

4Gen TFFFS

Setup

```
Needs["Controls`LinearControl`"]
```

```
$TextStyle = {FontFamily -> "Helvetica", FontSize -> 13};
```

```
plotopt = Sequence@@{GridLines -> Automatic, Frame -> True, FrameStyle -> Thickness[0.0025],  
PlotStyle -> {Darker[Green], Blue, Red}, BaseStyle -> {FontSize -> 13}};
```

```
plotoptn[n_Integer? (# > 0 & & # < 8 &)] :=  
Sequence@@{GridLines -> Automatic, Frame -> True, FrameStyle -> Thickness[0.0025],  
PlotStyle -> Take[{Gray, Orange, Purple, Brown, Darker[Green], Blue, Red}, -n],  
BaseStyle -> {FontSize -> 13}};  
plotoptn[n_Integer? (# ≤ 0 ∨ # ≥ 8 &)] := plotopt
```

```
mylegend[labels_List, pos_ : Right] :=  
{Placed[LineLegend[labels, LabelStyle -> {FontSize -> 11},  
LegendMargins -> 2, LegendFunction -> (Framed[#, Background -> White] &)], pos]}
```

Equations

Schematics is D1700075-v1.

Parallel and Serial Impedance

```
par[r1_, r2_] :=  $\frac{1}{\frac{1}{r1} + \frac{1}{r2}}$   
par[r1_, r2_, r3_] :=  $\frac{1}{\frac{1}{r1} + \frac{1}{r2} + \frac{1}{r3}}$   
par[r1_, r2_, r3_, r4_] :=  $\frac{1}{\frac{1}{r1} + \frac{1}{r2} + \frac{1}{r3} + \text{Plus}@@\left(\frac{1}{\text{List}[r4]}\right)}$   
ser[r1_, r2_] := r1 + r2  
ser[r1_, r2_, r3_] := r1 + r2 + r3  
ser[r1_, r2_, r3_, r4_] := r1 + r2 + r3 + Plus@@List[r4]
```

Pole/zero

$$\begin{aligned} \text{pole}[s_, s0_] &:= \frac{1}{1 + \frac{s}{s0}} \\ \text{zero}[s_, s0_] &:= 1 + \frac{s}{s0} \\ \text{pole}[s_, s0_, Q_] &:= \frac{1}{1 + \frac{1}{Q} \frac{s}{s0} + (s/s0)^2} \\ \text{zero}[s_, s0_, Q_] &:= 1 + \frac{1}{Q} \frac{s}{s0} + (s/s0)^2 \end{aligned}$$

Transfer Function of an OpAmp

This function computes the transfer function of an idealized OpAmp circuit

g: +1 for non-inverting configuration or -1 for inverting configuration, 0 for differential configuration

z2: Impedance in feedback path [Ohm]

z1: Impedance of input path (inverting) or impedance to ground (non-inverting) [Ohm]

$$\begin{aligned} \text{OpAmp}[g_, z1_, z2_] &:= \\ \text{Which}[g > 0, 1 + \frac{z2}{z1}, g < 0, \frac{z2}{z1}, \text{True}, \frac{z2}{z1}] \end{aligned}$$

Noise of an OpAmp

This function computes the equivalent input noise of an OpAmp circuit

g: +1 for non-inverting configuration or -1 for inverting configuration, 0 for differential configuration

z1: Impedance of input path (inverting) or impedance to ground (non-inverting) [Ohm]

z2: Impedance over feedback path [Ohm]

en: voltage noise [Volt]

in: current noise [Ampere]

$$\begin{aligned} \text{FourKT} &= 1.62 \cdot 10^{-20}; (* V^2/Hz/Ohm; room temperature 20C *) \\ \text{OpAmpNoise}[g_, z1_, z2_, en_, in_] &:= \\ \text{Which}[g > 0, & \text{If}[z1 == \text{Infinity}, \sqrt{\text{en}^2 + \text{FourKT Abs}[z2] + (\text{in Abs}[z2])^2}, \\ & \sqrt{(\text{en}^2 + \text{FourKT Abs}[\text{par}[z1, z2]]) + (\text{in Abs}[\text{par}[z1, z2]])^2}], \\ g < 0, & \sqrt{\left(\text{Abs}\left[1 + \frac{z1}{z2}\right]^2 \text{en}^2 + \text{Abs}[z1]^2 \left(\text{in}^2 + \text{Abs}\left[\frac{\text{FourKT}}{z1}\right] + \text{Abs}\left[\frac{\text{FourKT}}{z2}\right]\right)\right)}, \\ \text{True}, & \sqrt{\left(\text{Abs}\left[1 + \frac{z1}{z2}\right]^2 \text{en}^2 + 2 \text{Abs}[z1]^2 \left(\text{in}^2 + \text{Abs}\left[\frac{\text{FourKT}}{z1}\right] + \text{Abs}\left[\frac{\text{FourKT}}{z2}\right]\right)\right)}] \end{aligned}$$

Flicker Noise: The variable \$Flicker determines if flicker noise is added or not. It can also be explicitly

specified with the option Flicker.

```

$Flicker = True;
Clear[OpAmpNoiseFlicker];
Options[OpAmpNoiseFlicker] = {Flicker -> $Flicker};
OpAmpNoiseFlicker[f_, fknee_, opts___] :=

  If[Flicker /. {opts} /. Options[OpAmpNoiseFlicker],  $\sqrt{\frac{fknee}{f} + 1}$ , 1]

OpAmpNoiseFlicker[f_, fknee_, floor_, opts___] := floor OpAmpNoiseFlicker[f, fknee, opts]

```

OpAmp Parameters

```

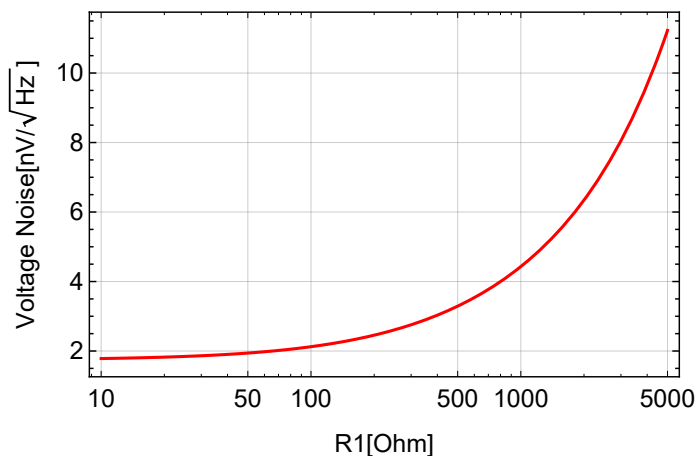
Clear[AD829, OP27]
AD829[f_] := {s → 2 π i f, en → enAD829, in → inAD829,
  enfloor → enfloorAD829, infloor → infloorAD829} //.
{enAD829 → OpAmpNoiseFlicker[f, ekneeAD829, enfloorAD829],
 inAD829 → OpAmpNoiseFlicker[f, ikneeAD829, infloorAD829],
 ekneeAD829 → 50, ikneeAD829 → 100, (*guess*)
 enfloorAD829 → 1.7*^-9, infloorAD829 → 1.5*^-12};
OP27[f_] := {s → 2 π i f, en → enOP27, in → inOP27,
  enfloor → enfloorOP27, infloor → infloorOP27} //.
{enOP27 → OpAmpNoiseFlicker[f, ekneeOP27, enfloorOP27],
 inOP27 → OpAmpNoiseFlicker[f, ikneeOP27, infloorOP27],
 ekneeOP27 → 2.7, ikneeOP27 → 140,
 enfloorOP27 → 3.0*^-9, infloorOP27 → 0.4*^-12};
LT1028[f_] := {s → 2 π i f, en → enLT1028, in → inLT1028,
  enfloor → enfloorLT1028, infloor → infloorLT1028} //.
{enLT1028 → OpAmpNoiseFlicker[f, ekneeLT1028, enfloorLT1028],
 inLT1028 → OpAmpNoiseFlicker[f, ikneeLT1028, infloorLT1028],
 ekneeLT1028 → 3.5, ikneeLT1028 → 250,
 enfloorLT1028 → 0.85*^-9, infloorLT1028 → 1*^-12};
LT1128[f_] := {s → 2 π i f, en → enLT1128, in → inLT1128,
  enfloor → enfloorLT1128, infloor → infloorLT1128} //.
{enLT1128 → OpAmpNoiseFlicker[f, ekneeLT1128, enfloorLT1128],
 inLT1128 → OpAmpNoiseFlicker[f, ikneeLT1128, infloorLT1128],
 ekneeLT1128 → 3.5, ikneeLT1128 → 250,
 enfloorLT1128 → 0.85*^-9, infloorLT1128 → 1*^-12};
AD797[f_] := {s → 2 π i f, en → enAD797, in → inAD797,
  enfloor → enfloorAD797, infloor → infloorAD797} //.
{enAD797 → OpAmpNoiseFlicker[f, ekneeAD797, enfloorAD797],
 inAD797 → OpAmpNoiseFlicker[f, ikneeAD797, infloorAD797],
 ekneeAD797 → 50, ikneeAD797 → 100, (*guess*)
 enfloorAD797 → 0.9*^-9, infloorAD797 → 2*^-12};
LT1012[f_] := {s → 2 π i f, en → enLT1012, in → inLT1012,
  enfloor → enfloorLT1012, infloor → infloorLT1012} //.
{enLT1012 → OpAmpNoiseFlicker[f, ekneeLT1012, enfloorLT1012],
 inLT1012 → OpAmpNoiseFlicker[f, ikneeLT1012, infloorLT1012],
 ekneeLT1012 → 2.5, ikneeLT1012 → 120, (*guess*)
 enfloorLT1012 → 14*^-9, infloorLT1012 → 6*^-15};
PA98A[f_] := {s → 2 π i f, en → enPA98A, in → inPA98A,
  enfloor → enfloorPA98A, infloor → infloorPA98A} //.
{enPA98A → OpAmpNoiseFlicker[f, ekneePA98A, enfloorPA98A],
 inPA98A → OpAmpNoiseFlicker[f, ikneePA98A, infloorPA98A],
 ekneePA98A → 100(*guess*), ikneePA98A → 120, (*guess*)
 enfloorPA98A → 4*^-9, infloorPA98A → 1*^-12 (*guess*)};

