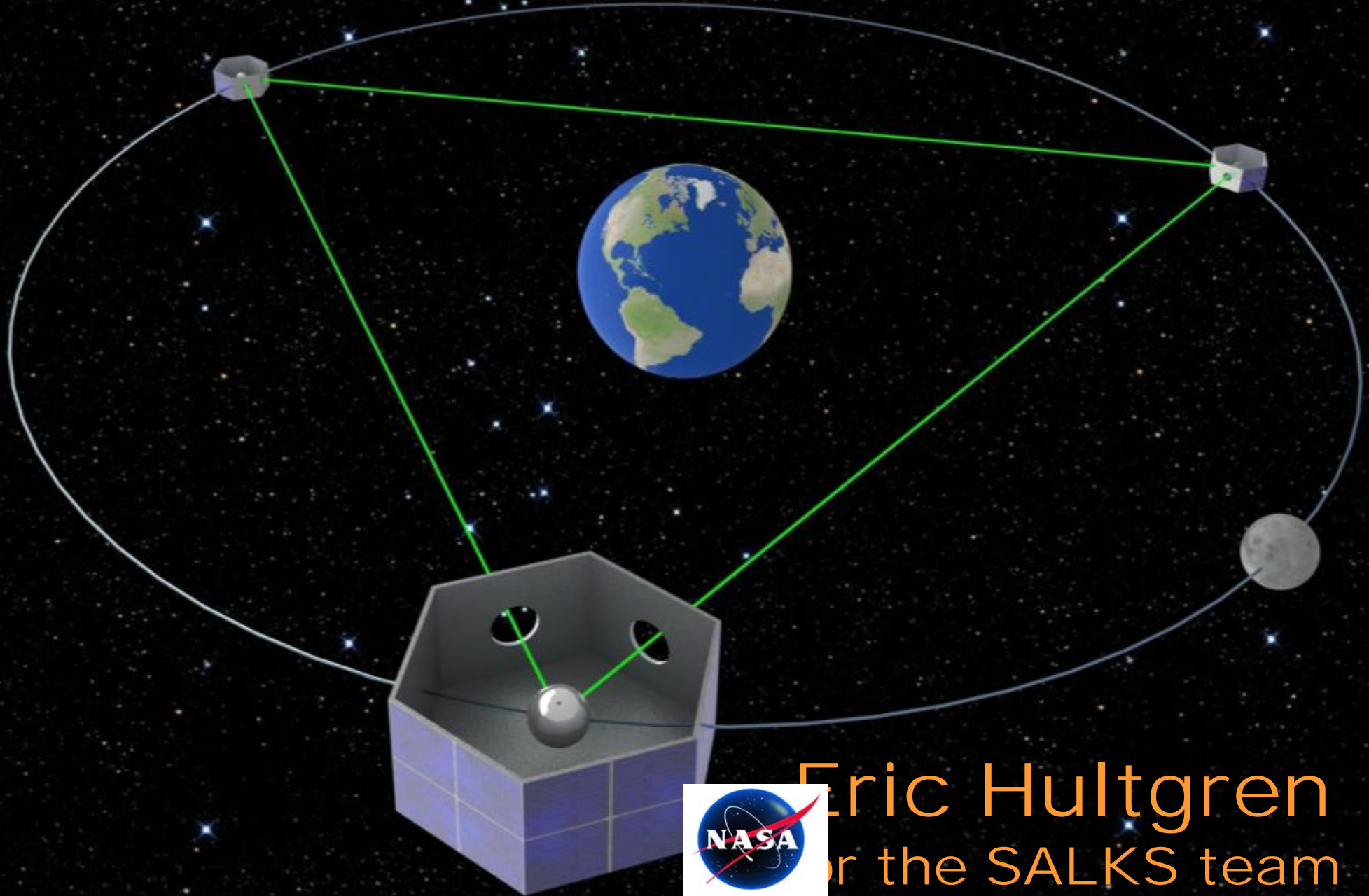


# LAser GRavitational-wave ANtenna in GEocentric Orbit



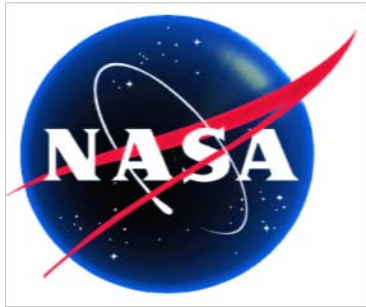
Eric Hultgren  
for the SALKS team

## Background

- **LASer GRAvitational-wave ANTenna in GEOcentric Orbit was proposed originally as a response to NASA's Request for Information (RFI) titled "Concepts for the NASA Gravitational Wave Mission" NNH11ZDA019L**
  - One of 17 submissions
  - One of two called "LAGRANGE"
- **Reference:**
  - Conklin, et. al. "LAGRANGE: LASer GRAvitational-wave Antenna at GEO-lunar Lagrange points" arXiv:1111.5264v2 [astro-ph.IM] 5 Dec 2011



