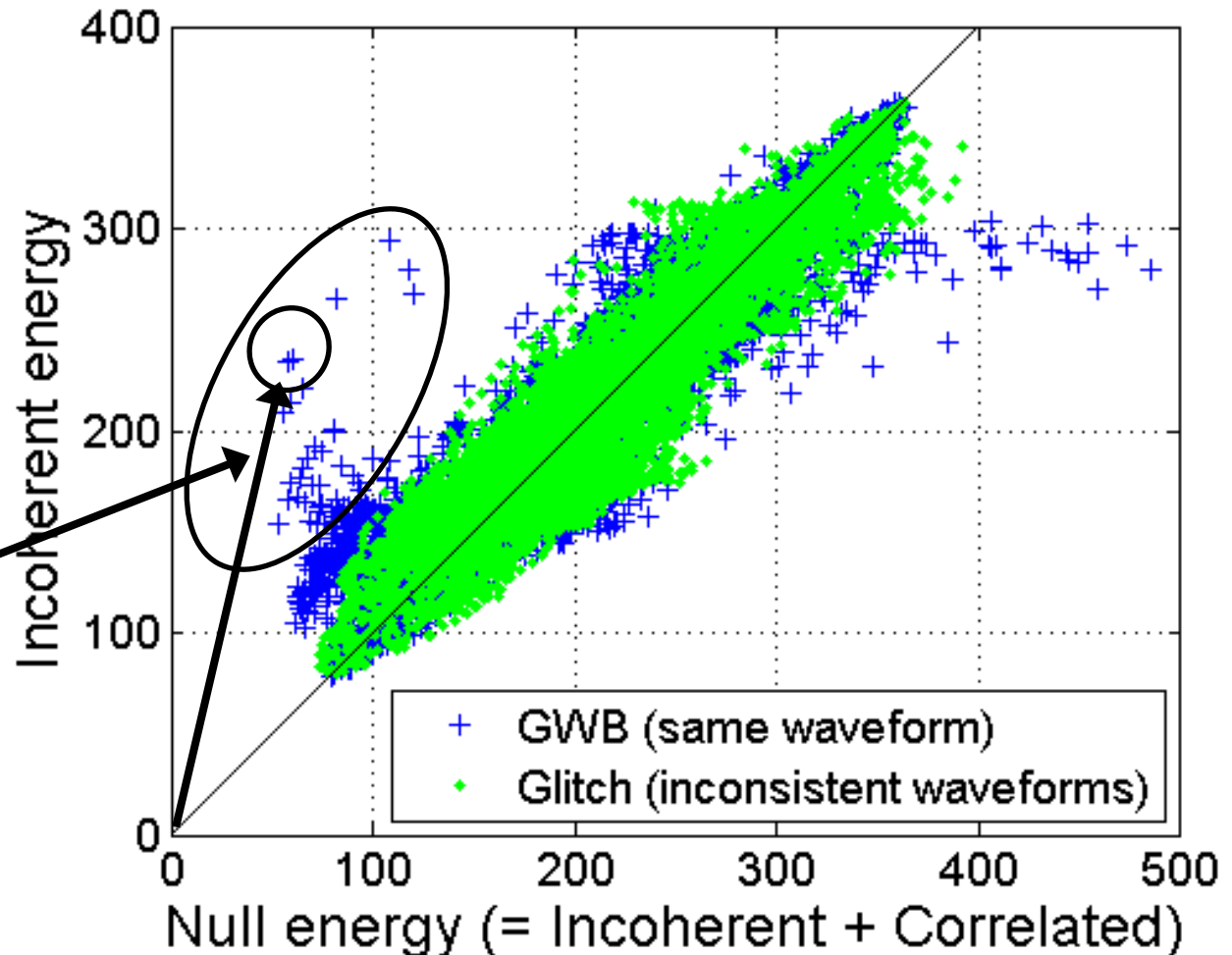
Example: 1 GWB vs. 1 Glitch

One point for each sky position tested (10^4 total).