```

Examples (AD829)

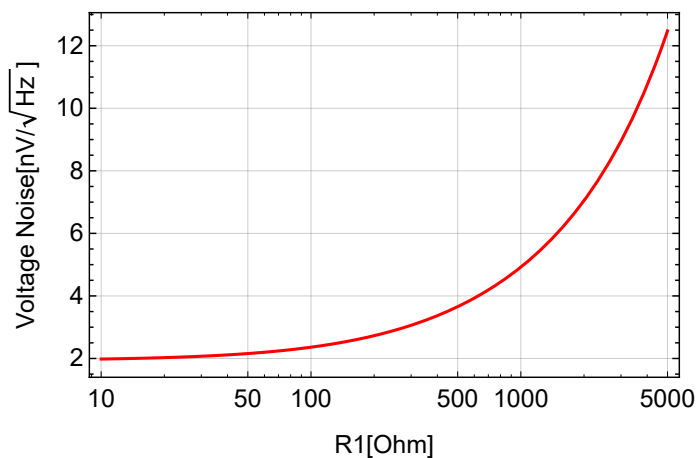
Non-Inverting configuration: input noise w/ gain of 10 as function of r1

```
LogLinearPlot[1*^9 OpAmpNoise[+1, r, 9 r, en, in] /. AD829[1000],
  {r, 10, 5000}, FrameLabel -> {"R1[Ohm]", "Voltage Noise[nV/√Hz]"},
  Frame -> True, GridLines -> Automatic, Evaluate[plotopt]]
```



Inverting configuration: input noise w/ gain of 10 as function of r1

```
LogLinearPlot[1*^9 OpAmpNoise[-1, r, 9 r, en, in] /. AD829[1000],
  {r, 10, 5000}, FrameLabel -> {"R1[Ohm]", "Voltage Noise[nV/√Hz]"},
  Frame -> True, GridLines -> Automatic, Evaluate[plotopt]]
```



Series Product of OpAmps

Computes the transfer function of several OpAmps circuits in series.

```
OpAmpProduct[t_, m_] := Product[t[i], {i, m}]
OpAmpProduct[t_List] := Product @@ t
```

Computes the equivalent input noise of several OpAmps circuits in series.

```

NoiseSum[prev_, {t_, n_}] :=  $\sqrt{\text{prev}^2 + n^2}$  Abs[t]
OpAmpNoiseProduct[t_, n_, m_] :=
  Fold[NoiseSum, 0, Table[{t[i], n[i]}, {i, m}]] / Abs[OpAmpProduct[t, m]]
OpAmpNoiseProduct[t_List, n_List] :=  $\frac{\text{Fold}[\text{NoiseSum}, 0, \text{Transpose}[t, n]]}{\text{Abs}[\text{OpAmpProduct}[t]]}$ 

```

Spectrum Math

Propagate noise spectrum

```

SpecProp[prev_, t_] := {#[[1]], Abs[t /. s -> 2.  $\pi$ #[[1]] #[[2]]] & /@ prev
SpecProp[noise_, t_List] := FoldList[SpecProp, noise, t]
SpecProp[noise_, t_, m_] := FoldList[SpecProp, noise, Table[t[i], {i, m}]]

```

RMS of spectrum

```

Clear[SpecRMS];
SpecRMS[l_List?(MatrixQ[#, NumberQ] &)] := Block[{i, sqr = 0},
  For[i = 1, i < Length[l], ++i,
    sqr += (l[[i + 1, 1]] - l[[i, 1]])  $\left(\frac{l[[i, 2]] + l[[i + 1, 2]]}{2}\right)^2$ ;
   $\sqrt{\text{sqr}}$  ]

```

Integrated RMS spectrum

```

Clear[RMSSpec];
RMSSpec[l_List?(MatrixQ[#, NumberQ] &), dir_ : (-1)] := Block[{i, sqr = 0, r = N[l]},
  If[dir >= 0,
    For[i = 2, i <= Length[l], ++i,
      r[[i, 2]] =  $\sqrt{(r[[i - 1, 2]]^2 + r[[i, 2]]^2 (r[[i, 1]] - r[[i - 1, 1]])}$ ],
    For[i = Length[l] - 2, i >= 1, --i,
      r[[i, 2]] =  $\sqrt{(r[[i + 1, 2]]^2 + r[[i, 2]]^2 (r[[i + 1, 1]] - r[[i, 1]])}$ ];
  r]

```

EOM Actuator Path

PA98 Open Loop Gain

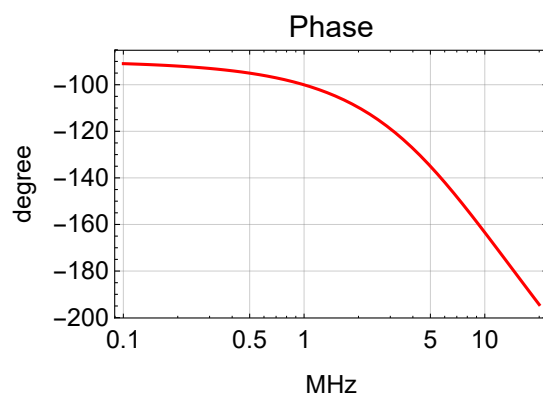
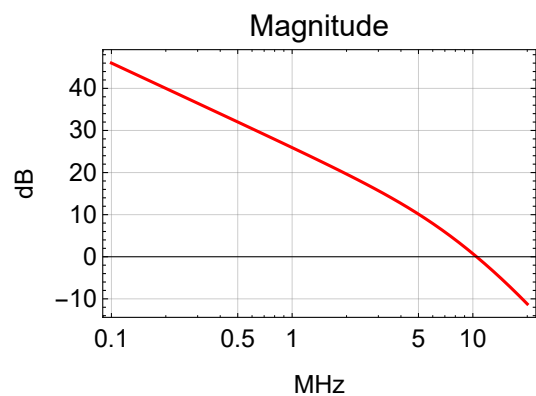
Data sheet at www.apexanalog.com.

```

prmpa98 = {gpa → 2*^5, spa → 2 π 100, spa2 → 2 π 7*^6, spa3 → 2 π 30*^6, rpa → 50};
pa98[s_] := gpa pole[s, spa] pole[s, spa2] pole[s, spa3]
(* heuristic model representing the published curves with Cc = 20 pF *)

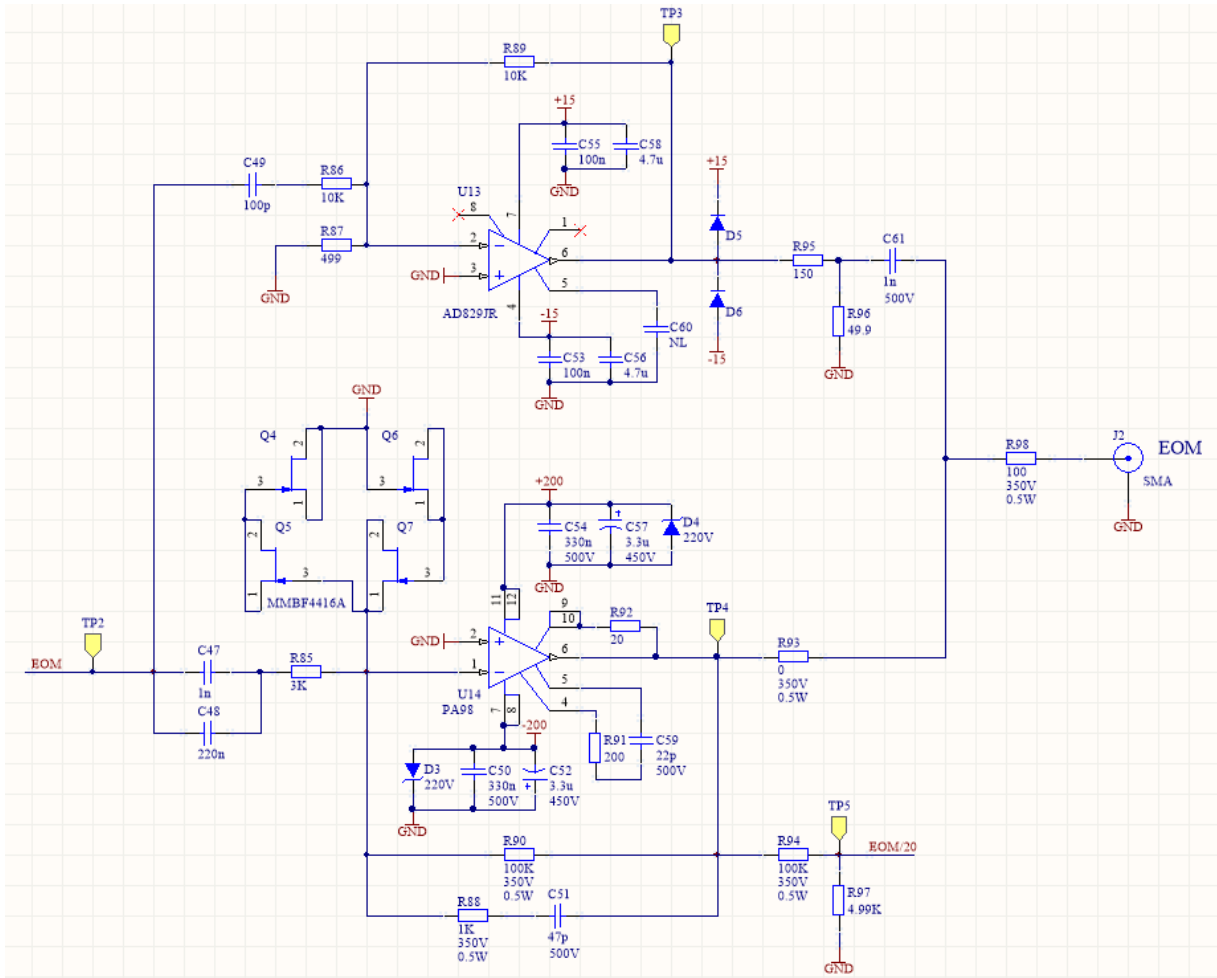
```

```
BodePlotEx[pa98[2 π i 1*^6 f] /. prmpa98, {f, 0.1, 20}, Evaluate[plotopt], XAxisLabel → "MHz"]
```