# The SALKS Collaboration

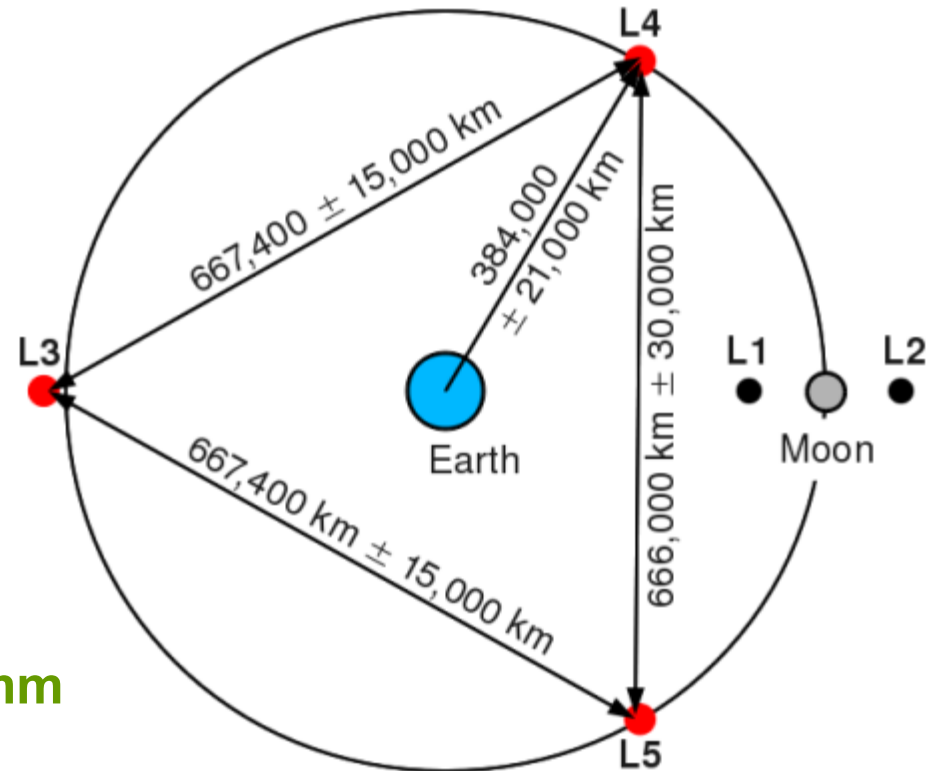


Stanford	NASA ARC	Lockheed Martin	KACST of Saudi Arabia	SRI International
science payload lead (GRS / IMS)	science orbit, orb. injection, prop. mod.	telescope, spacecraft	science payload, tech development	$\mu$ N thrusters



# Design Overview

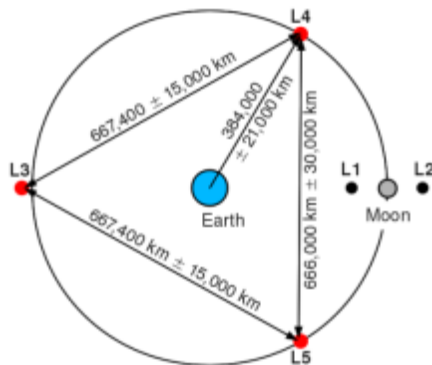
- **3 identical drag-free spacecraft & payloads**
- **Communications & cost drives decision for geocentric orbit**
- **Minimum complexity**
  - 1 spherical TM per S/C
  - 1 laser (+1 spare) & bench per S/C
  - 2 telescopes, in-field pointing
  - 7 DoF control per spacecraft
    - Translation
    - Rotation
    - Breathing angle
- **Continuous, simultaneous, fast comm**
  - Fixed antennas on each S/C
  - Mbps through NASA GN (11 m class), ~1 hour data latency
- **5 year mission lifetime**





