SEISMIC ISOLATION SYSTEM (SEI) ASSEMBLY FIXTURE & SEQUENCE PRELIMINARY DESIGN REVIEW (PDR)

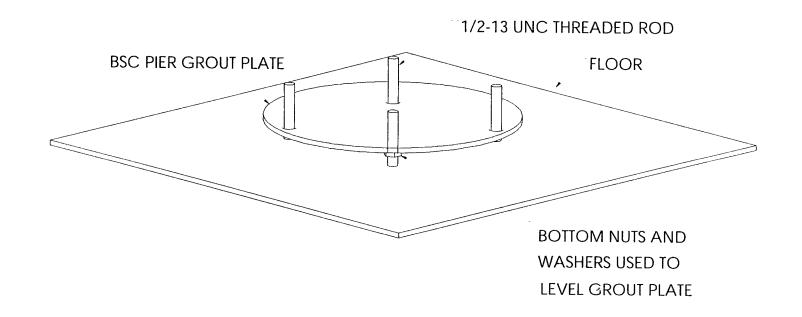
Bill K. Miller HYTEC Inc.

September 23, 1997

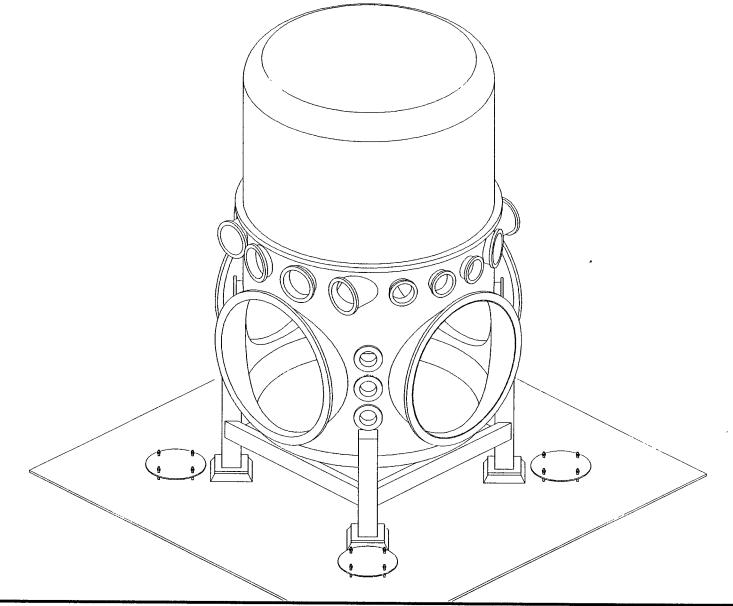
LIGO-G970291-00.D

3 P

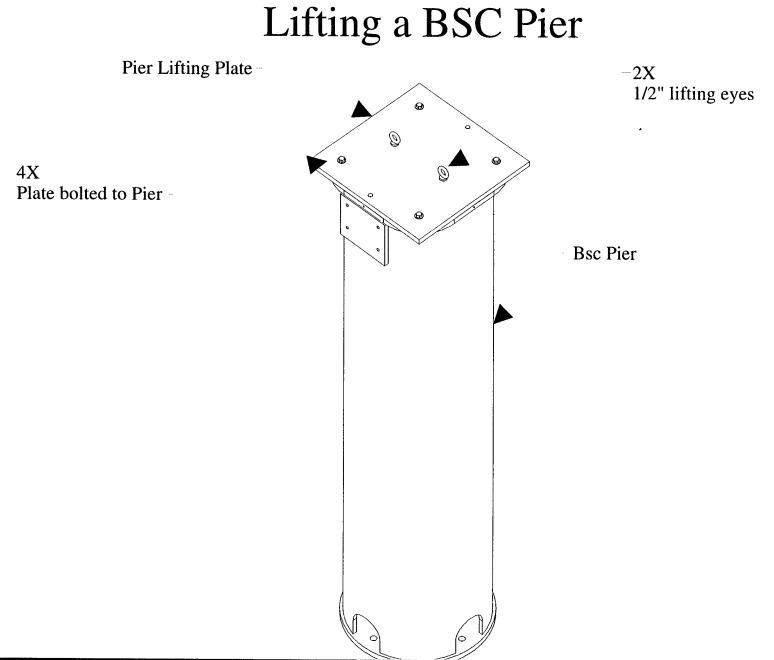
Pier Grout Plate Assembly



All Four Grout Plates Installed and Leveled

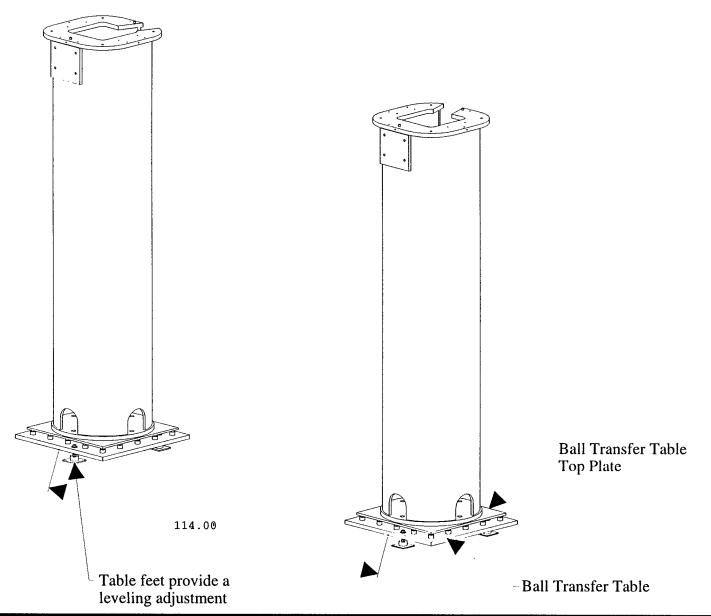


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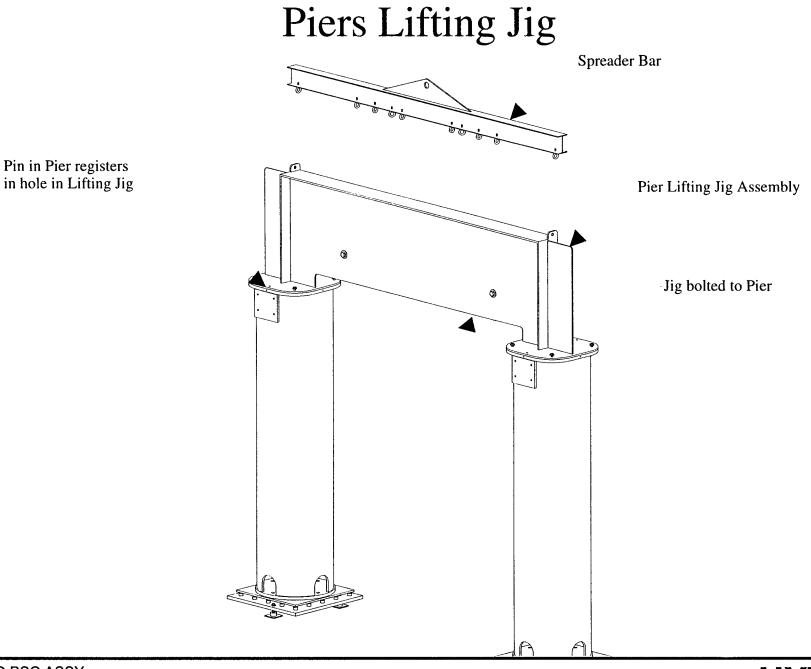