Old Double Path Configuration

Schematics



Transfer Function

$$\text{prmFbEom} = \left\{ Z_{in} \rightarrow R85 + \frac{1}{s C48}, Z_{fb} \rightarrow \text{par} \left[R90, R88 + \frac{1}{s C51} \right] \right\};$$

$$\text{prmActEom2Path} = \{ R90 \rightarrow 100 * 10^3, R88 \rightarrow 1 * 10^3, C51 \rightarrow 47 * 10^{-12}, R85 \rightarrow 3 * 10^3, \\ C48 \rightarrow 220 * 10^{-9}, C49 \rightarrow 100 * 10^{-12}, R86 \rightarrow 10 * 10^3, R87 \rightarrow 499, R89 \rightarrow 10 * 10^3, \\ R93 \rightarrow 0, R95 \rightarrow 150, R96 \rightarrow 50, C61 \rightarrow 1 * 10^{-9}, R98 \rightarrow 100, C_{\text{eom}} \rightarrow 10 * 10^{-12} \};$$

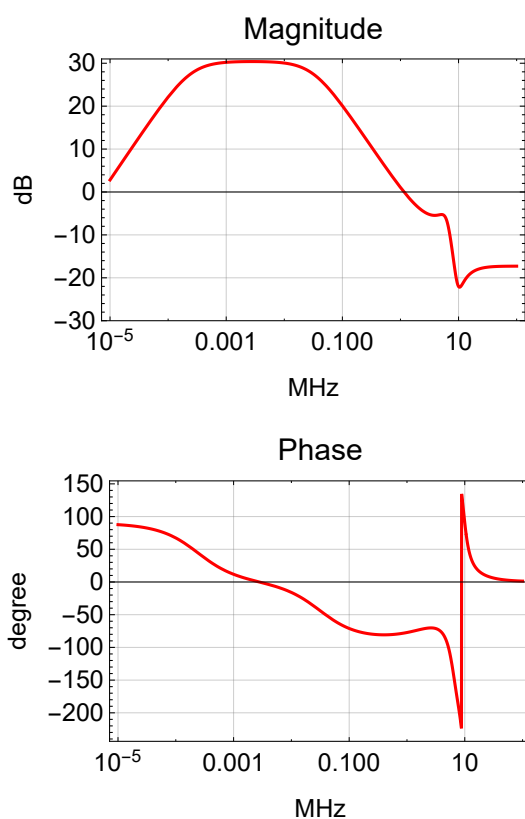
$$u14[s_] := -\frac{Zfb}{Zin} /. prmFbEom$$

$$u13[s_] := -\frac{R89}{R86 + \frac{1}{s C49}}$$

Pole/zero Determination

Bode Plot

```
BodePlotEx[-eomact2Path[2 π i 1*^6 f] /. prmpa98 // . prmActEom2Path,
  {f, 0.00001, 100}, MagnitudeRange → {-30, 31}, Evaluate[plotopt], XAxisLabel → "MHz"]
```

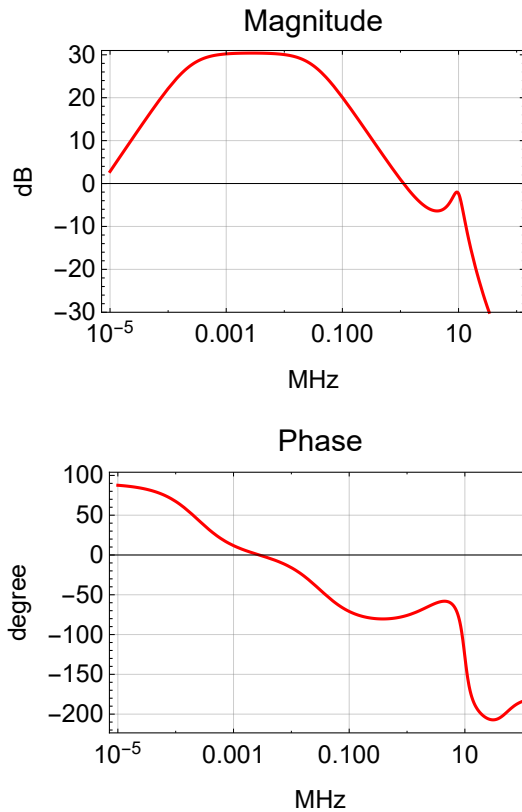


Single Path Configuration with Old Parameters

Remove C61 in AD829 path.

The AD829 path seems to reduce the gain peaking around 10 MHz, but otherwise has little effect below 1 MHz.

```
BodePlotEx[-eomact2Path[2 π i 1*^6 f] /. prmpa98 /. C61 → 0 /. prmActEom2Path,
{f, 0.00001, 100}, MagnitudeRange → {-30, 31}, Evaluate[plotopt], XAxisLabel → "MHz"]
```



New Single Path Configuration (no PMC pole)

We add a passive low pass filter to the output and remove the U13 path all together. C61 has changed to 560 pF and goes to ground with R96 → 0 and R95 → ∞.

Transfer Function

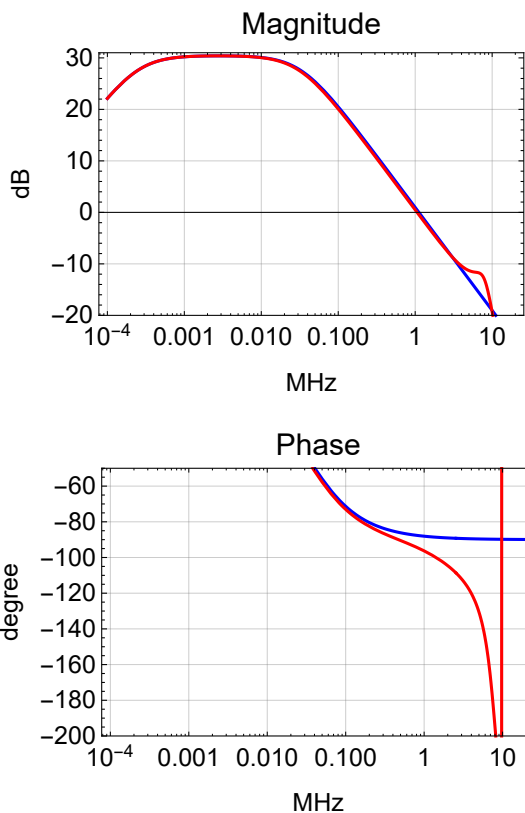
```
prmAActEom = {R90 → 100*^3, R88 → 1*^3, C51 → 47*^-12,
  R85 → 3*^3, C48 → 220*^-9, C49 → 0, R86 → 10*^3, R87 → 499, R89 → 10*^3,
  R93 → 100, R95 → ∞, R96 → 0, C61 → 560*^-12, R98 → 0, Ceom → 10*^-12};
paPole = {gPA →  $\frac{R90}{R85}$ , pPA1 →  $\frac{1}{C48 R85}$ , pPA2 →  $\frac{1}{C51 (R90 + R88)}$ } /. prmAActEom;
eomPrm = Join[paPole, {coefEOM → 0.015 (* rad/V *)}];
eomActTF[s_] := gPA  $\frac{s}{pPA1}$  pole[s, pPA1] pole[s, pPA2]
eomCoeff[s_] := coefEOM s (* rad/s/V *)
{  $\frac{pPA1}{2. \pi}$ ,  $\frac{pPA2}{2. \pi}$  } /. eomPrm
```

```
{241.144, 33527.5}
```