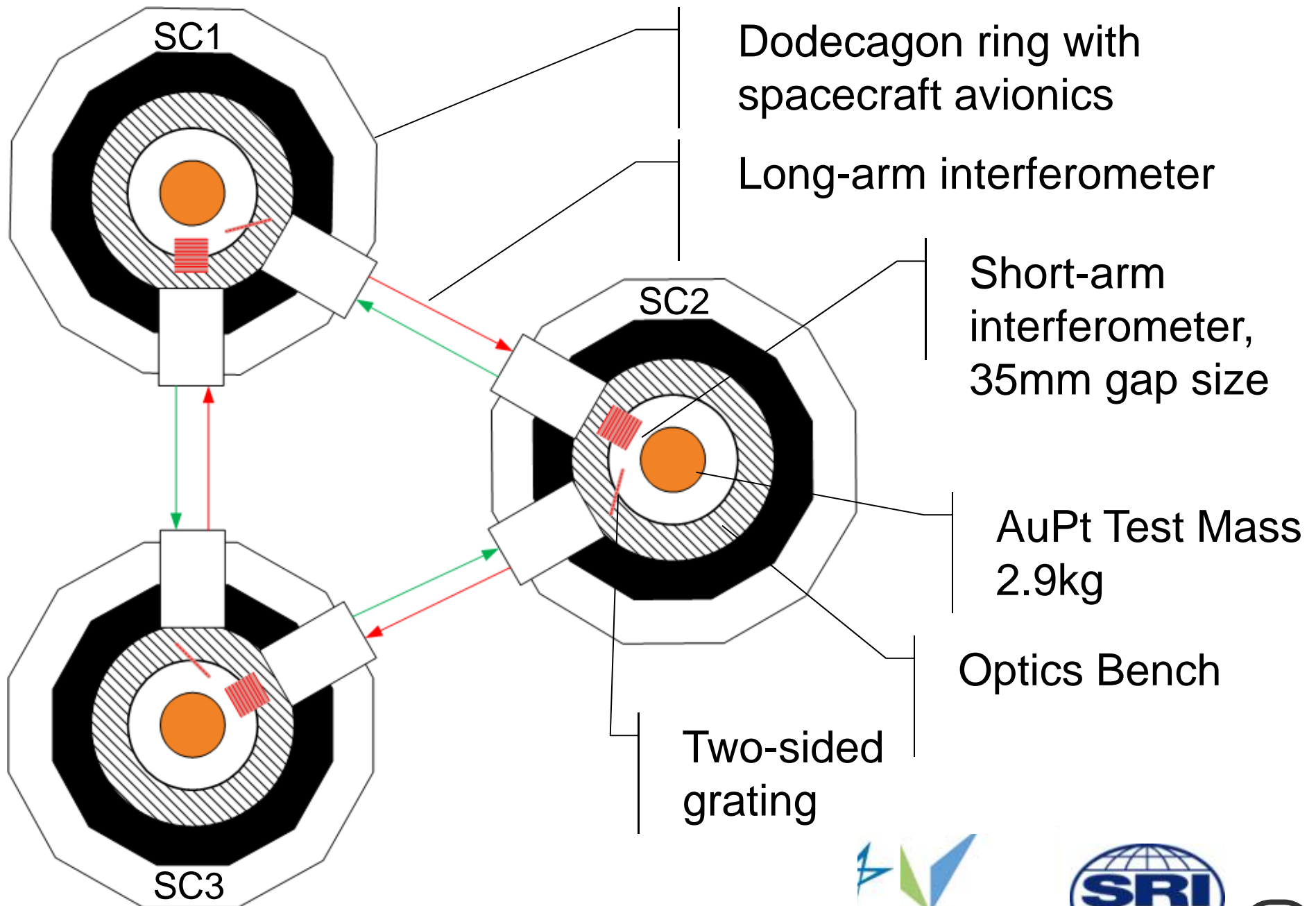
# Orbit Selection

- **~ 3 stable, near-Earth orbits considered**
  1. High retrograde: ~600,000 km from Earth (Hellings, OMEGA 1998)
  2. Earth-moon L3, L4, L5: 384,000 km from Earth
  3. Earth-Sun L2 circular Halo: ~1.5 Mkm from Earth (must be checked)
- **EM L3, L4, L5 chosen for detailed study, because:**
  - Closest to Earth
  - Minimum cruise time
    - Launch to Weak Stability Boundary: 4 months with  $\Delta v = 580$  m/sec
    - Launch to Trans-Lunar Injection: 7 months with  $\Delta v = 475$  m/sec



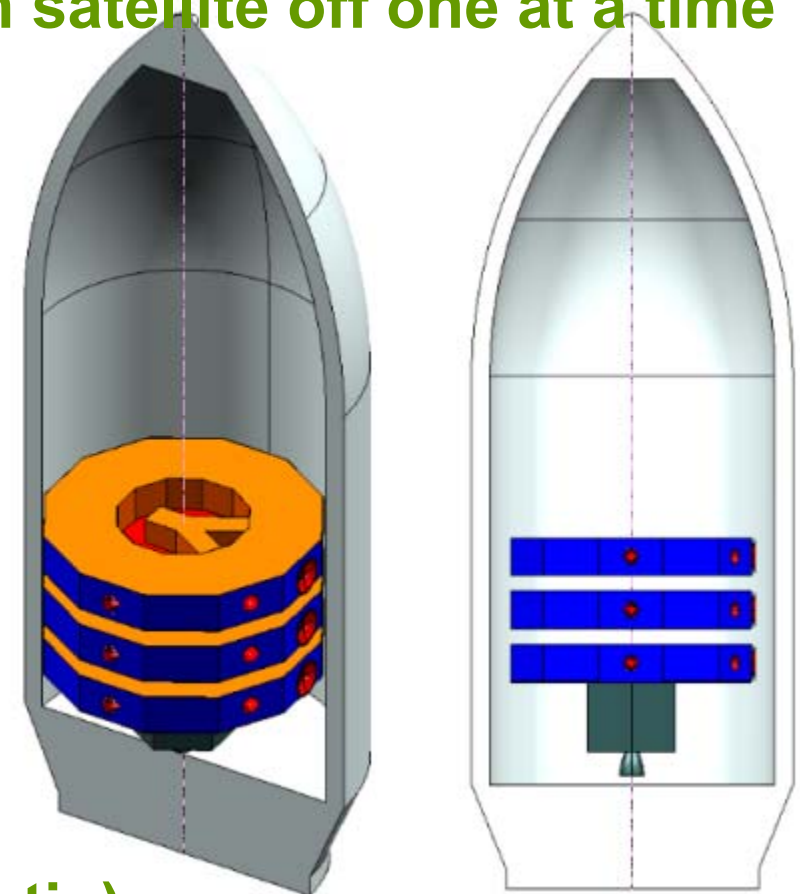
	EM L3,L4,L5	LISA
Arm length	670 000 km	5 000 000 km
$\Delta$ arm length	$\leq 5\%$	1%
Breathing angle	$\leq \pm 5$ deg	$\pm 0.5$ deg
Range rate	$\leq 150$ m/sec	10 m/sec
$\Delta$ orbit plane	5 deg	60 deg