LIGO BSC ASSY 09/23/97 - WKM -TT 3

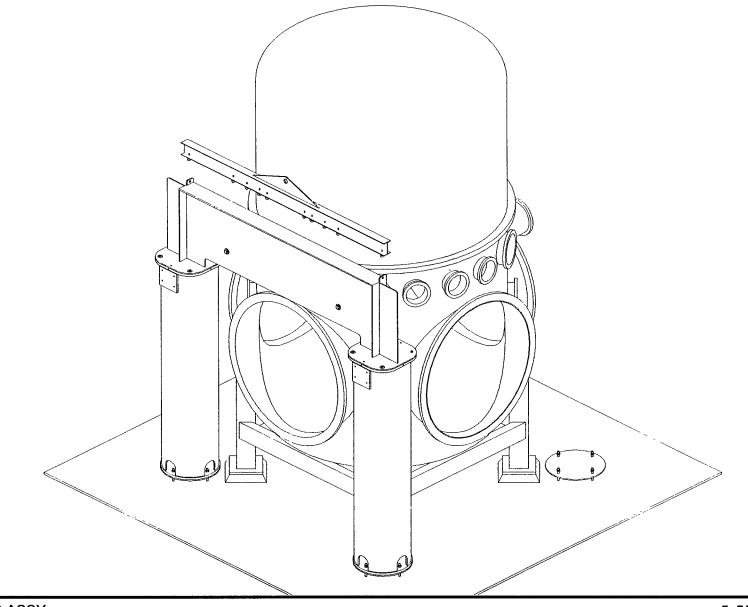
BSC Piers on Ball Transfer Tables



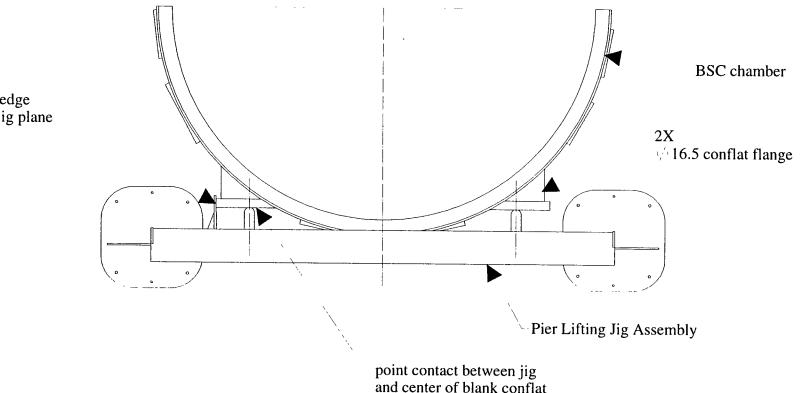
1



Piers are Lowered Into Position



Jig Referencing the Nozzle Port Surfaces

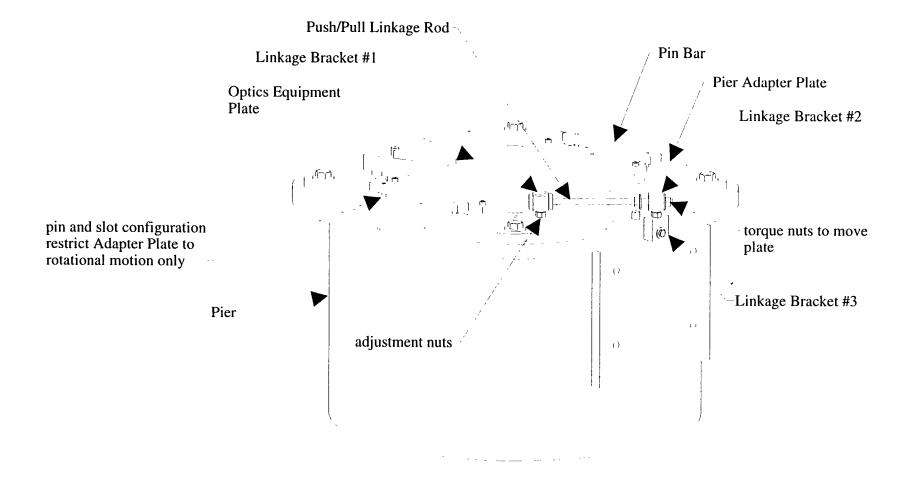


line contact between edge of blank conflat and jig plane

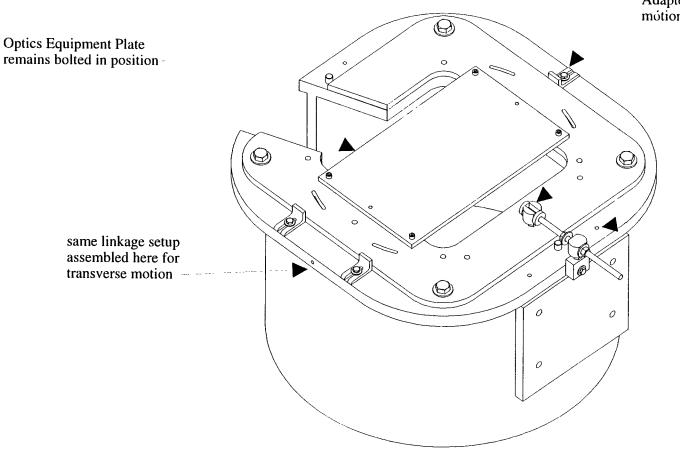
3



Leveling and Clocking the Pier Adapter Plate



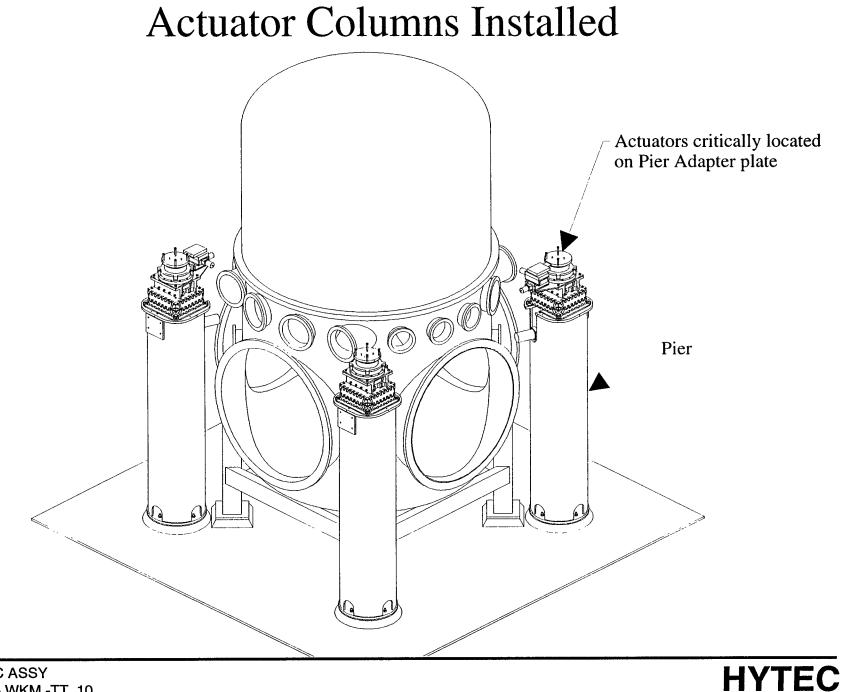
Translating the Pier Adapter Plate



Guide Brackets restrict Adapter Plate to linear motion only

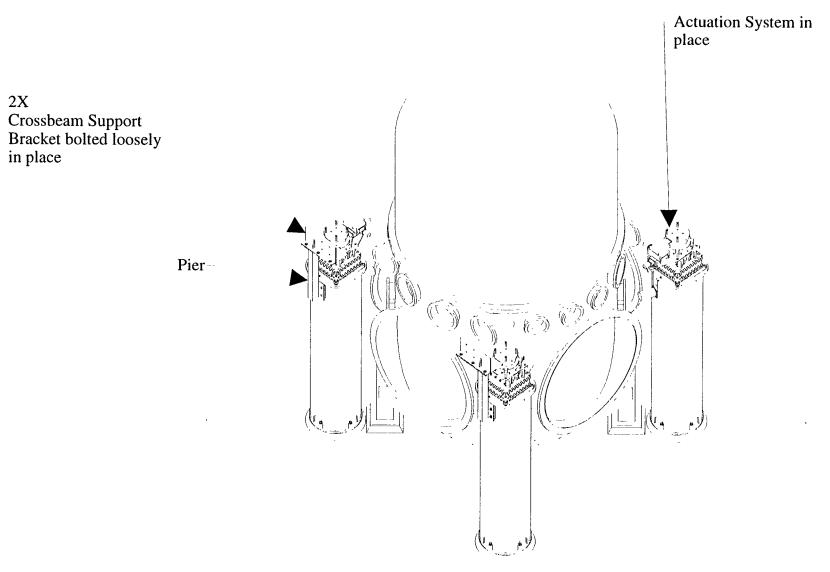
> -Linkage Bracket #1 moved to this position for linear motion

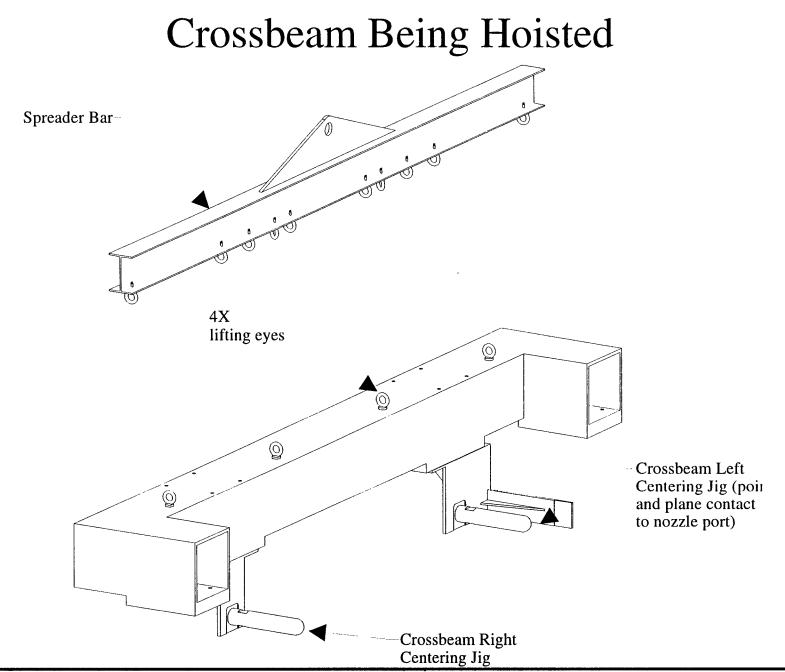
Guide Brackets are moved to new positions to provide transverse motion