Pole/zero Determination

Bode Plot

```
BodePlotEx[{eomActTF[s] /. eomPrm /. s -> 2 π i 1*^6 f,
  -eomact[s] /. prmpa98 /. prmActEom /. s -> 2 π i 1*^6 f},
{f, 0.0001, 20}, MagnitudeRange -> {-20, 31}, PhaseRange -> {-200, -50},
Evaluate[plotoptn[2]], XAxisLabel -> "MHz"]
```



New Single Path Configuration (with 600 kHz PMC pole)

We limit the gain roll-off above 600 kHz by increasing R88 to 5.62K. We also eliminate C61, since it is not needed.

Transfer Function

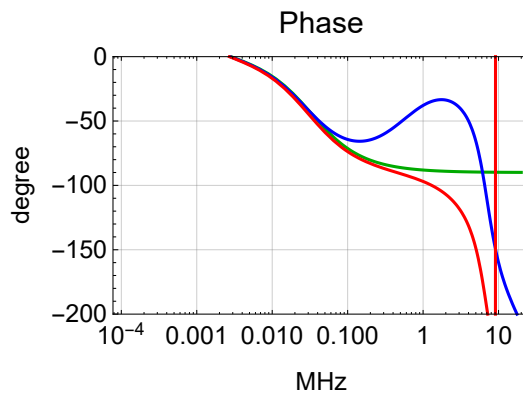
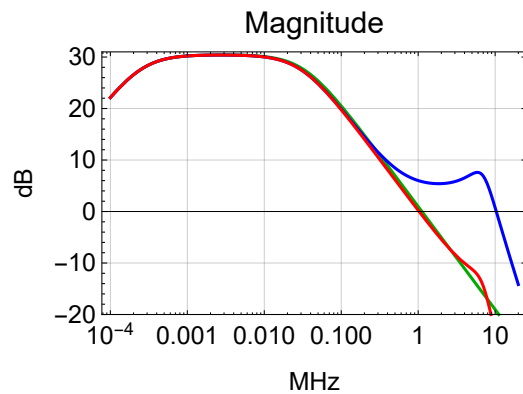
```
prmActEomPMC = {R90 -> 100*^3, R88 -> 5.62*^3, C51 -> 47*^-12,
  R85 -> 3*^3, C48 -> 220*^-9, C49 -> 0, R86 -> 10*^3, R87 -> 499, R89 -> 10*^3,
  R93 -> 100, R95 -> ∞, R96 -> 0, C61 -> 0*^-12, R98 -> 0, Ceom -> 10*^-12};
pmcPole = {pPMC -> 2 π 600*^3};
```

Bode Plot

```

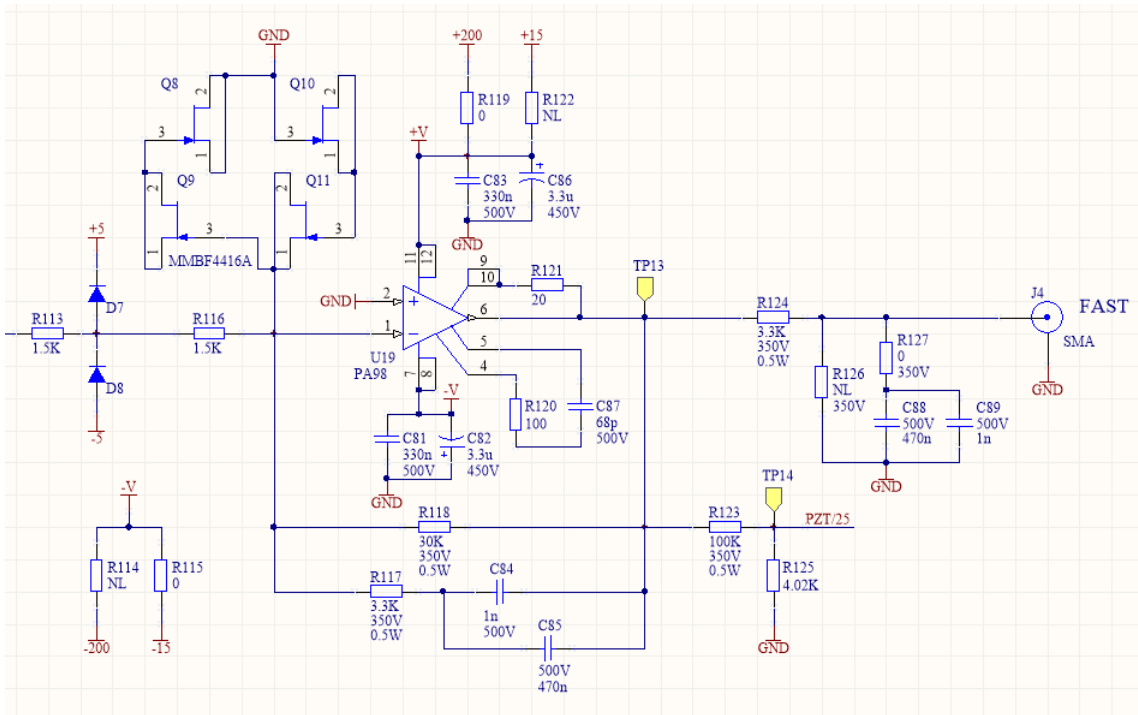
BodePlotEx[{eomTF[s] /. paPole /. s -> 2 π i 1*^6 f,
  -eomact[s] /. prmpa98 /. prmActEomPMC /. s -> 2 π i 1*^6 f,
  -eomact[s] pole[s, pPMC] /. prmpa98 /. prmActEomPMC /. pmcPole /. s -> 2 π i 1*^6 f},
{f, 0.0001, 20}, MagnitudeRange -> {-20, 31}, PhaseRange -> {-200, 0},
Evaluate[plotoptn[3]], XAxisLabel -> "MHz"]

```



PZT Actuator Path

Schematics



Transfer Function

```

prmFbPZT = {Zin → R113 + R116, Zfb → par[R118, R117 +  $\frac{1}{s C85}$ ]};
prmActPztPath = {R118 → 30*^3, R117 → 3.3*^3, C85 → 470*^-9, R113 → 1.5*^3,
  R116 → 1.5*^3, C88 → 470*^-9, R124 → 3.3*^3, R127 → 0, Cpzt → 40*^-12};
pztPole = {gPZT →  $\frac{R118}{R113 + R116}$ , pPZT1 →  $\frac{1}{C85 (R117 + R118)}$ } /. prmActPztPath;
pztPrm = Join[pztPole, {coefPZT → 2 π 1*^6 (* rad/s/V *), bwPZT → 2 π 100*^3}];
pztTF[s_] := gPZT pole[s, pPZT1]
pztCoeff[s_] := coefPZT pole[s, bwPZT] (* rad/s/V *)
{  $\frac{pPZT1}{2. \pi}$  } /. pztPrm

```

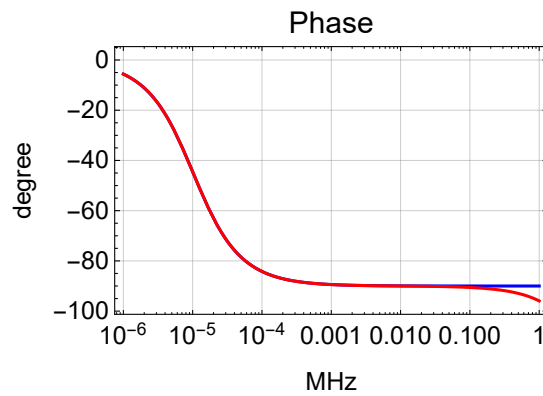
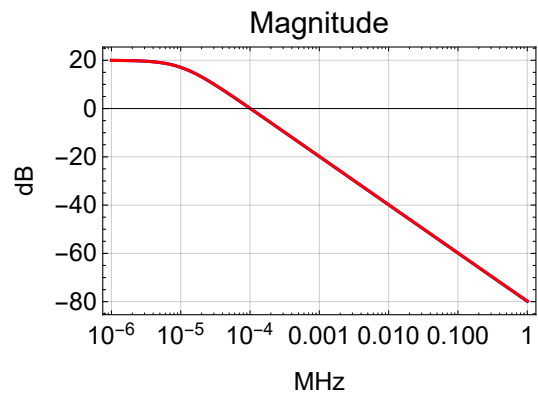
{10.169}