# System Overview



# Spacecraft & Mission Design

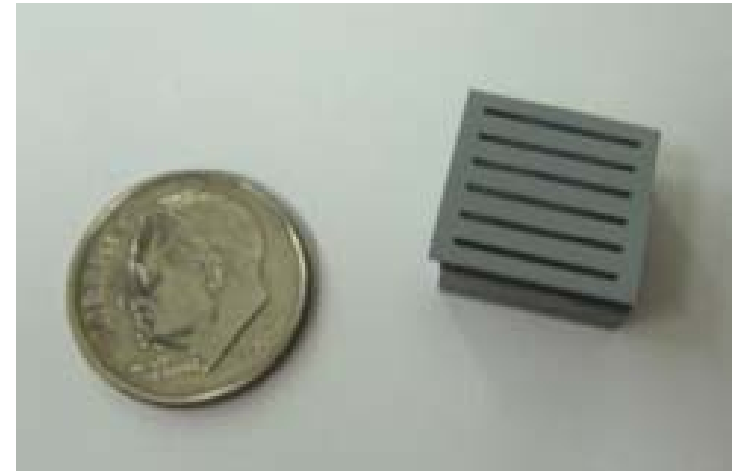
- **S/C based on existing LM S/C, TRL >6**
  - ~3 m × 0.7 m, 300 kg, 500 W
- **Single propulsion module drops each satellite off one at a time**
- **Thermal design: GRS 10  $\mu$ K at 1 mHz**
  - $\pm 50$  K at exterior at 27.3 period
  - Thermal load radiated top/bottom
  - Payload at center
- **Launch mass: 2,070 kg**
- **4-7 month cruise**
- **5 year lifetime**
- **ROM cost \$950M FY12 (Lockheed Martin)**



- **Includes 30% reserve**

# Spacecraft Propulsion

- **Initial conditions maximize time each S/C remains at L-point**
  - Station keeping every 6-12 months (L3)
  - Station keeping capability recommended for any orbit
- **Drag-free & attitude via  $\mu\text{N}$  ion thrusters**
- **NGO evaluating alternates to FEEPs**
- **SRI micro-fabricated ion thruster attractive alternate to Busek CMNT or Italian/Austrian FEEPs**
  - Micro-fabricated emission sites produce ions & electrons
  - “Digital propulsion”: 100’s – 1,000’s of independent emitters /  $\text{cm}^2$ 
    - Single unit can produce forces + torques
  - Huge dynamic range: ion production physics unchanged over  $10^{-9}$  to 1 N
  - Up to 10,000 sec Isp
  - Prototype: 1 nN to 5  $\mu\text{N}$  thruster ion source tested to 40 hr of operation
  - Can be demonstrated on a 1U CubeSat

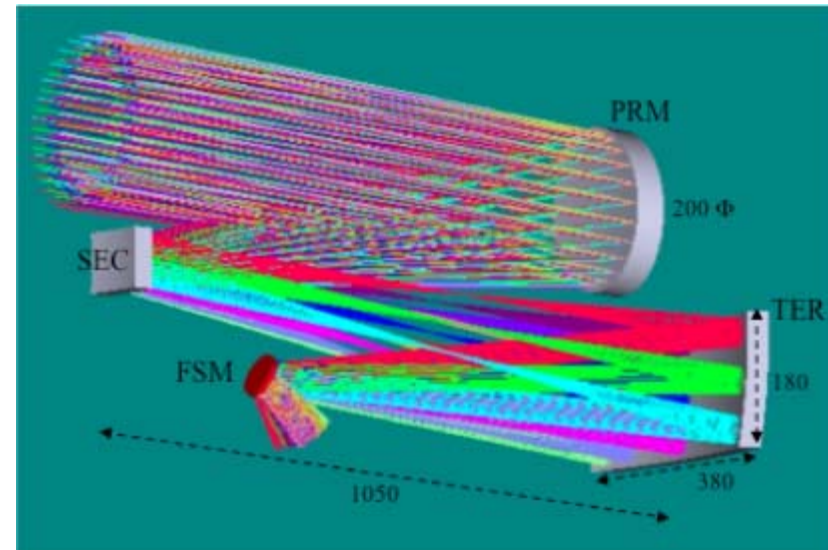




# Telescope Design

- **Two-stage design required for**
  - 5 degree Field or Regard due to constellation geometry changes
  - 1mm beam size on optical bench
- **20 cm aperture**
- **$\pm 2.5$  deg beam steering**
- **5 pm path-length stability**
- **Low CTE composite metering structure**
- **Stage one is 6:1 3-mirror Anastigmat (TMA)**
  - Leads to  $\pm 15$  deg steering mirror near exit pupil
- **mK temperature control**