Glitch lies on diagonal $E_{\text{null}} \sim E_{\text{inc}}$ (low correlation)

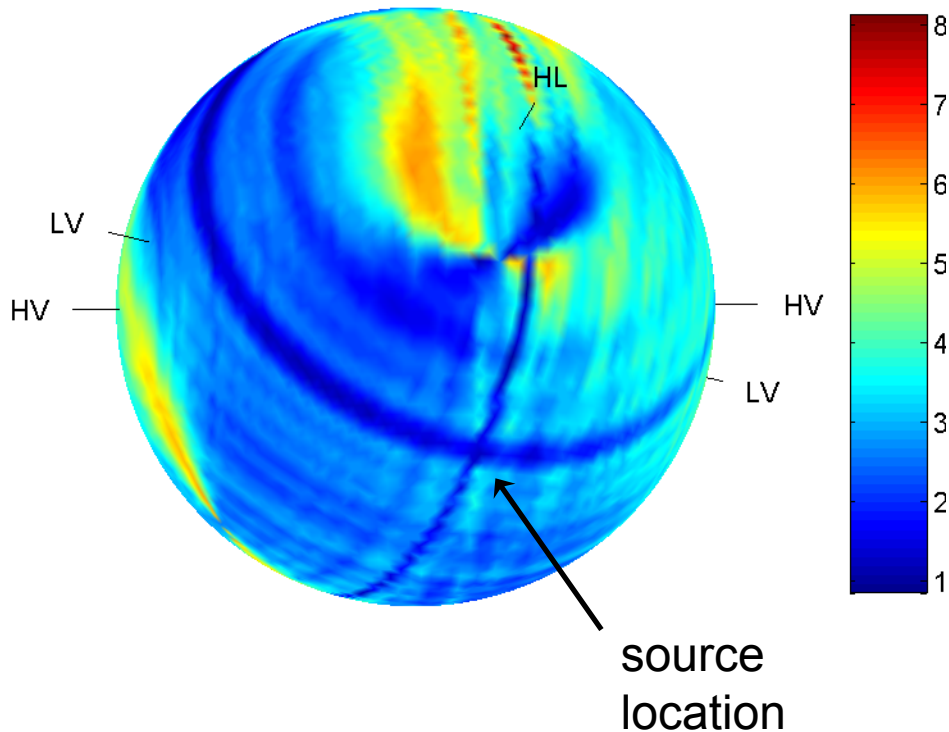
GWB has off-diagonal points $E_{\text{null}} \sim E_{\text{inc}}$ (high correlation)

Strongest cancellation (lowest $E_{\text{null}}/E_{\text{inc}}$)



Source Localization: Not Good!

E_{null} across the sky for 1 GWB
(Hanford-Livingston-Virgo network)

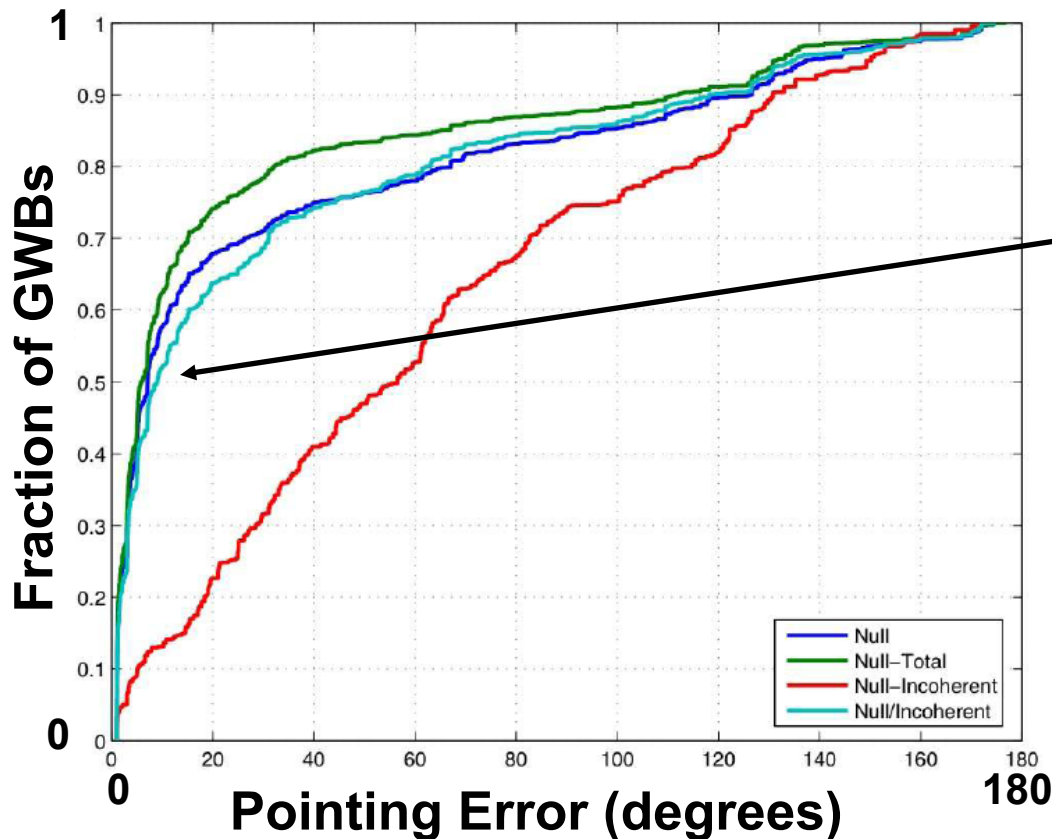


Null energy E_{null} varies slowly along rings of constant time delay with respect to any detector pair.