$$u19[s_] := - \frac{Zfb}{Zin} /. prmFbPZT$$

Pole/Zero Determination

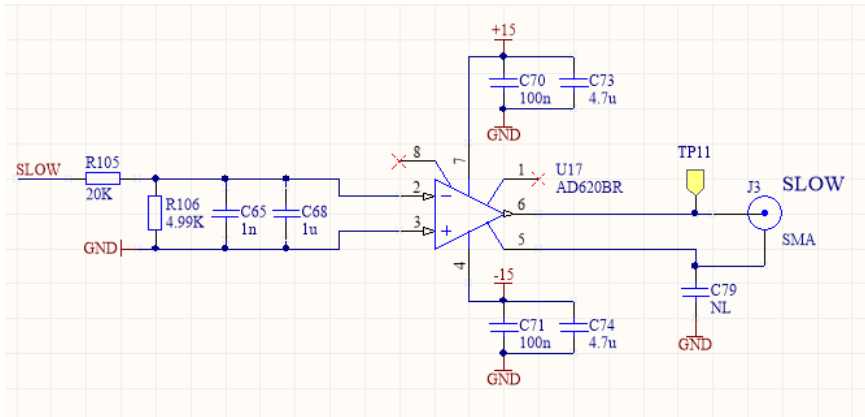
Bode Plot

```
BodePlotEx[  
  {pztTF[2  $\pi$  i 1*^6 f] /. pztPole, -pztactPath[2  $\pi$  i 1*^6 f] /. prmpa98 /. prmActPztPath},  
  {f, 0.000001, 1}, Evaluate[plotoptn[2]], XAxisLabel  $\rightarrow$  "MHz"]
```



Slow Actuator Path

Schematics



Transfer Function

```

prmActSlowPath = {R105 → 20*^3, R106 → 4.99*^3, C68 → 1*^-6};
slowPole = {gSlow →  $\frac{R106}{R105 + R106}$ , pSlow →  $\frac{1}{C68 \text{ par } [R105, R106]}$ } /. prmActSlowPath;
slowTF[s_] := gSlow pole[s, pSlow]
slowCoeff[s_] := 2 π 3*^9 pole[s, 2 π 0.5] (* rad/s/V *)
{gSlow,  $\frac{pSlow}{2. \pi}$ } /. slowPole

```

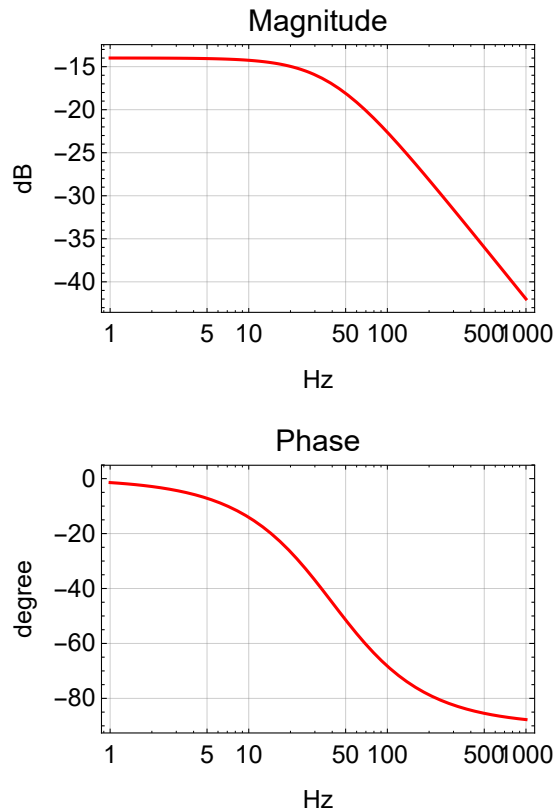
{0.19968, 39.8525}

$$\frac{\text{par}\left[R106, \frac{1}{s C65}\right]}{\text{par}\left[R106, \frac{1}{s C65}\right] + R105} // \text{Together}$$

$$\frac{R106}{R105 + R106 + C65 R105 R106 s}$$

Bode Plot

```
BodePlotEx[{slowTF[2 π i f] /. slowPole},
  {f, 1, 1000}, Evaluate[plotoptn[1]], XAxisLabel → "Hz"]
```



Sensing Path

Phase-Frequency Discriminator (Laser Locking)

A phase-frequency discriminator is used for laser locking. The standard LIGO PFD circuit is described in LIGO-E1200114. The PCB LIGO-D1002471 is used with a modification to make it higher bandwidth. This is described in LIGO-E1700100.

Transfer Function

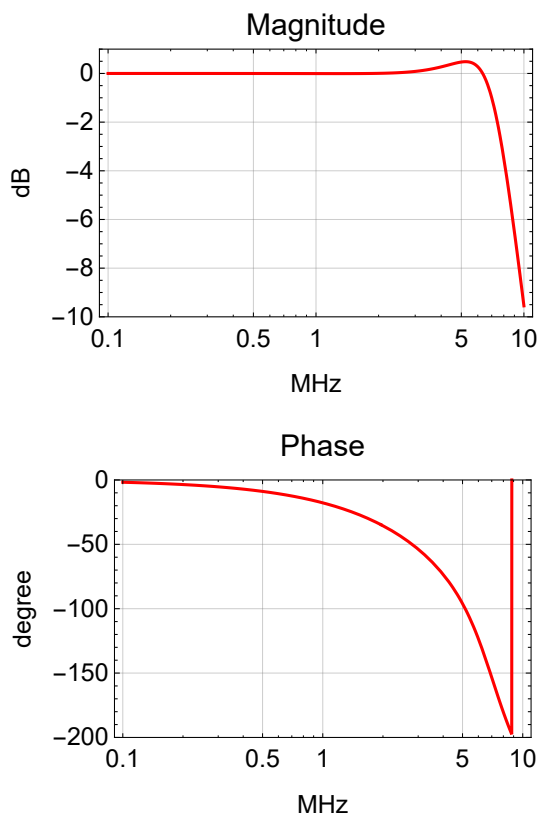
```

prmPFD =
  {sPFD1 → 2 π 5.72*^6, sPFD2 → 2 π 7.08*^6, qPFD2 → 1.44, sPFD3 → 169*^6, gPFD →  $\frac{10}{2 \pi}$ };
pfd[s_] := pole[s, sPFD1] pole[s, sPFD2, qPFD2] pole[s, sPFD3]
pfdCoeff[s_] := gPFD  $\frac{1}{s}$  (* V/(rad/s) *)
    
```

Bode Plot

```

BodePlotEx[pfd[2 π i f 1*^6] /. prmPFD, {f, 0.1, 10}, MagnitudeRange → {-10, 1},
  PhaseRange → {-200, 0}, Evaluate[plotoptn[3]], XAxisLabel → "MHz"]
    
```



Mixer (Cavity Locking)

The FET IQ demodulator is used for locking to a reference cavity. The standard LIGO FET IQ demodulator circuit is described in LIGO-E1200113. The PCB LIGO-D0902745 is used with a modification to make it ultra-fast bandwidth. This is described in LIGO-E1100044.

Transfer Function

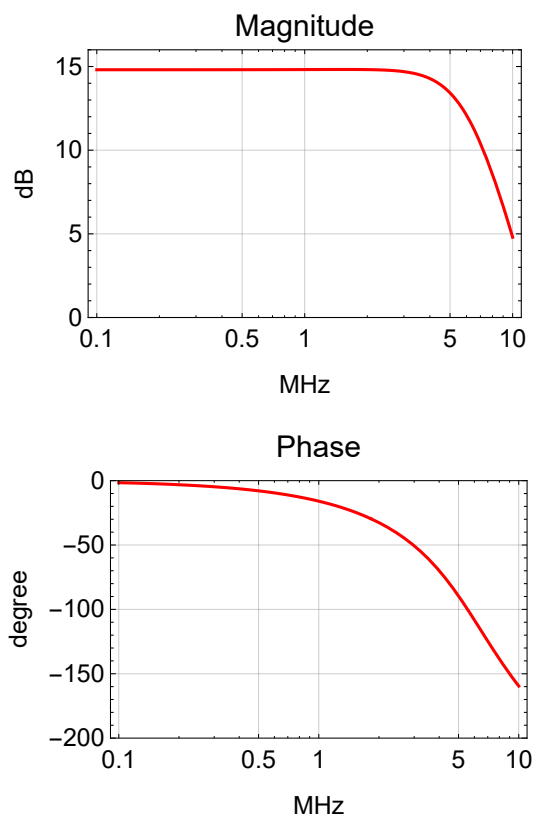
```
prmDemod = {gDemod → 5.5, pDemod1 → 2 π 15.9*^6, pDemod2 → 2 π 6.17*^6, qDemod2 → 0.761};
demod[s_] := gDemod pole[s, pDemod1] pole[s, pDemod2, qDemod2]
```