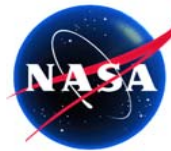
## Stage One Design: TMA



Stage Two gives additional 33x magnification

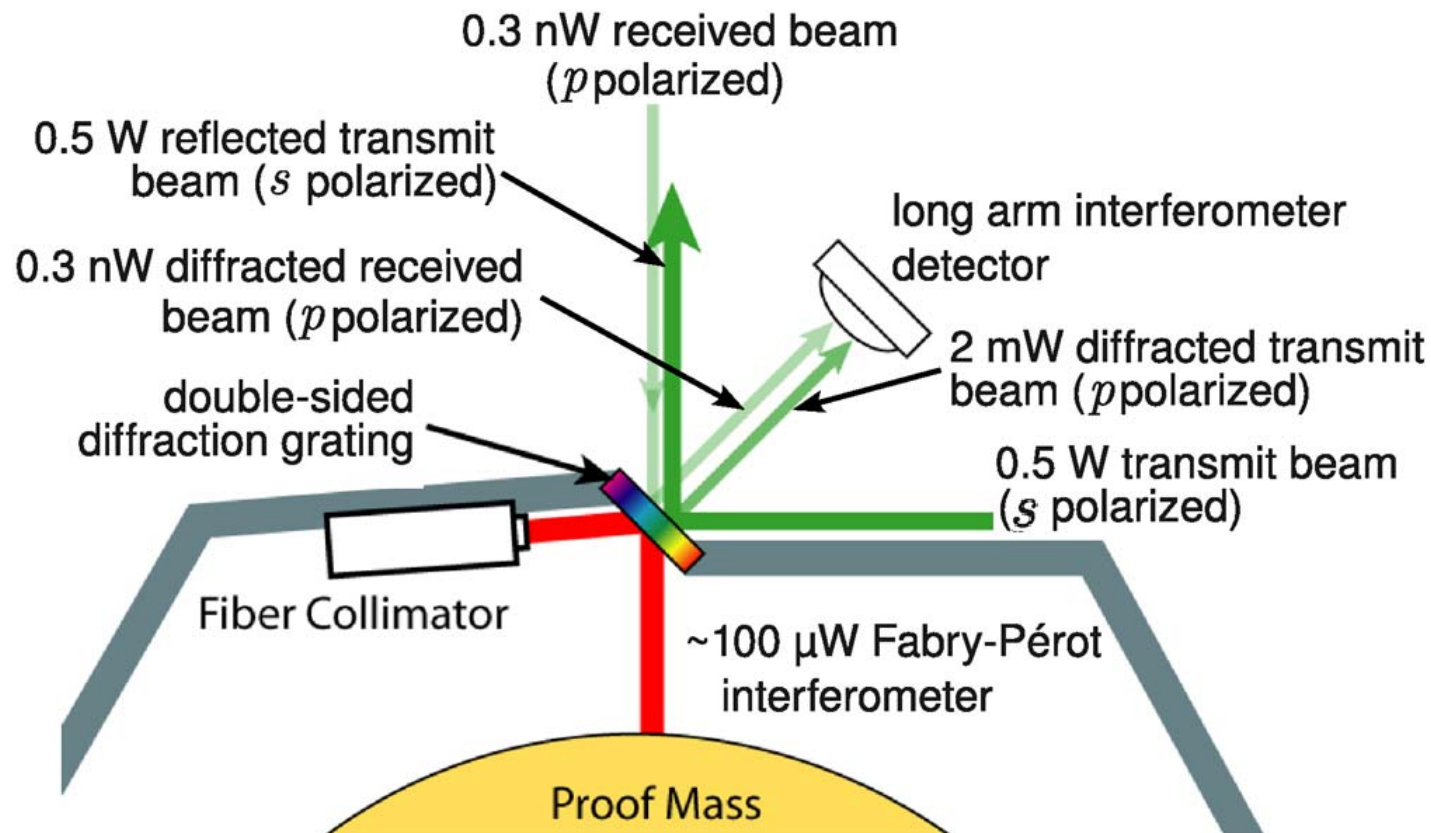
# *Interferometric Measurement System*

- **IMS follows LISA scheme with some differences**
- **1 W Nd:YAG NPRO (1064 nm), split to feed both arms**
- **Split interferometry: long-arm / short-arm interferometers**
  - **Short-arm (TM to optics bench): grating Fabry-Pérot cavity**
  - **Long-arm (optics bench to remote optics bench): local & received laser phase difference (PBS or diffraction grating)**
- **Laser pre-stabilization by optical cavity or iodine cell**
- **150 MHz Doppler frequency**
  - **Use modified LISA phasemeter**
- **6  $\mu$ rad point-ahead angle: LISA Point Ahead Angle Mirror (PAAM) by TNO (TRL 4)**



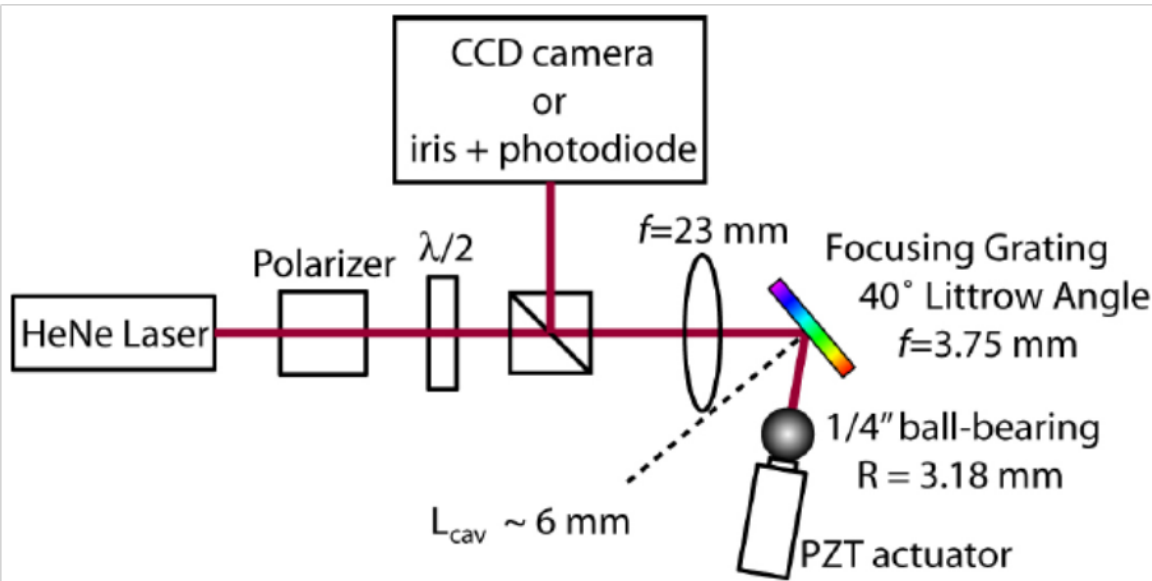
# Interferometry with a Diffraction Grating