Noise fluctuations often move minimum away from source location (pointing error)

Example: Lazarus Black Hole Mergers, SNR = 100 (!) (H-L-V network)

Pointing Error for 10^4 Lazarus GWBs



L. Stein B.Sc. Thesis, Caltech, 2006.

Median pointing error $O(10)$ degrees.

Must use additional information for accurate source localization!

- E.g.: timing or global ring structure rather than local energy
- More research required!

Maximum Entropy Cont.

- Maximizing $P(\mathbf{h}|\mathbf{d},I)$ equivalent to minimizing

$$F(\mathbf{h} | \mathbf{d}, \mathbf{R}, \mathbf{N}, \mathbf{m}) = \chi^2(\mathbf{R}, \mathbf{h}, \mathbf{d}, \mathbf{N}) - 2\alpha S(\mathbf{h}, \mathbf{m})$$

- α is a Lagrange parameter that balances being faithful to the signal (minimizing χ^2) and avoiding overfitting (maximizing entropy)
- α associated with constraint which can be formally established. In summary: half the data contain information about the signal

Maximum Entropy Cont.

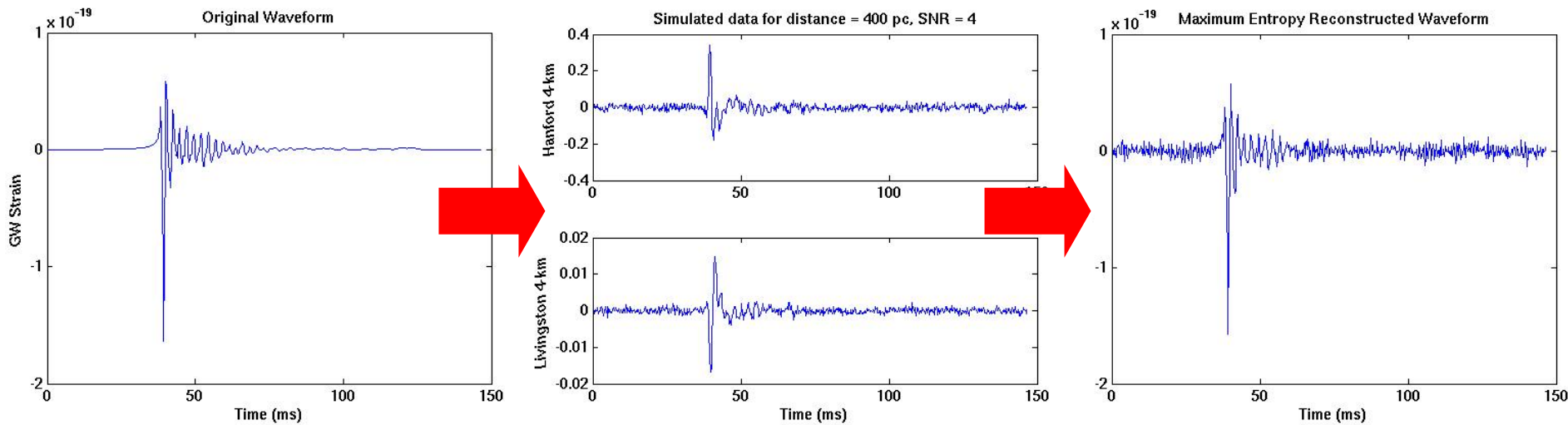
- Choosing m

- Pick a simple model where all elements $m_i = m$
- Model m related to the variance of the signal which is unknown
- Using Bayes' Theorem: $P(m|\mathbf{d}) \propto P(\mathbf{d}|m)P(m)$
- Assuming no prior preference, the best m maximizes $P(\mathbf{d}|m)$
- Bayes again: $P(\mathbf{h}|\mathbf{d},m)P(\mathbf{d}|m) = P(\mathbf{d}|\mathbf{h},m)P(\mathbf{h}|m)$
- Integrate over \mathbf{h} : $P(\mathbf{d}|m) = \int D\mathbf{h} P(\mathbf{d}|\mathbf{h},m)P(\mathbf{h}|m)$ where

$$P(\mathbf{d} | \mathbf{h}, m) = \frac{\exp(-\chi^2 / 2)}{\int D\mathbf{d} \exp(-\chi^2 / 2)} \quad P(\mathbf{h} | m) = \frac{\exp(\alpha S)}{\int D\mathbf{h} \exp(\alpha S)}$$