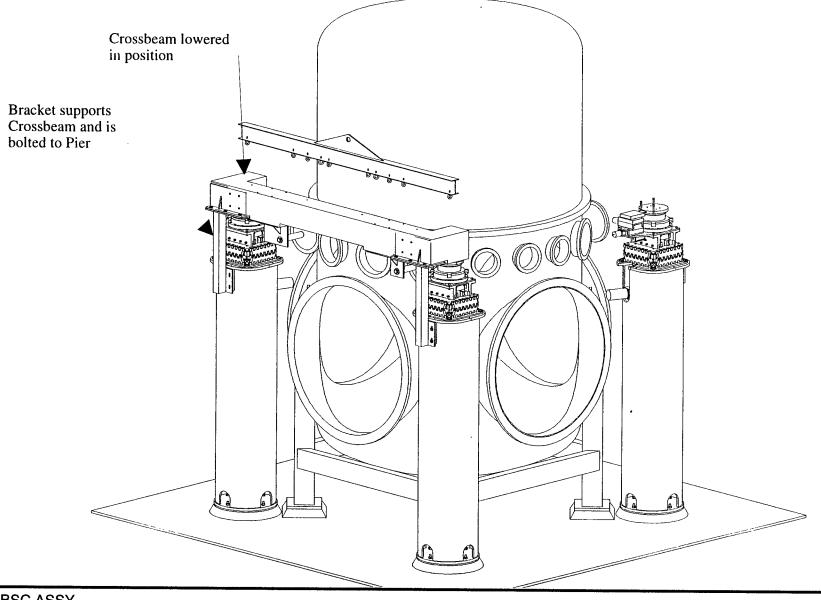
LIGO BSC ASSY 09/23/97 - WKM -TT 10

Crossbeam Support Brackets in Place

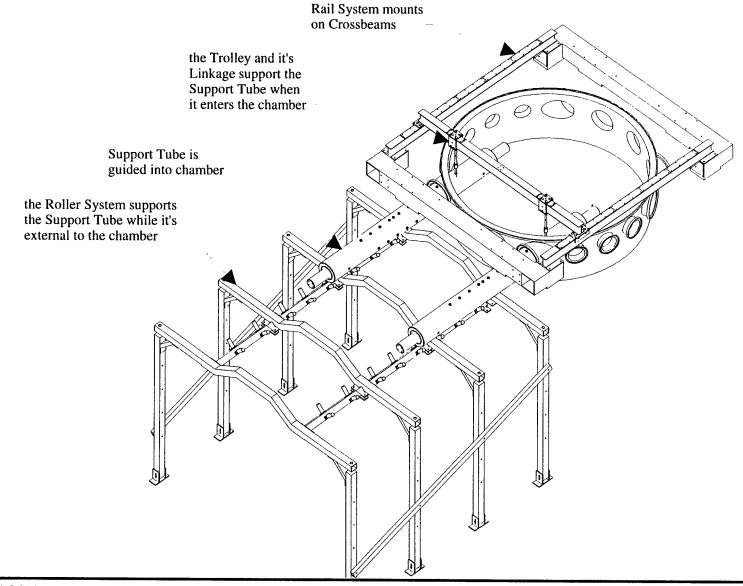




Crossbeam Lowered Into Position

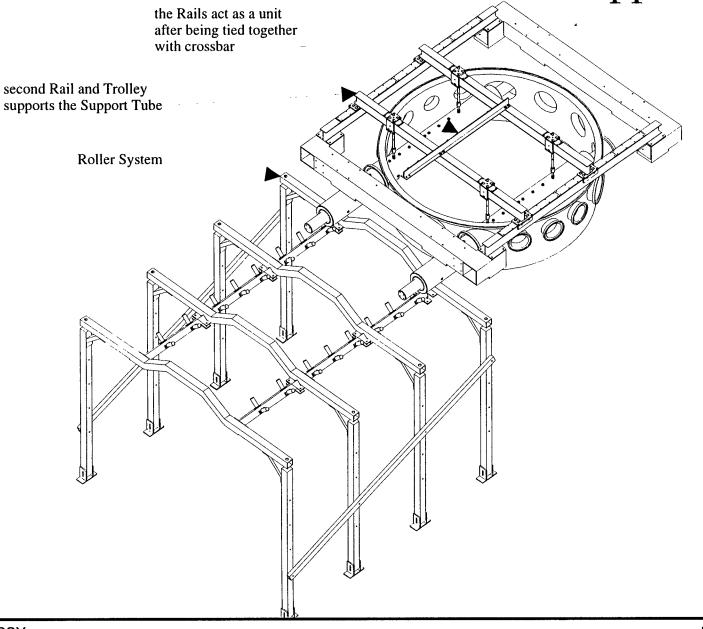


Transverse Rail #1 Connected to the Support Tubes

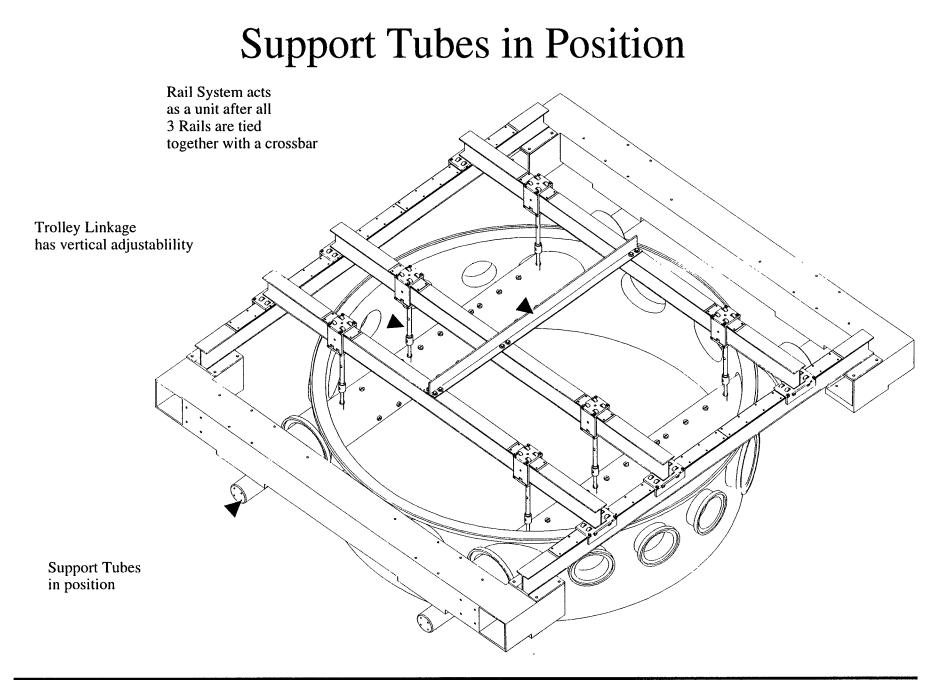


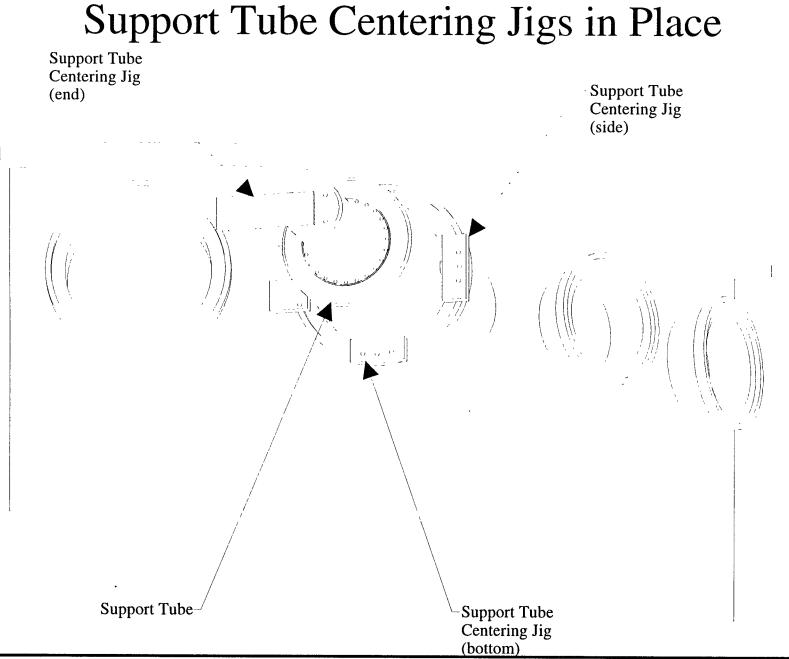
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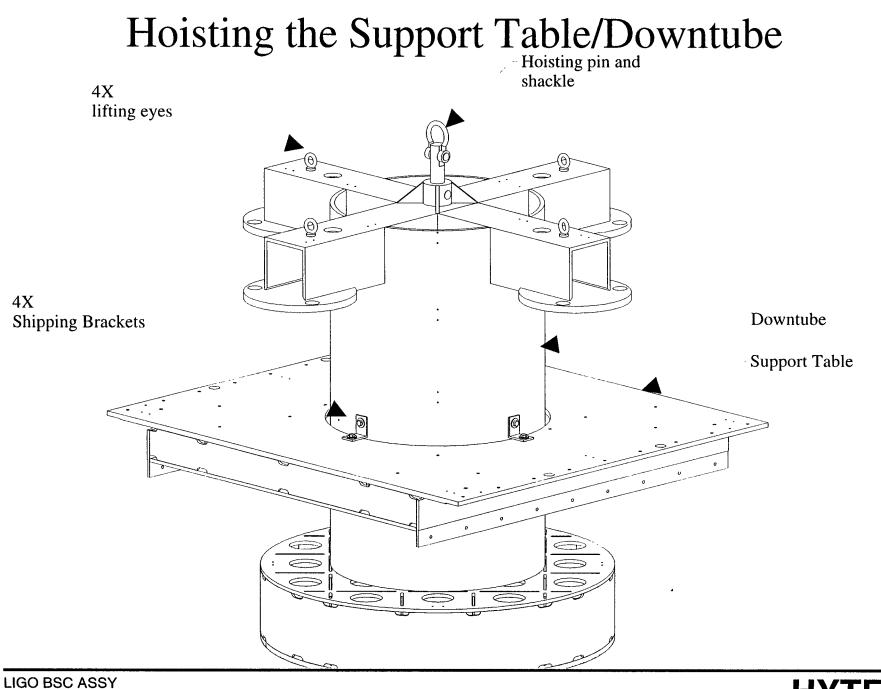
Transverse Rail #2 Connected to the Support Tubes