- **Double sided diffraction grating on low CTE material**
  - Small, ~ mm relay region between long & short arm interferometers
  - $CTE < dn/dT$
  - Fewer components compared to LISA → smaller optics bench
- **Sensitivity to grating motion: 1  $\mu$ cycle/pm**

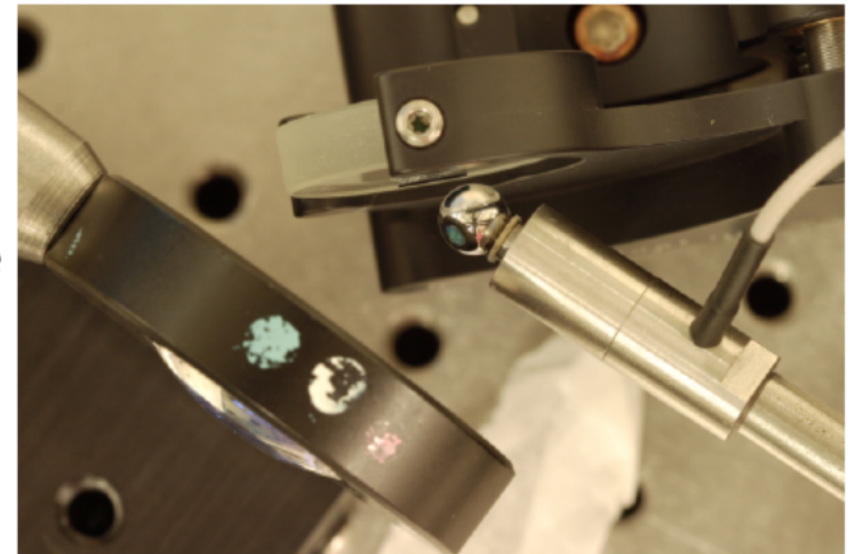


# Grating-Sphere Cavity

- **Mode matching and stable low finesse cavity demonstrated**



(a) Layout of the spherical grating cavity



(b) Picture of the cavity

Figure A.1: Schematic and photograph of focusing grating cavity used to demonstrate successful mode-matching using a spherical end-mirror.



# *Advantages of a Spherical GRS*

## 1. **No TM forcing or torquing**

- Neither electrostatic support nor capacitive sensing required, reducing disturbances & complexity

## 2. **Optical readout enables large gap (35 mm)**

- Disturbances reduced and/or spacecraft requirements relaxed

## 3. **A long flight heritage**

- Honeywell gyros, Triad I ( $5 \times 10^{-11}$  m/sec<sup>2</sup>), GP-B ( $4 \times 10^{-11}$  m/sec<sup>2</sup> Hz<sup>1/2</sup>)

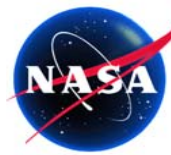
## 4. **Scalability**

- Performance can be scaled up or down by adjusting TM and gap size

## 5. **Simplicity**

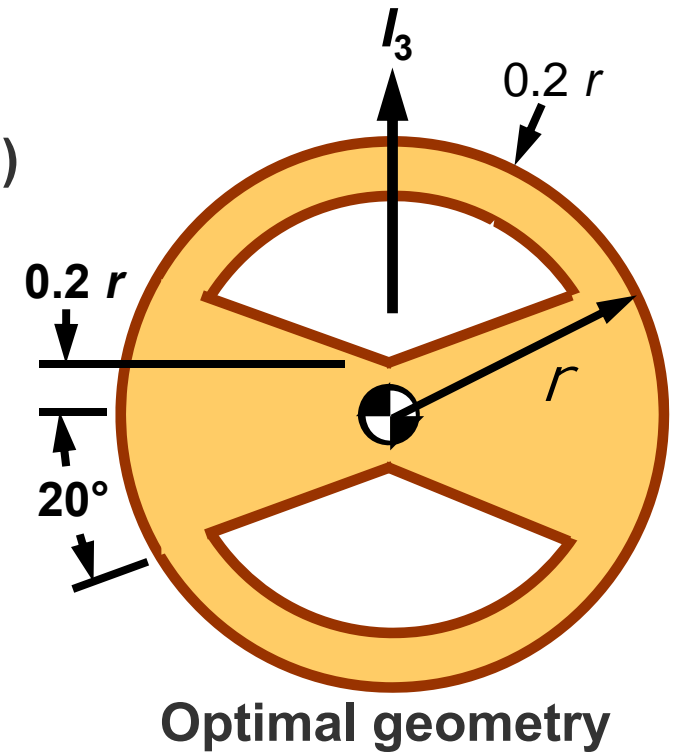
- No cross coupling of degrees of freedom

