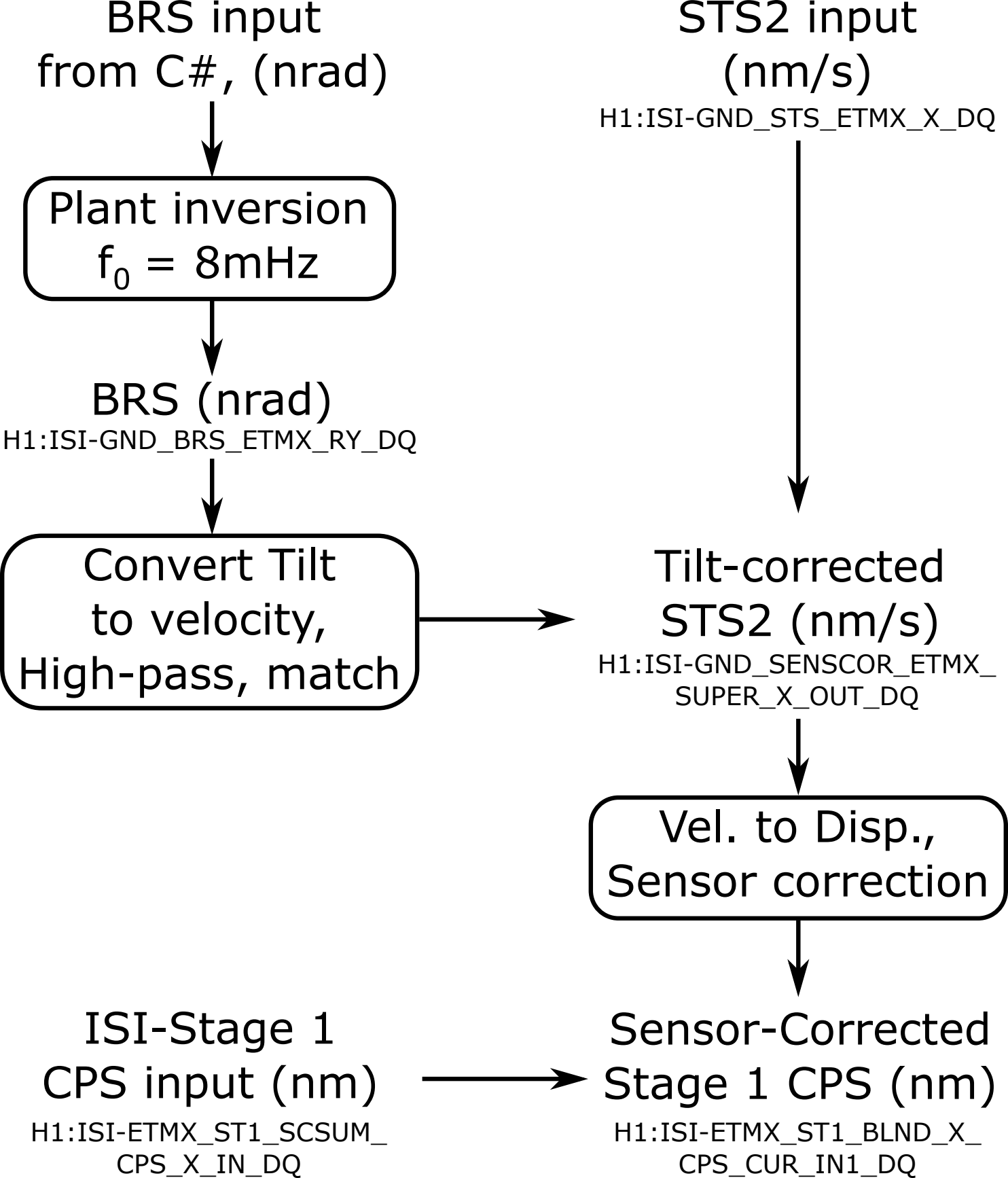
BRS input
from C#, (nrad)
Plant inversion
f_0 = 8mHz
BRS (nrad)
H1:ISI-GND_BRS_ETMX_RY_DQ
Convert Tilt
to velocity,
High-pass, match
STS2 input
(nm/s)
H1:ISI-GND_STS_ETMX_X_DQ
Tilt-corrected
STS2 (nm/s)
H1:ISI-GND_SENSCOR_ETMX_
SUPER_X_OUT_DQ
Vel. to Disp.,
Sensor correction
ISI-Stage 1
CPS input (nm)
H1:ISI-ETMX_ST1_SCSUM_
CPS_X_IN_DQ
Sensor-Corrected
Stage 1 CPS (nm)
H1:ISI-ETMX_ST1_BLND_X_
CPS_CUR_IN1_DQ