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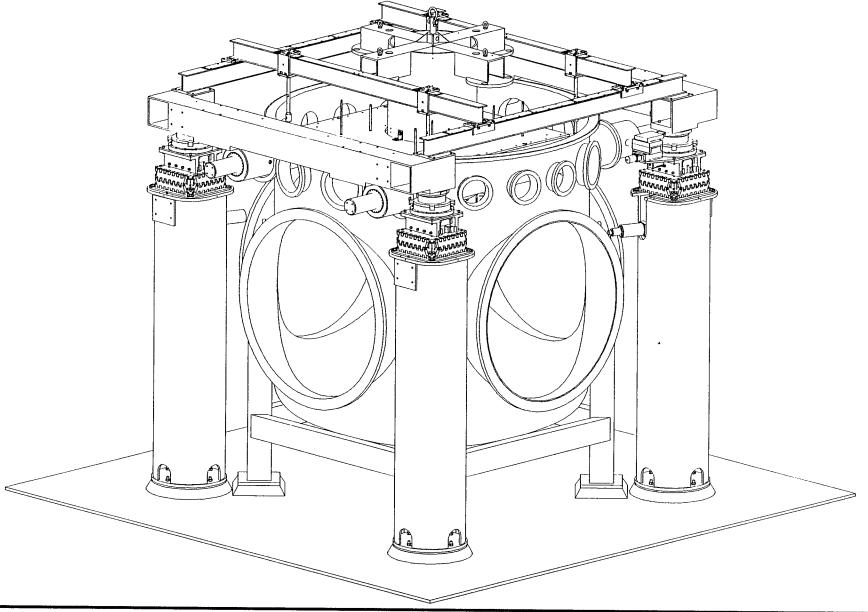


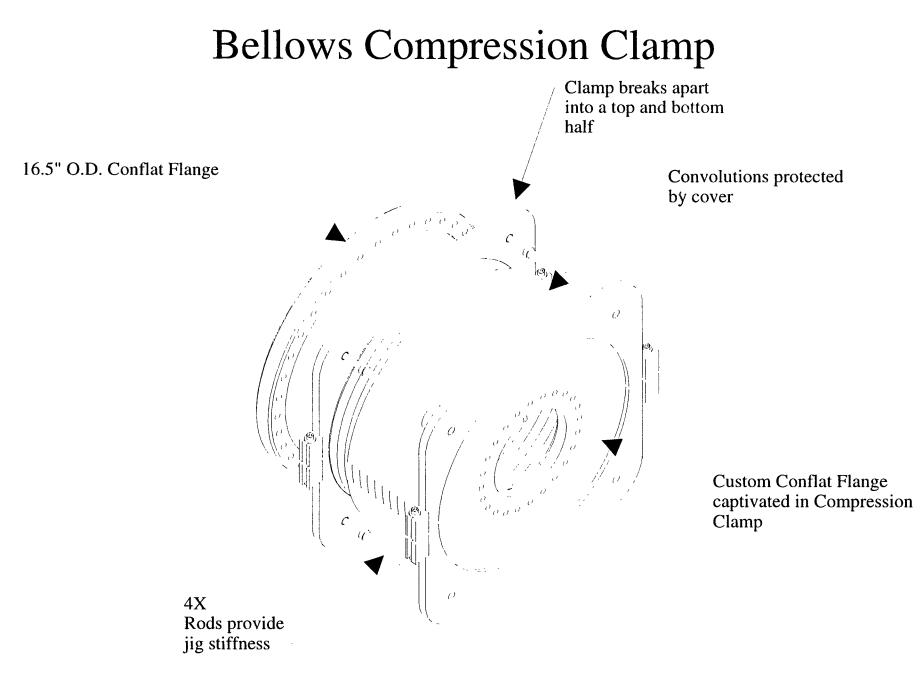




09/23/97 - WKM -TT 18

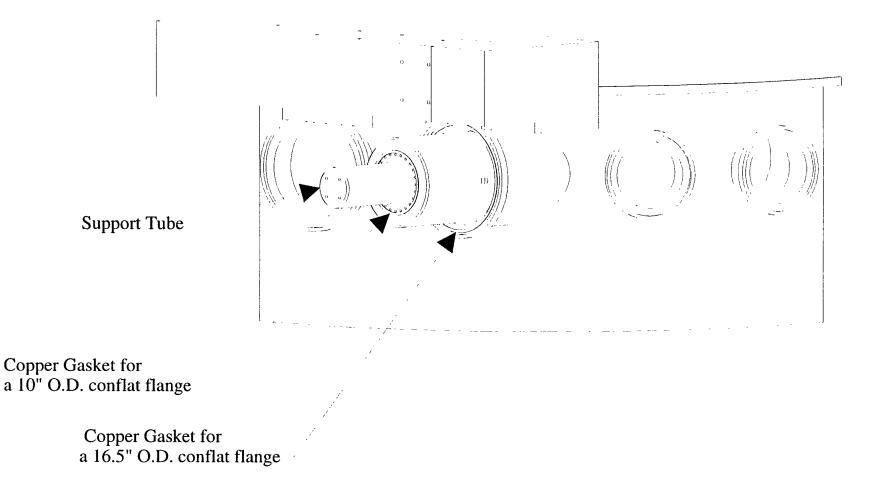
Support Table Bolted to the Support Tubes





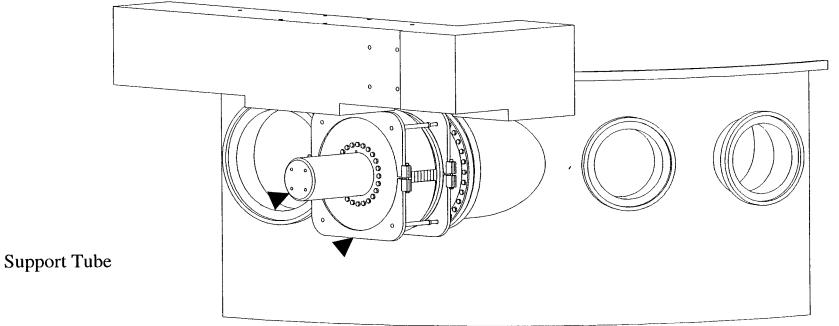
LIGO BSC ASSY 09/23/97 - WKM -TT 20

Copper Gaskets Placed in Position



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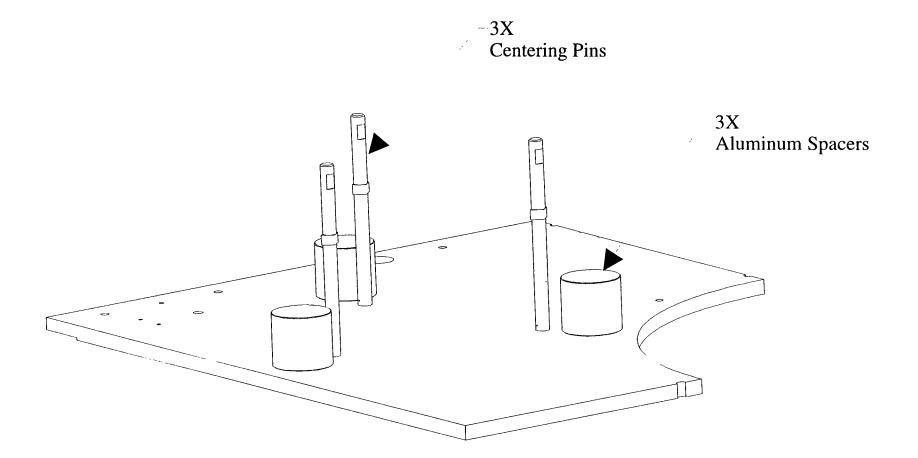
Bellows Being Installed