## 6. **Simple flight-proven caging mechanism (DISCOS)**



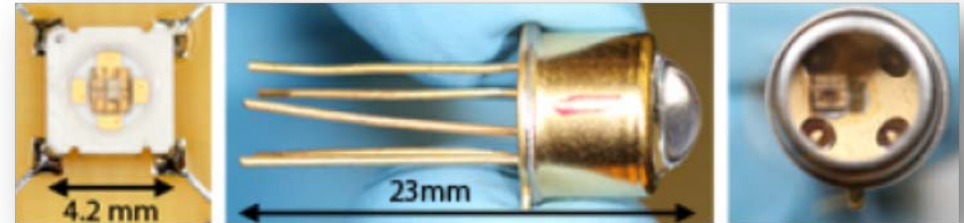
## Test Mass

- **Test mass: 70%/30% Au/Pt (LISA)**
  - Alternate: Berglide (2%/97.5%/0.5% Be/Cu/Co)
- **Spinning (3-10 Hz) average all but axisymmetric irregularities**
  - Out-of-plane motion → patch length changes  $1 \text{ pm/Hz}^{1/2}$  at 1 mHz
- **Hollowed out sections ( $\Delta I/I = 0.1$ ) shift polhode to 0.3-1 Hz**
- **Carbide coated (e.g. SiC)**
  - Hard (no sticking), reflective, conductive, allows UV charge control, measured patches consistent or better than gold

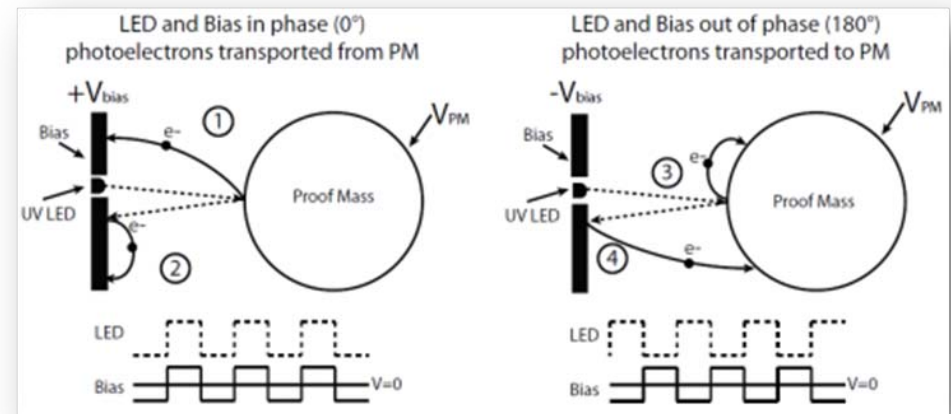


## Insert Charge Management Here

- Charge accumulation on proof mass: 50-200 e-/sec
- Charge control by UV photoemission using 254 nm line of an rf mercury source successfully demonstrated on GP-B
- Newer commercial UV LEDs (240-255 nm)



Fast-switchable ( $> 100$  MHz) allowing ac charge management through synchronization with bias electrode

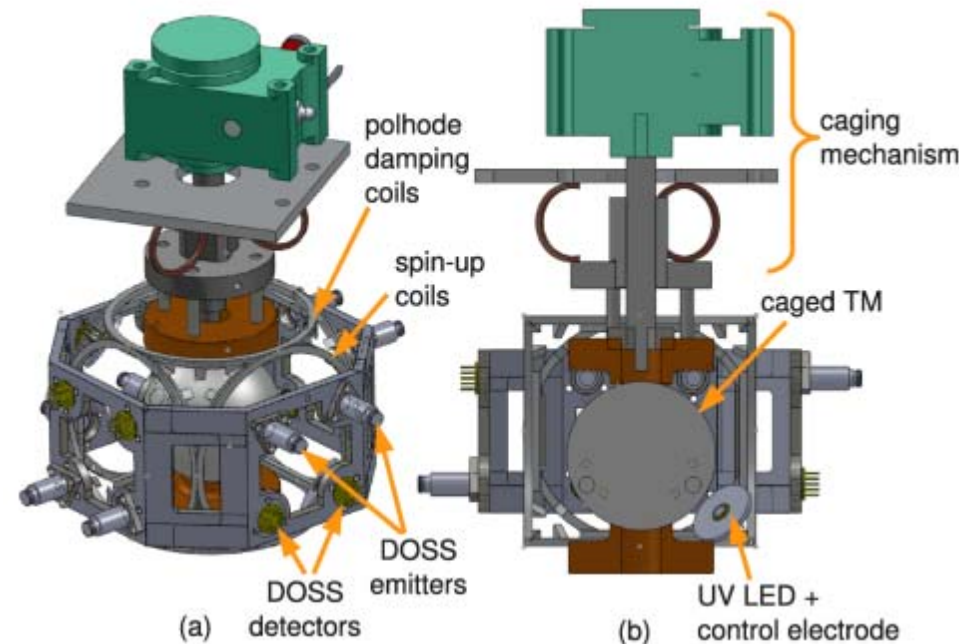
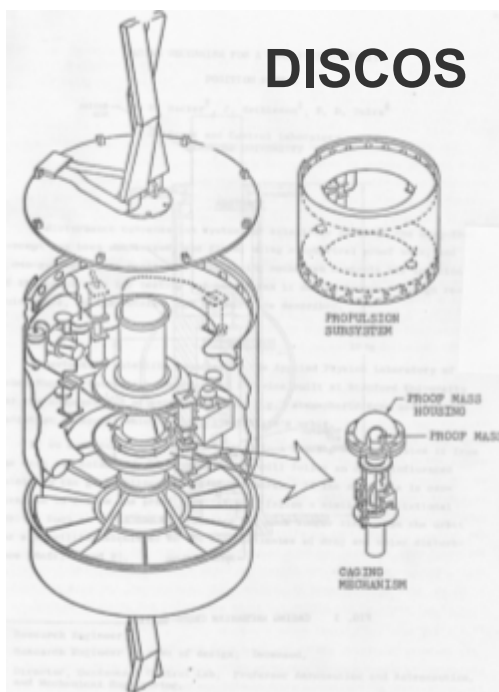