Reference Cavity

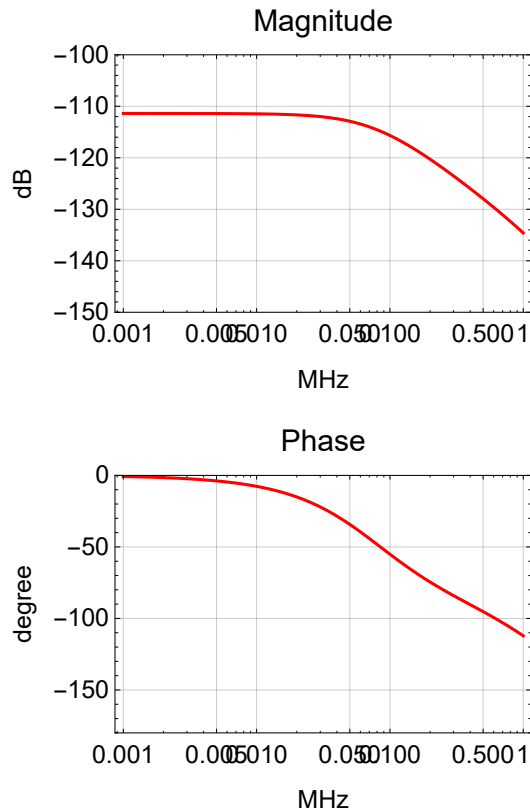
```
prmPDH = {pRefCav → 2 π 77.5*^3, pwrRefCav → 10*^-3, gainRefCav → 1*^-6,
  gammaRefCav → 1.0, effPD → 0.8, transPD → 500, pPD → 2 π 2*^6}; (* estimates *)
pdh[s_] := 2 BesselJ[0, gammaRefCav] BesselJ[1, gammaRefCav] pwrRefCav
  gainRefCav pole[s, pRefCav] effPD transPD pole[s, pPD]
```

Bode Plot

```
BodePlotEx[demod[2 π i f 1*^6] /. prmDemod, {f, 0.1, 10}, MagnitudeRange → {0, 16},
  PhaseRange → {-200, 0}, Evaluate[plotoptn[3]], XAxisLabel → "MHz"]
```



```
BodePlotEx[pdh[2 π i f 1*^6] /. prmPDH, {f, 0.001, 1}, MagnitudeRange → {-150, -100},
PhaseRange → {-180, 0}, Evaluate[plotoptn[3]], XAxisLabel → "MHz"]
```



Combined Sensing Path

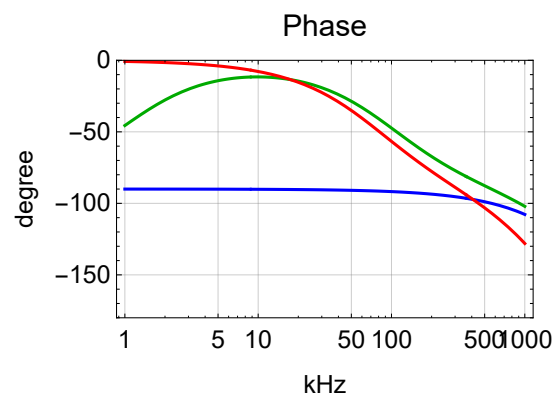
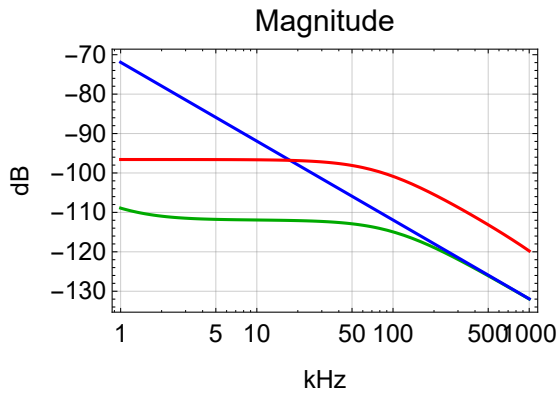
The sensing path transfer function combines one of the sensors, PFD or mixer, with an optional anti-boost. The anti-boost will make the PFD transfer function look more like the mixer one.

Transfer Function

```
prmSensing = {sBoostGain → 100, sBoostPole → 2 π 100 000};
allSensing := Join[prmPFD, prmDemod, prmPDH, prmSensing]
sensingTF::unknownsensing = "Unknown sensing parameter `1`; must be PFD or Mixer.";
Options[sensingTF] = {Sensing → "PFD", sBoost → False};
sensingTF[s_, opts___] := Switch[Sensing /. {opts} /. Options[sensingTF],
    "PFD", pfdCoeff[s] pfd[s],
    "Mixer", pdh[s] demod[s],
    _, Message[sensingTF::unknownsensing, Sensing]; 0] *
If[sBoost /. {opts} /. Options[sensingTF],
    1 / sBoostGain zero[s, sBoostPole / sBoostGain] pole[s, sBoostPole], 1]
```

Bode Plot

```
BodePlotEx[{sensingTF[2 π i f 1*^3, Sensing → "PFD", sBoost → True] /. allSensing,
  sensingTF[2 π i f 1*^3, Sensing → "PFD"] /. allSensing,
  sensingTF[2 π i f 1*^3, Sensing → "Mixer"] /. allSensing}, {f, 1, 1000},
  MagnitudeRange → All, PhaseRange → {-180, 0}, Evaluate[plotoptn[3]], XAxisLabel → "kHz"]
```



TFFS Servo

Common Path

Transfer Function

```

poleCommon = {R89 → 3.16*^3, R87 → 3.16*^3, C101 → 330*^-9,
  R88 → 3.16*^3, R90 → 3.16*^3, C107 → 330*^-9};
prmCommon = {cGain → 100/20, gCom1 →  $\frac{R87}{R89}$ , zCom1 →  $\frac{1}{C101 R87}$ ,
  gCom2 →  $\frac{R90}{R88}$ , zCom2 →  $\frac{1}{C107 R90}$ } /. poleCommon;
allCommon := prmCommon;

Options[commonTF] = {cBoost1 → False, cBoost2 → False};
commonTF[s_, opts___] := cGain If[cBoost1, gCom1  $\frac{zCom1}{s}$  zero[s, zCom1], gCom1]
  If[cBoost2, gCom2  $\frac{zCom2}{s}$  zero[s, zCom2], gCom2] /. {opts} /. Options[commonTF]

```

Parameters

$$N\left[\left\{gCom1, \frac{zCom1}{2\pi}\right\} /. allCommon\right]$$

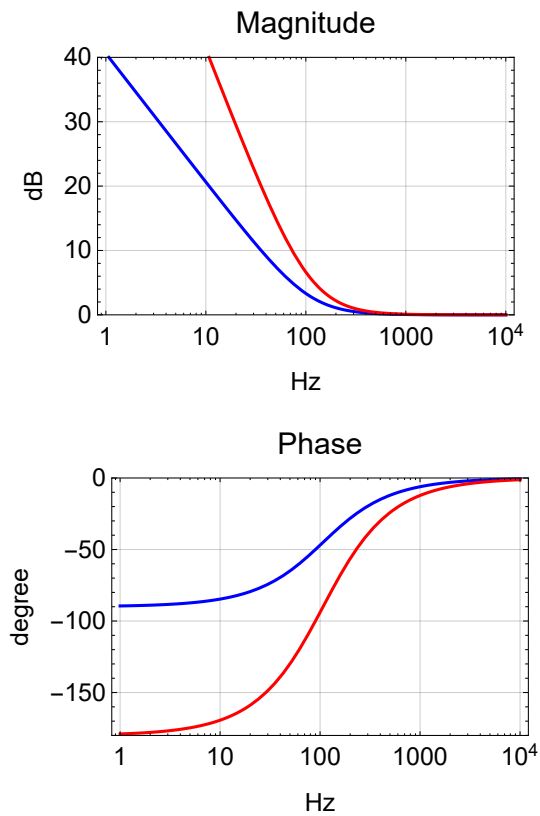
$$N\left[\left\{gCom2, \frac{zCom2}{2\pi}\right\} /. allCommon\right]$$

{1., 107.161}

{1., 107.161}

Bode Plot

```
BodePlotEx[{commonTF[2  $\pi$  i f, cBoost1  $\rightarrow$  True] /. prmCommon,  
commonTF[2  $\pi$  i f, cBoost1  $\rightarrow$  True, cBoost2  $\rightarrow$  True] /. prmCommon}, {f, 1, 10000},  
MagnitudeRange  $\rightarrow$  {0, 40}, PhaseRange  $\rightarrow$  {-180, 0}, Evaluate[plotoptn[2]], XAxisLabel  $\rightarrow$  "Hz"]
```