Bellows Compression Clamp



Preparation for Leg Element #1



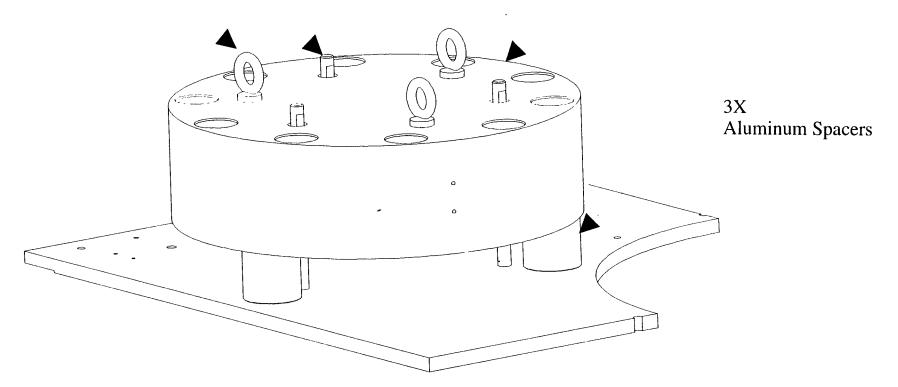


Leg Element #1 Lowered in Position

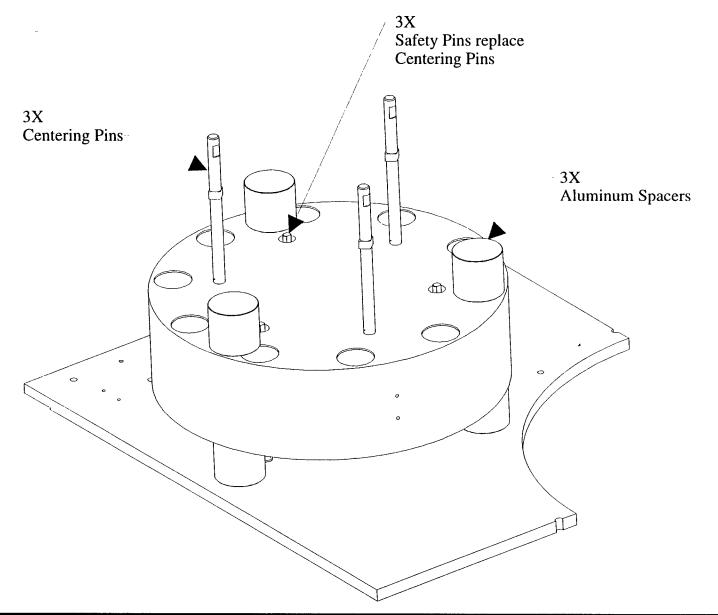
3X Centering Pins

> 3X Lifting Eye

Leg Element #1



Preparation for Leg Element #2

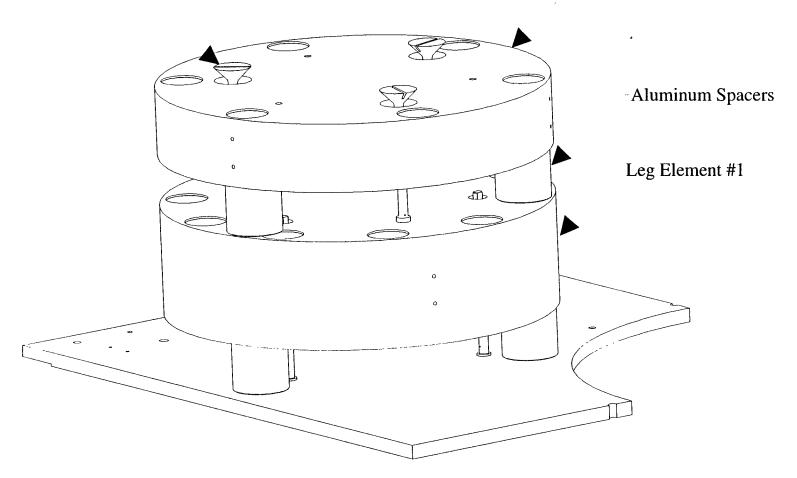


LIGO BSC ASSY 09/23/97 - WKM -TT 25

Leg Element #2 in Position with Safety Pins

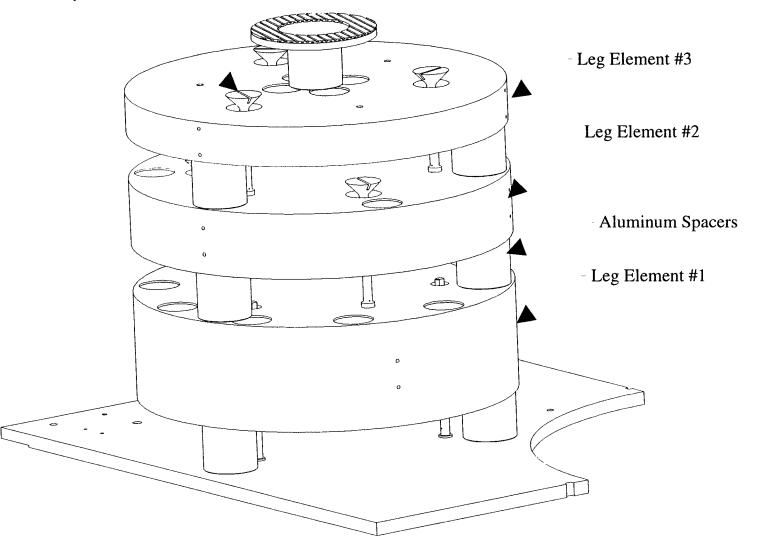
3X Safety Pins

Leg Element #2

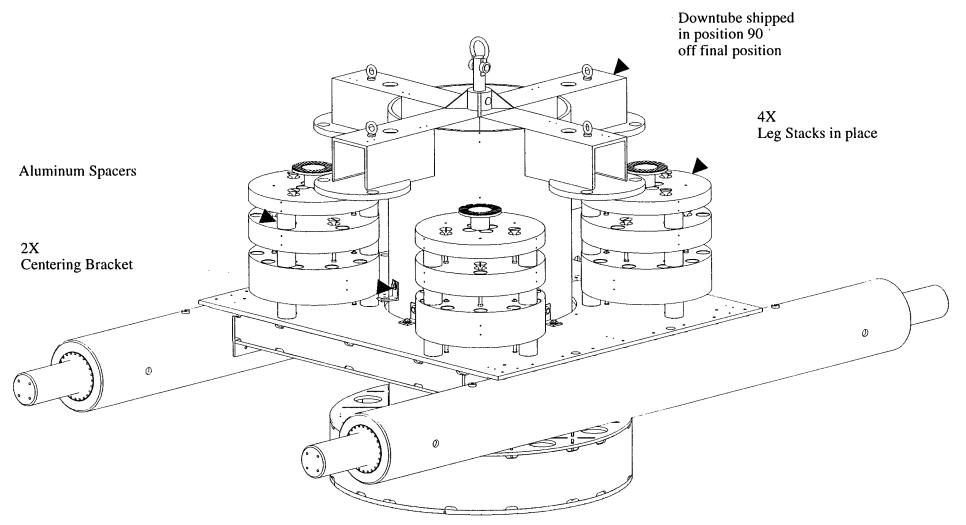


Isolation Stack Leg Assembled

Safety Pins

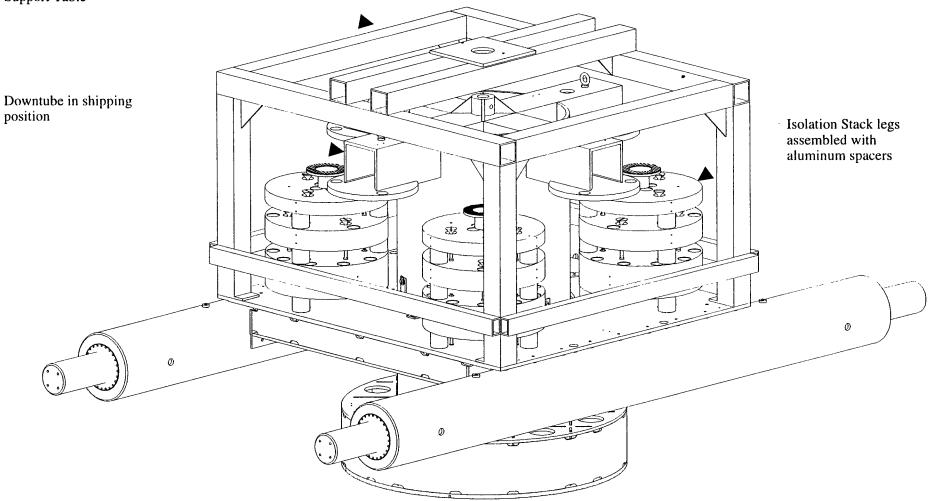


BSC Isolation Stack Assembled



Downtube Centering Structure Lowered in Place

Downtube Centering Structure legs register on temporary pins put into Support Table

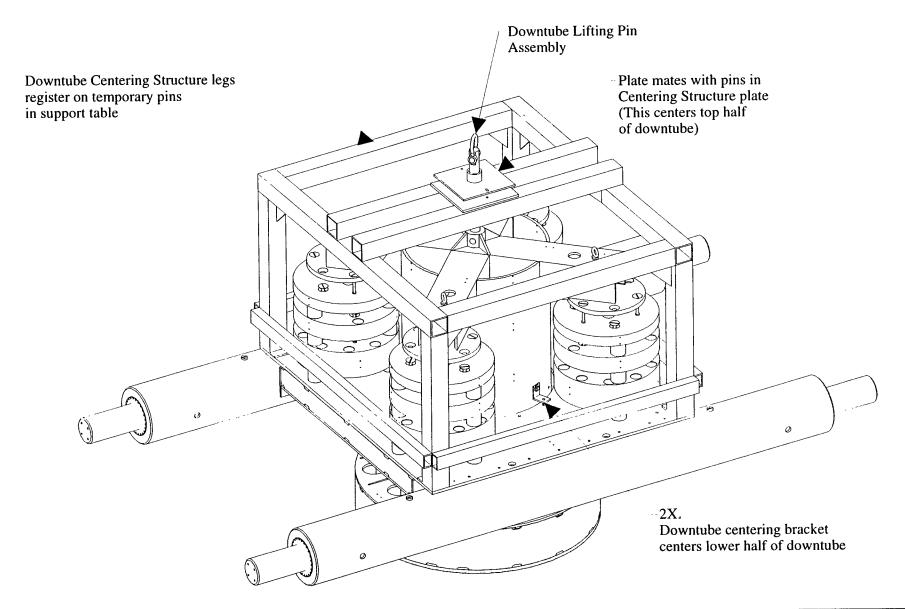




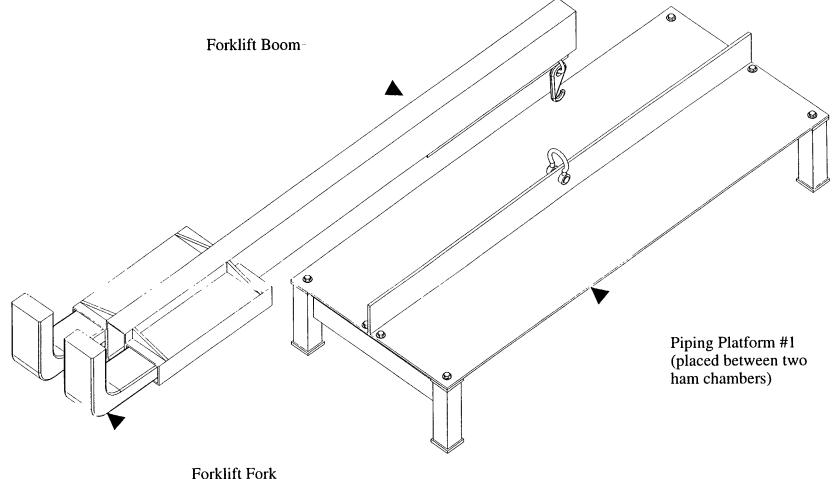
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Downtube Rotated 45 Degrees for Spring Assembly