# Test Mass Caging & Release

- **DISCOS flight proven mechanism**
  - Jack screw holds TM against housing
  - Successfully demonstrated twice on-orbit, 2<sup>nd</sup> time after 6 month caging
- **After release,  $\mu\text{N}$  thrusters 'catch up' with inertial TM**

- **Capture time only function of residual velocity & max thrust**

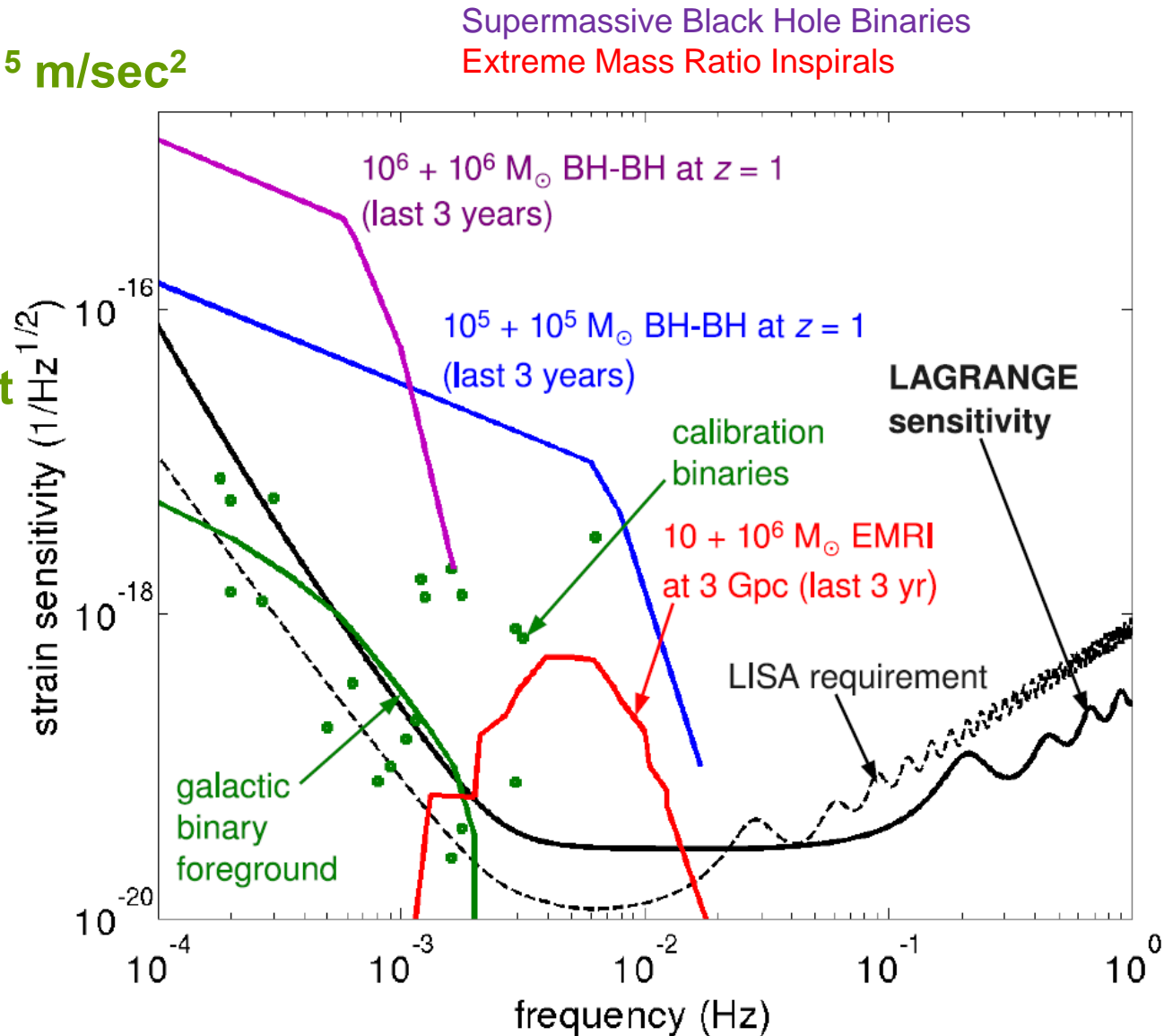
DISCOS capture time: ~100 sec  
Proposed: ~1000 sec





# Strain Sensitivity

- **Arm length: ~670,000 km**
- **Metrology: 8 pm/Hz<sup>1/2</sup> at 3 mHz**
- **Acceleration noise:  $3 \times 10^{-15}$  m/sec<sup>2</sup>**
- **Sensitivity 2x less than LISA below 20 mHz**
- **Below 2 mHz galactic binary confusion sets limit**
- **Maintains most important science objectives of LISA**



# The End