Fast Path

Transfer Function

```

poleFast = {R35 → 1000, R33 → 3.16*^3, C36 → 10*^-12, R30 → 28*^3, C43 → 2.2*^-9,
  R36 → 1000, R31 → 3.16*^3, C37 → 390*^-12,
  R80 → 499, R81 → 1.58*^3, C77 → 330*^-9, R82 → 14.3*^3,
  R83 → 1000, (*R84→66.7*^3,C95→2.2*^-9,*) R85 → 1000, R86 → 100*^3, C79 → 330*^-9
};

prmFast = {fGain → 100/20,
  gFast1 → - $\frac{R30}{R35}$ , pFast1 →  $\frac{1}{C43 (R30 + R33)}$ , zFast1 →  $\frac{1}{C43 R33}$ ,
  gFast2 → - $\frac{R31}{R36}$ , pFast2 →  $\frac{1}{C37 R31}$ ,
  gFast3 → - $\frac{R82}{R80}$ , pFast3 →  $\frac{1}{C77 (R81 + R82)}$ , zFast3 →  $\frac{1}{C77 R81}$ ,
  gFast4 → - $\frac{R86}{R83}$ , pFast4A →  $\frac{1}{C79 (R85 + R86)}$ , zFast4A →  $\frac{1}{C79 R85}$ ,
  (*pFast4B→ $\frac{1}{C95 R83}$ , zFast4B→ $\frac{1}{C95 (R83+R84)}$ ,*)
  gFast5 → -1

} /. poleFast;
allFast := Join[pztPrm, prmFast]

Options[fastTF] = {FastOnly → False};
fastTF[s_, opts___] :=
  If[FastOnly /. {opts} /. Options[fastTF],
    gFast3 pole[s, pFast3] zero[s, zFast3] * -1
    (*gFast4 pole[s,pFast4A]zero[s,zFast4A]*),
    fGain gFast1 pole[s, pFast1] zero[s, zFast1] gFast2 pole[s, pFast2]] *
    gFast5 /. {opts} /. Options[fastTF]

```

Parameters

$$N\left[\left\{g_{\text{Fast1}}, \frac{p_{\text{Fast1}}}{2\pi}, \frac{z_{\text{Fast1}}}{2\pi}\right\} /. \text{allFast}\right]$$

$$N\left[\left\{g_{\text{Fast2}}, \frac{p_{\text{Fast2}}}{2\pi}\right\} /. \text{allFast}\right]$$

$$N\left[\left\{g_{\text{Fast3}}, \frac{p_{\text{Fast3}}}{2\pi}, \frac{z_{\text{Fast3}}}{2\pi}\right\} /. \text{allFast}\right]$$

$$N\left[\left\{g_{\text{Fast4}}, \frac{p_{\text{Fast4A}}}{2\pi}, \frac{z_{\text{Fast4A}}}{2\pi} \left(*, \frac{p_{\text{Fast4B}}}{2\pi}, \frac{z_{\text{Fast4B}}}{2\pi} *\right)\right\} /. \text{allFast}\right]$$

{-28., 2321.67, 22893.4}

{-3.16, 129142.}

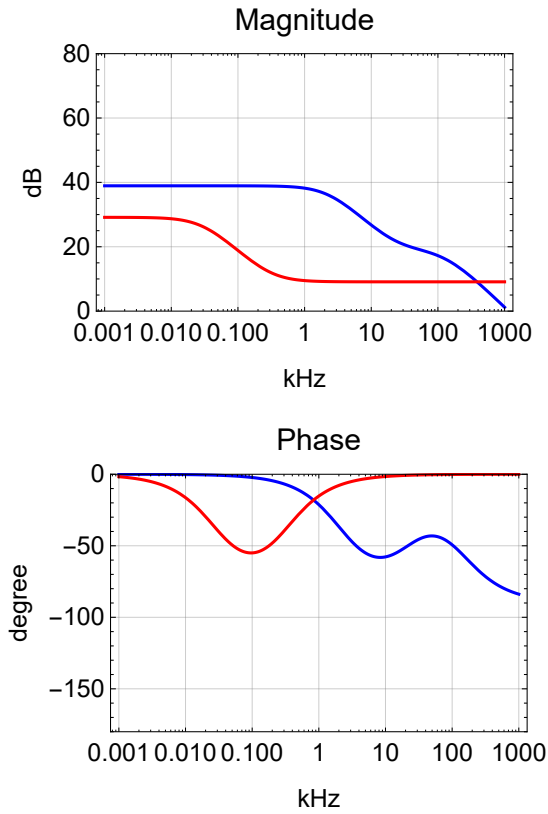
{-28.6573, 30.3708, 305.245}

{-100., 4.77513, 482.288}

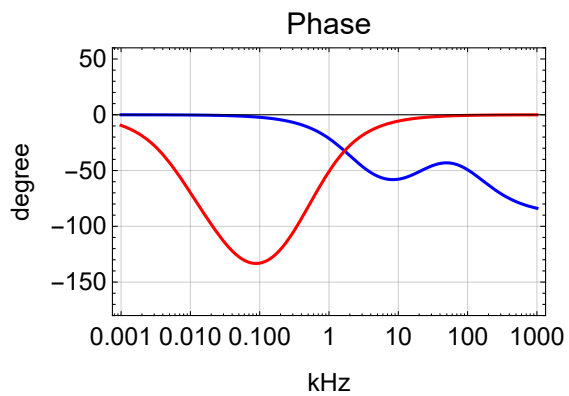
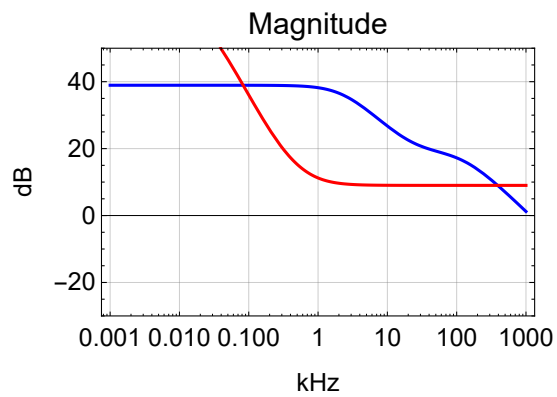
Pole/zero Determination

Bode Plot

```
BodePlotEx[
  {-fastTF[2 π i f 1*^3] //. allFast, -fastTF[2 π i f 1*^3, FastOnly → True] //. allFast},
  {f, 0.001, 1000}, MagnitudeRange → {0, 80}, PhaseRange → {-180, 0},
  Evaluate[plotoptn[2]], XAxisLabel → "kHz"]
```

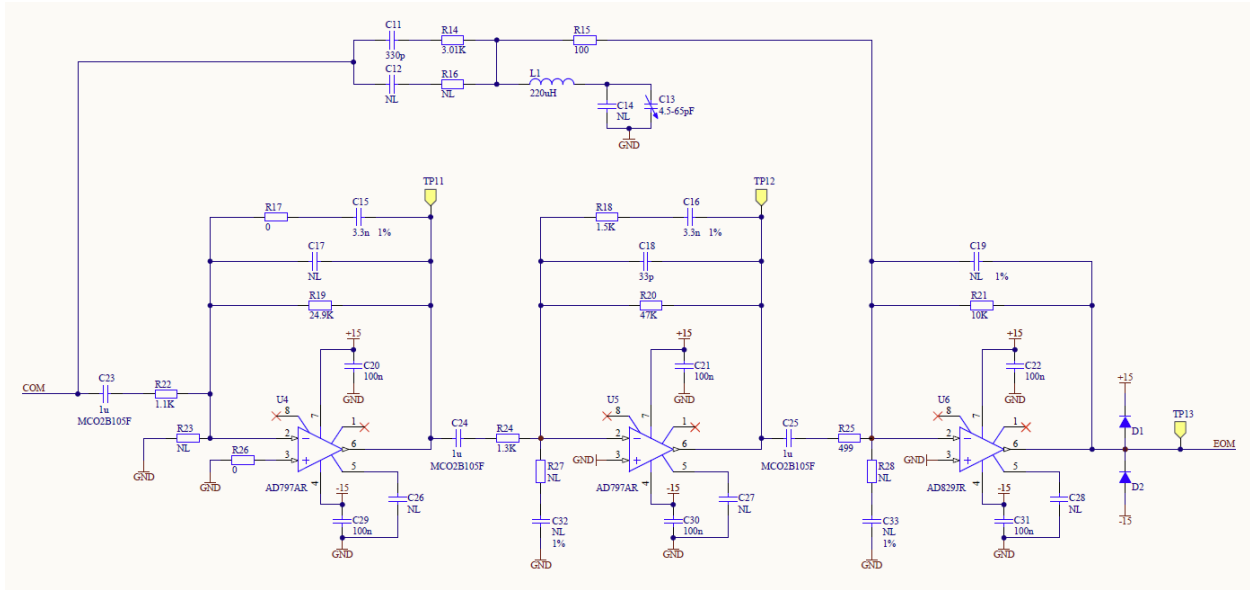


```
BodePlotEx[  
  {-fastTF[2  $\pi$  i f 1*^3] /. allFast, -fastTF[2  $\pi$  i f 1*^3, FastOnly  $\rightarrow$  True] /. allFast},  
  {f, 0.001, 1000}, MagnitudeRange  $\rightarrow$  {-30, 50},  
  PhaseRange  $\rightarrow$  {-180, 60}, Evaluate[plotoptn[2]], XAxisLabel  $\rightarrow$  "kHz"]
```