Piping Platform Being Hoisted

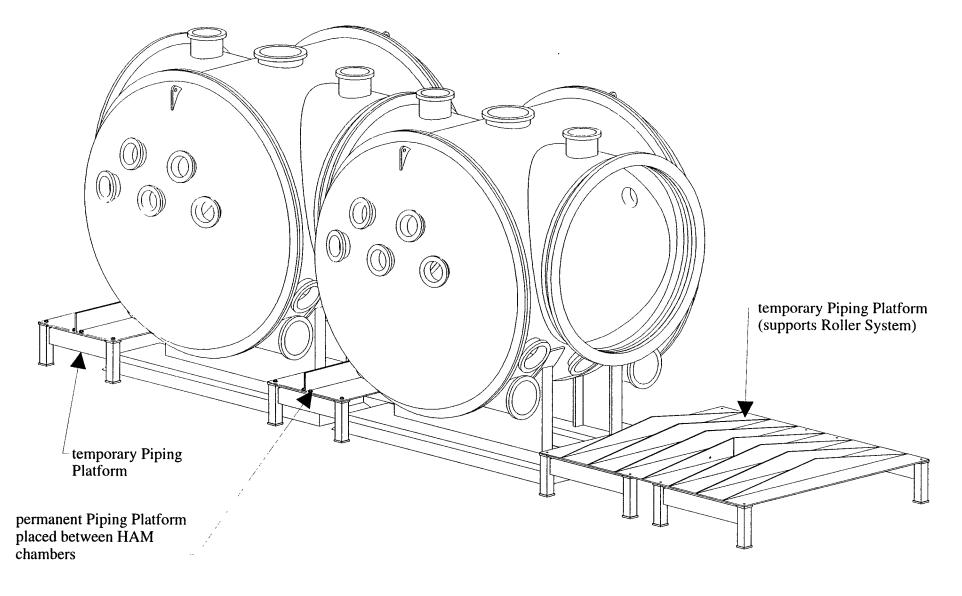


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Piping Platforms Located in Position for Two Chambers