- Evaluate $P(\mathbf{d}|m)$ with m ranging over several orders of magnitude and pick the m for which it is highest

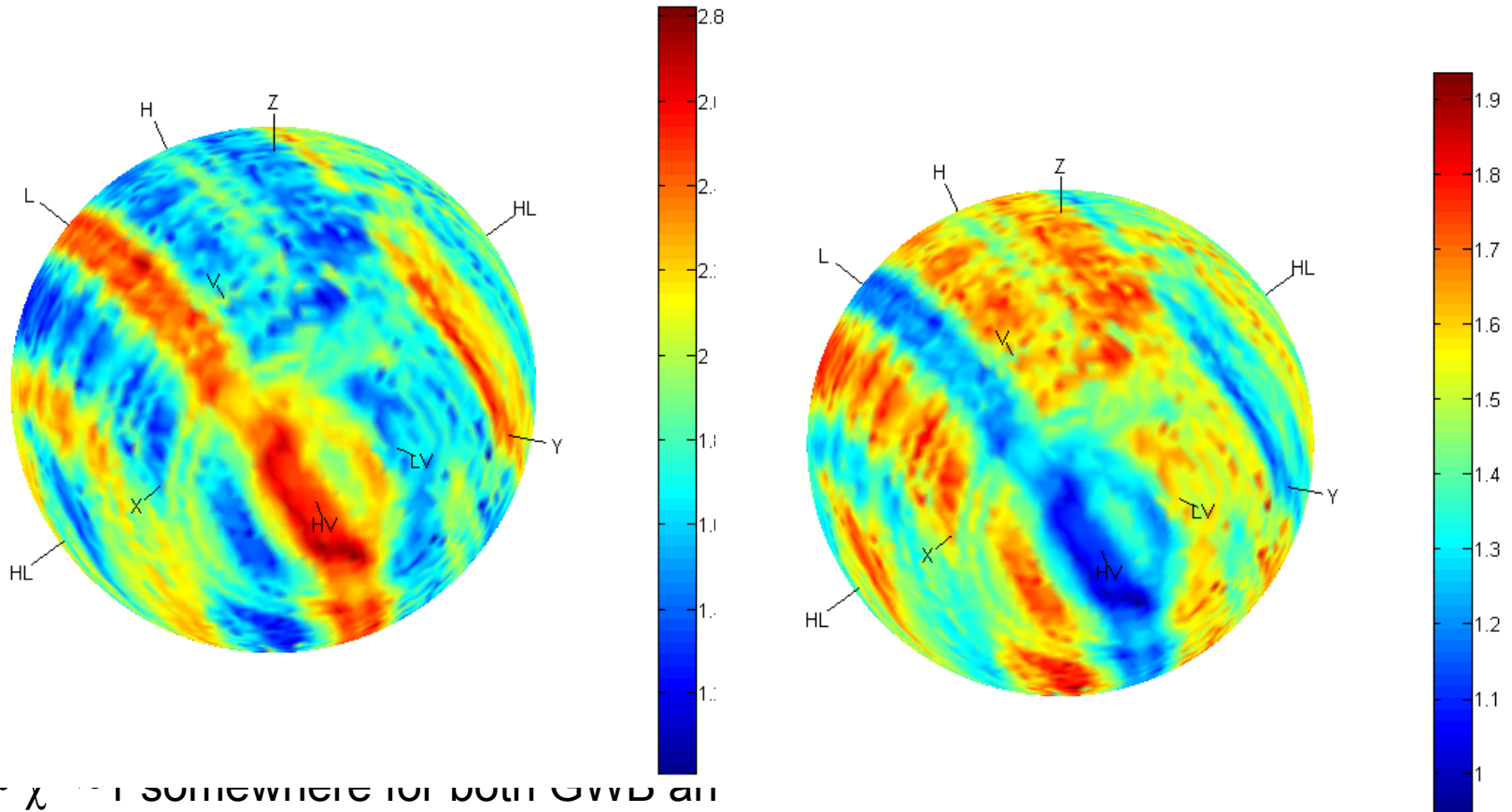
Maximum Entropy Performance, Strong Signal



- Maximum entropy recovers waveform with only a small amount of noise added

Sky Maps: Null Energy / DOF

GWB: Insert a Lazarus null energy map, Tot-Null map



Summary

- Gravitational-wave bursts are an interesting class of GW signals
 - Probes of physics of supernovae, black-hole mergers, gamma-ray burst engines, ...
- Coherent data analysis for GWBs using the global network of GW detectors is a potentially powerful tool for
 - detection
 - source localization
 - waveform extraction
 - consistency testing