LIGO HAM ASSY 09/23/97 - WKM -TT 2

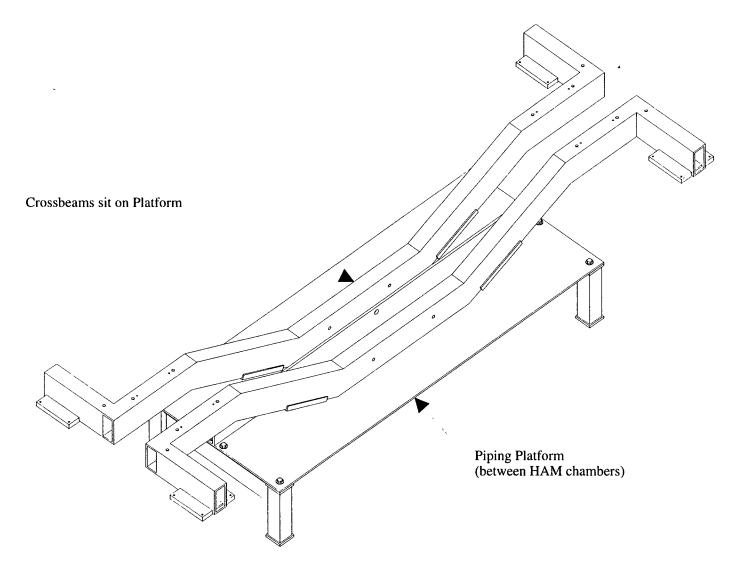


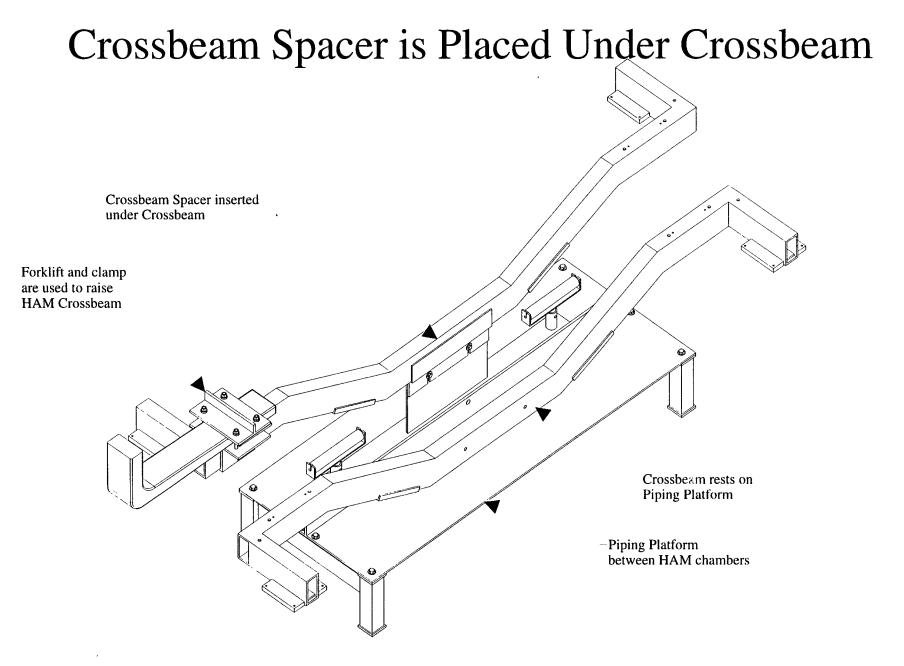
HAM Crossbeam -Crossbeam Lifting Clamp

-Forklift fork

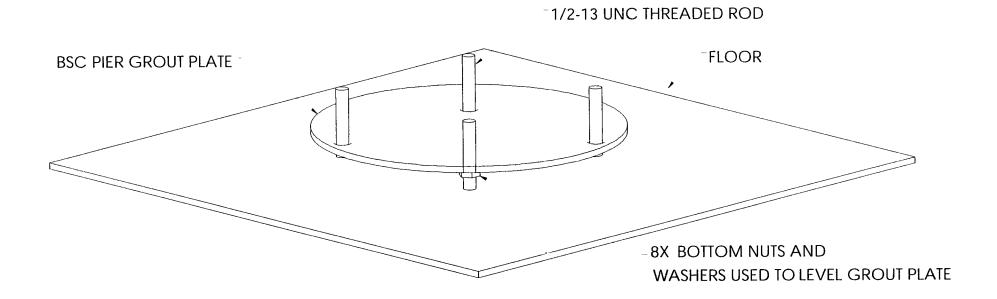
LIGO HAM ASSY 09/23/97 - WKM -TT 3

Two HAM Crossbeams on a Piping Platform

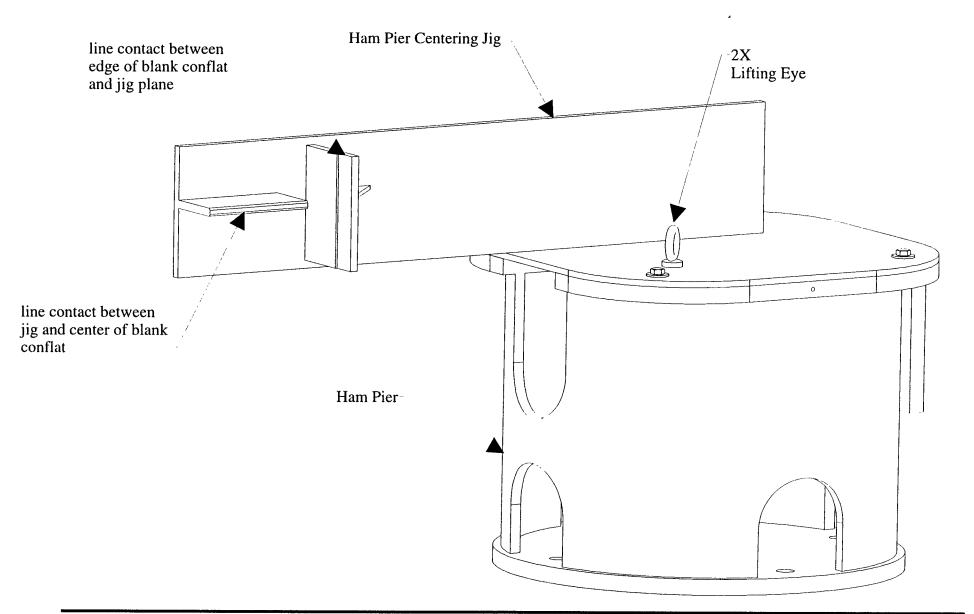




Pier Grout Plate Installation

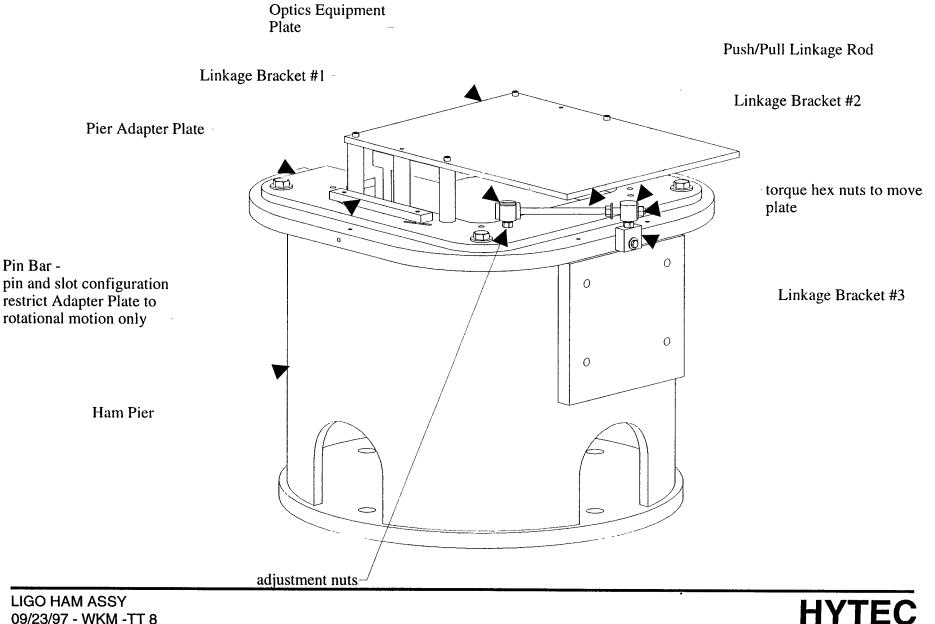


HAM Pier with Centering Jig



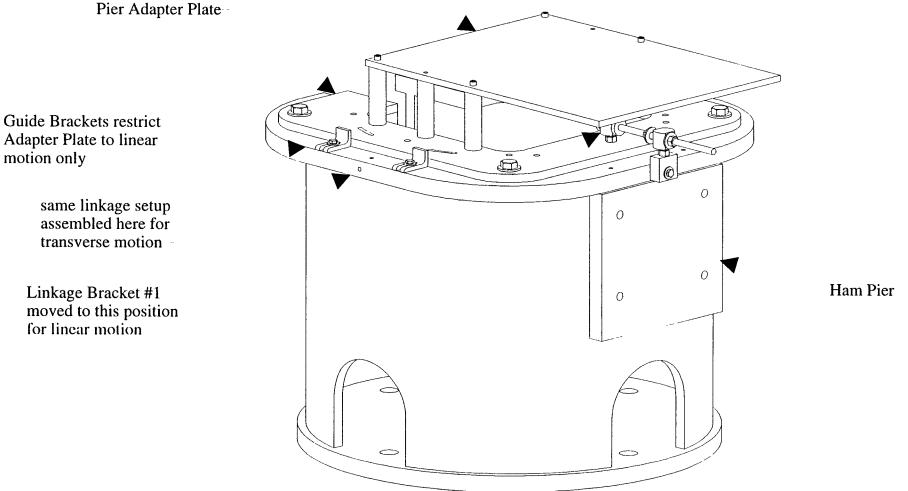


Leveling and Clocking Pier Adapter Plate



Translating Pier Adapter Plate

Optics Equipment Plate remains bolted in position -

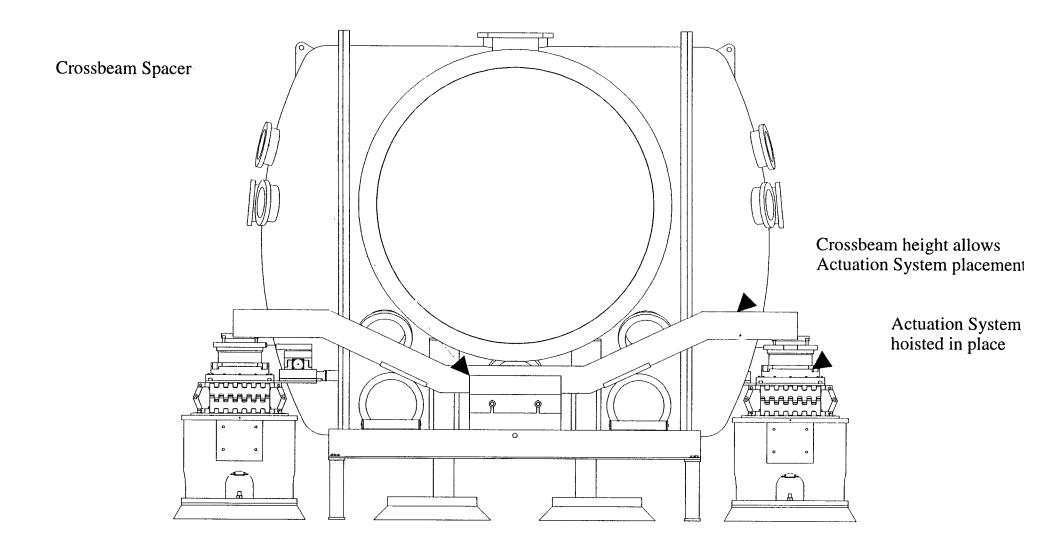


motion only

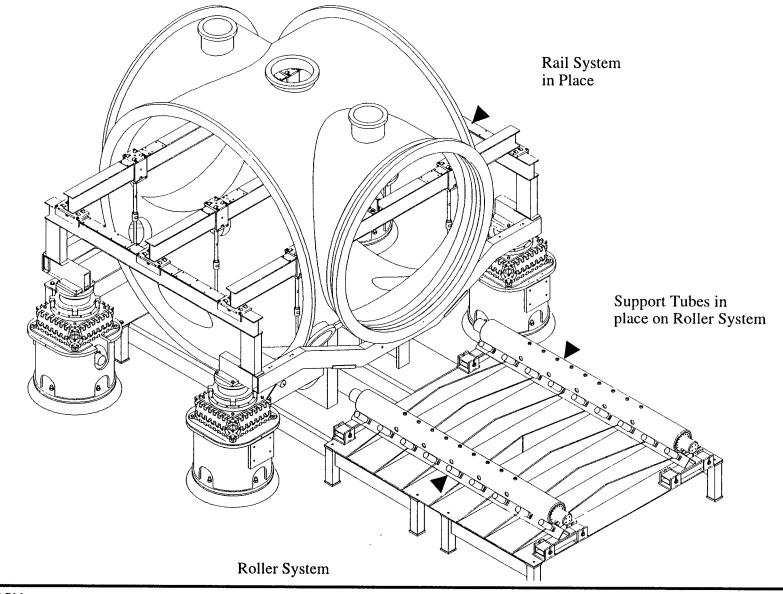
transverse motion -

Linkage Bracket #1 moved to this position for linear motion

Actuator Columns Installed

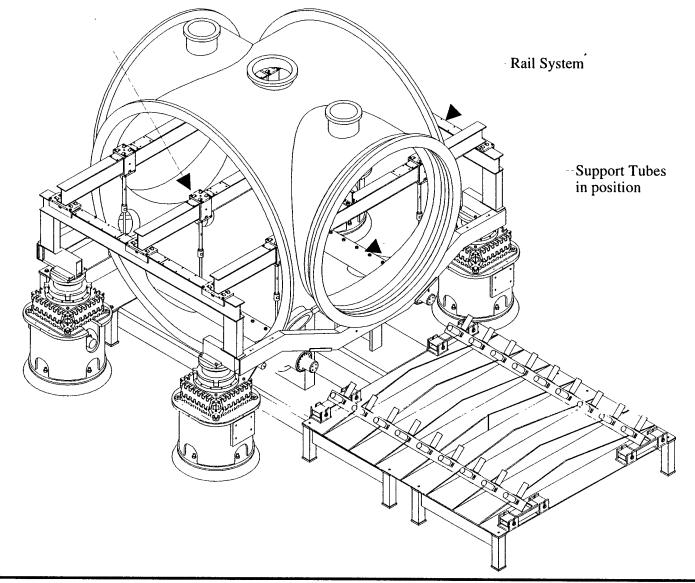


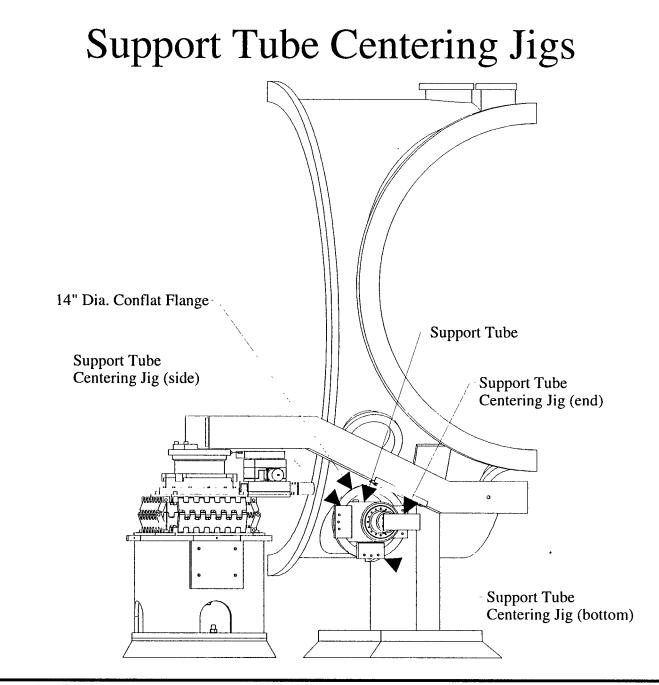
Support Tubes in Roller System



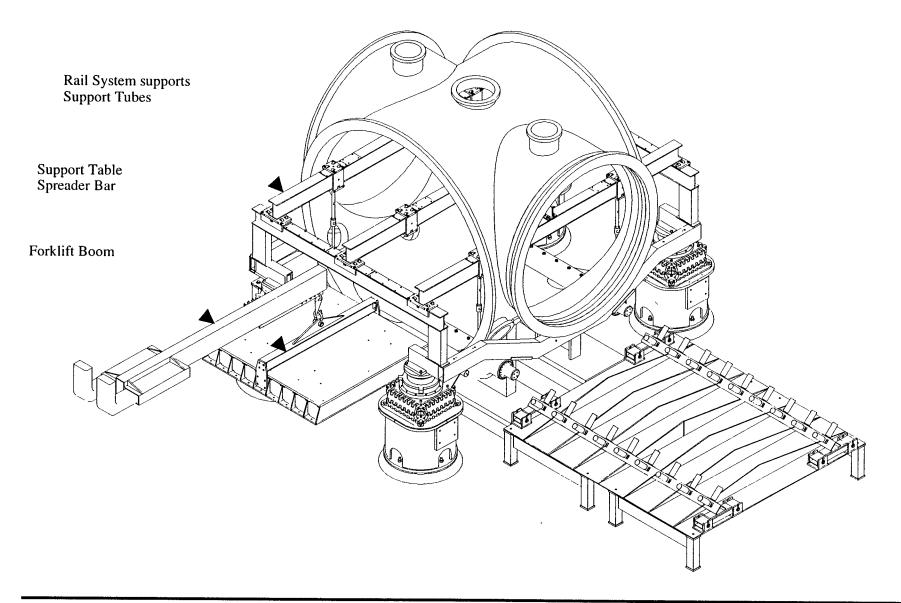


Support Tubes in Position





Hoisting the Support Table



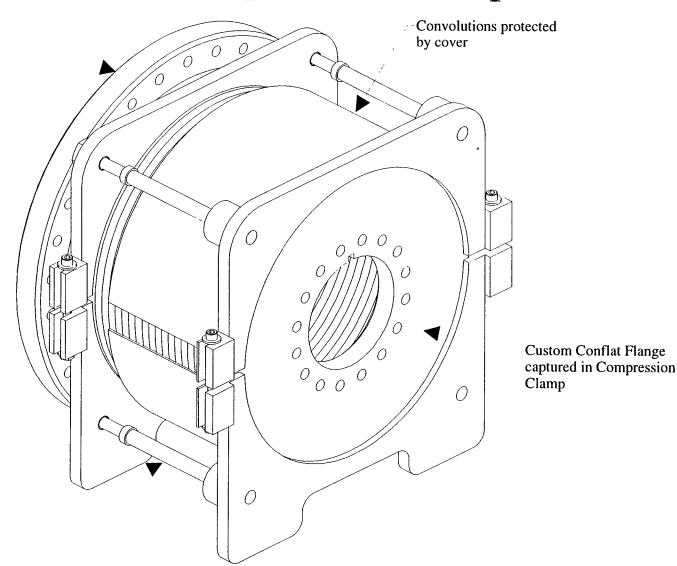
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Bellows Compression Clamp

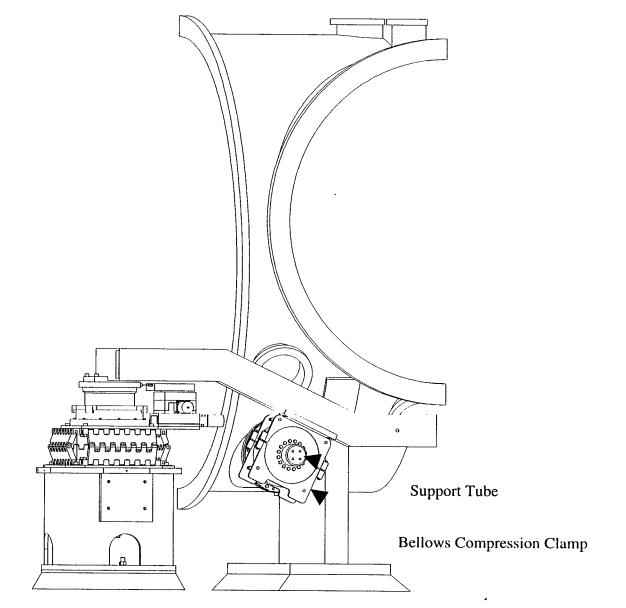
14.0" O.D. Conflat Flange --

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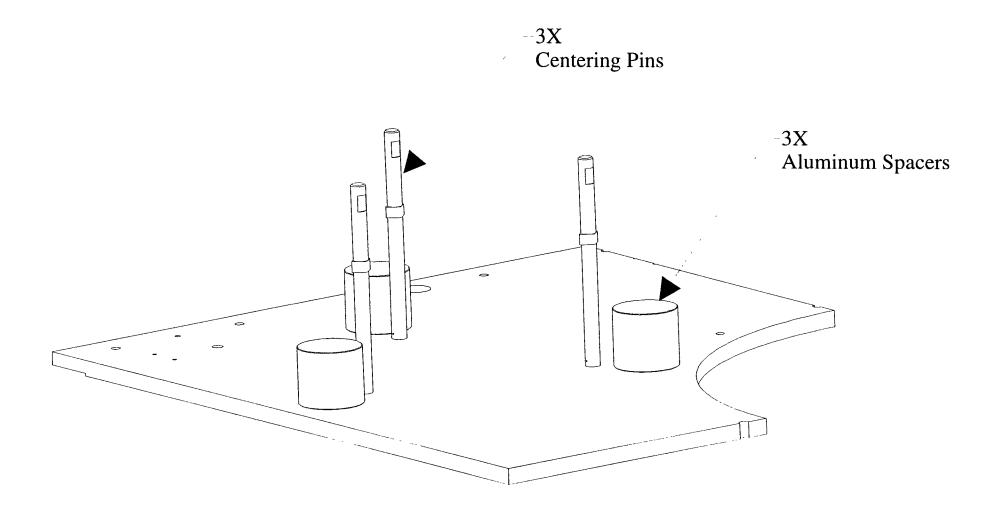
4X Rods provide jig stiffness and are used to compress bellows

Bellows Being Installed

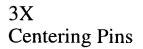


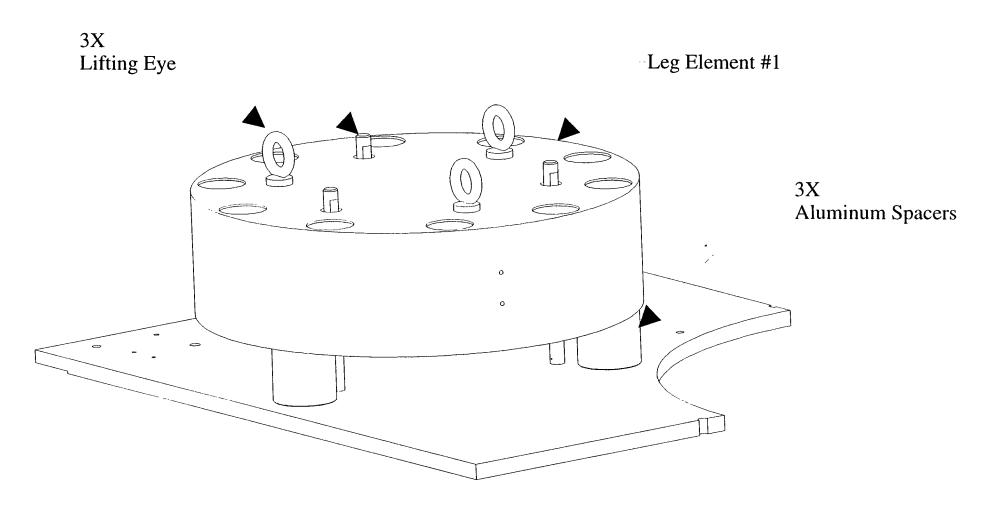
LIGO HAM ASSY 09/23/97 - WKM -TT 16

Preparation for Leg Element #1

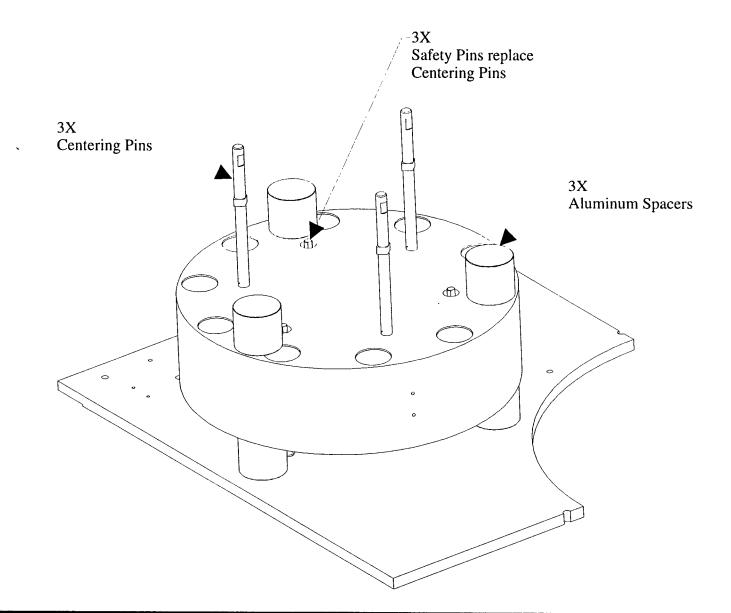


Leg Element #1 Lowered Into Position





Preparation for Leg Element #2

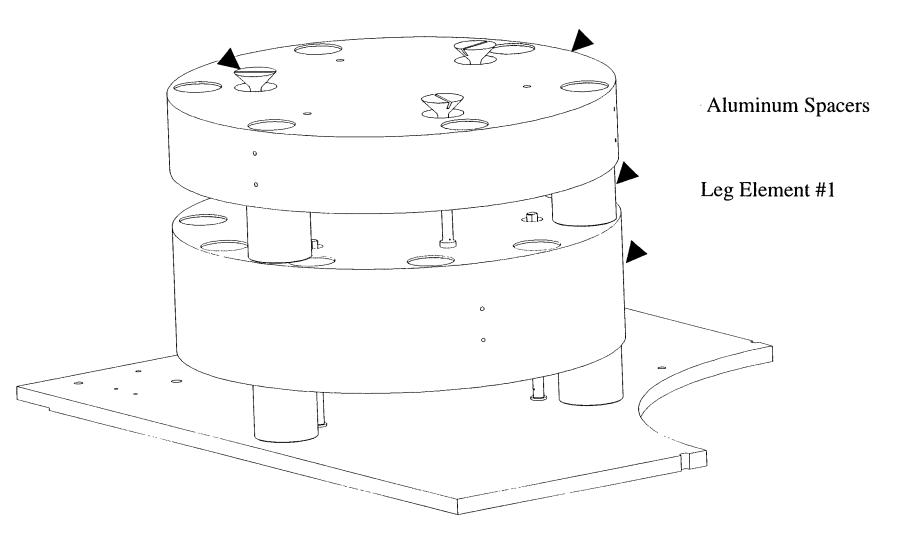




Leg Element #2 in Position with Safety Pins

3X Safety Pins

Leg Element #2



Stack Assembly Complete

Safety Pins