EOM Path

Schematics



Transfer Function

```

poleEom = {R22 → 1*^3, C23 → 100*^-9, R17 → 0.1, C15 → 3.3*^-9, R19 → 28*^3,
  C17 → 0.5*^-12, R24 → 1.58*^3, C24 → 100*^-9, R18 → 1.58*^3, C16 → 3.3*^-9,
  R20 → 48.7*^3, C18 → 47*^-12, R14 → 3.16*^3, C11 → 1*^-9, L1 → 220*^-6,
  C13 → 30*^-12, R15 → 100, R25 → 499., C25 → 100*^-9, R21 → 1*^3, C19 → 0.1*^-12};

prmEom = {gEOM1 → - $\frac{R19}{R22}$ , pEOM1a →  $\frac{1}{C23 R22}$ , pEOM1b →  $\frac{1}{C15 (R17 + R19)}$ ,
  zEOM1b →  $\frac{1}{C15 R17}$ , pEOM1c →  $\frac{1}{\text{par}[R17, R19] C17}$ ,
  gEOM2 → - $\frac{R20}{R24}$ , pEOM2a →  $\frac{1}{C24 R24}$ , pEOM2b →  $\frac{1}{C16 (R18 + R20)}$ ,
  zEOM2b →  $\frac{1}{C16 R18}$ , pEOM2c →  $\frac{1}{\text{par}[R18, R20] C18}$ ,
  gEOM3 → - $\frac{R21}{R25}$ , pEOM3a →  $\frac{1}{C25 R25}$ , pEOM3b →  $\frac{1}{C19 R21}$ ,
  gEOM4 → - $\frac{R21}{R14 + R15}$ , pEOM4a →  $\frac{1}{C11 (R14 + R15)}$ , zEOM4b →  $\frac{1}{\sqrt{C13 L1}}$ ,
  pEOM4b →  $\frac{1}{\sqrt{C13 L1}}$ , qEOM4b →  $\frac{\sqrt{C13 L1}}{C13 \text{par}[R14, R15]}$ , pEOM4c →  $\frac{1}{C19 R21}$ } /. poleEom;

allEom := Join[eomPrm, prmEom]

Options[eomTF] = {};
eom1TF[s_, opts___] :=
  gEOM1  $\frac{s}{pEOM1a}$  pole[s, pEOM1a] pole[s, pEOM1b] zero[s, zEOM1b] pole[s, pEOM1c] *
  gEOM2  $\frac{s}{pEOM2a}$  pole[s, pEOM2a] pole[s, pEOM2b] zero[s, zEOM2b] pole[s, pEOM2c] *
  gEOM3  $\frac{s}{pEOM3a}$  pole[s, pEOM3a] pole[s, pEOM3b] /. {opts} /. Options[eomTF]
eom2TF[s_, opts___] :=
  gEOM4  $\frac{s}{pEOM4a}$  pole[s, pEOM4a] zero[s, zEOM4b, ∞] pole[s, pEOM4b, qEOM4b] pole[s, pEOM4c] /.
  {opts} /. Options[eomTF]
eomTF[s_, opts___] := eom1TF[s, opts] + eom2TF[s, opts]

```

Parameters

$$\left\{g_{EOM1}, \frac{p_{EOM1a}}{2 \cdot \pi}, \frac{p_{EOM1b}}{2 \cdot \pi}, \frac{z_{EOM1b}}{2 \cdot \pi}, \frac{p_{EOM1c}}{2 \cdot \pi}\right\} /. prmEom /. poleEom$$

$$\left\{g_{EOM2}, \frac{p_{EOM2a}}{2 \cdot \pi}, \frac{p_{EOM2b}}{2 \cdot \pi}, \frac{z_{EOM2b}}{2 \cdot \pi}, \frac{p_{EOM2c}}{2 \cdot \pi}\right\} /. prmEom /. poleEom$$

$$\left\{g_{EOM3}, \frac{p_{EOM3a}}{2 \cdot \pi}, \frac{p_{EOM3b}}{2 \cdot \pi}\right\} /. prmEom /. poleEom$$

$$\left\{g_{EOM4}, \frac{p_{EOM4a}}{2 \cdot \pi}, \frac{p_{EOM4b}}{2 \cdot \pi}, q_{EOM4b}, \frac{p_{EOM4c}}{2 \cdot \pi}\right\} /. prmEom /. poleEom$$

$$\{-28, 1591.55, 1722.45, 4.82288 \times 10^8, 3.18311 \times 10^{12}\}$$

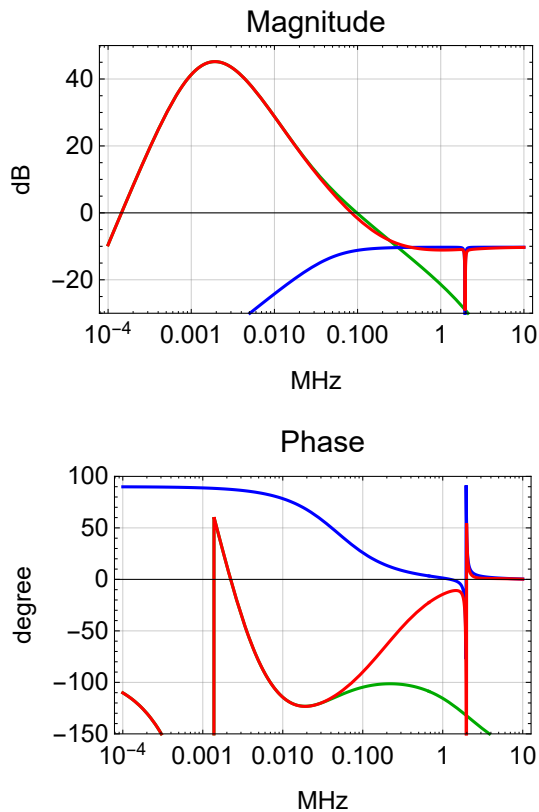
$$\{-30.8228, 1007.31, 959.204, 30524.5, 2.21275 \times 10^6\}$$

$$\{-2.00401, 3189.48, 1.59155 \times 10^9\}$$

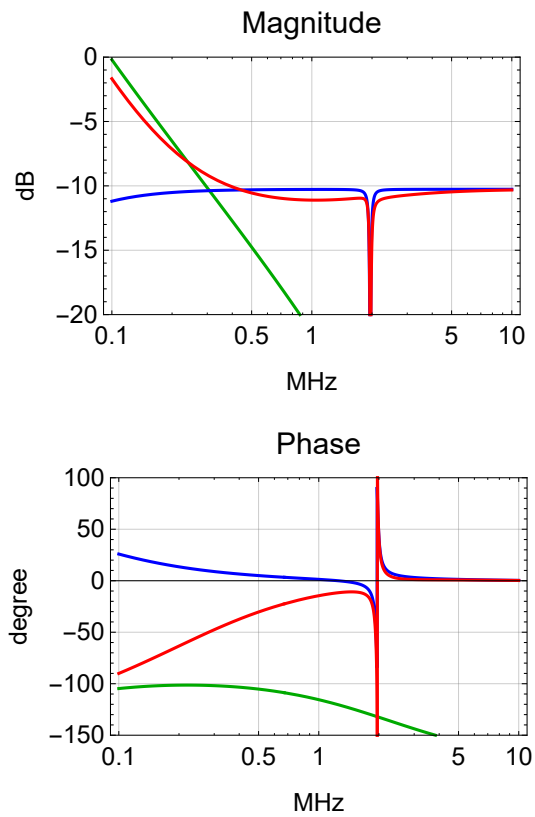
$$\{-0.306748, 48820.5, 1.95906 \times 10^6, 27.9371, 1.59155 \times 10^9\}$$

Bode Plot

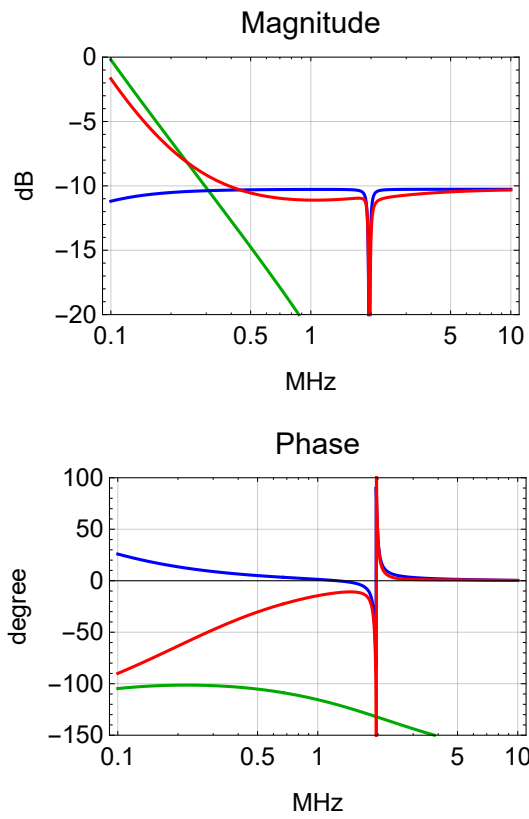
```
BodePlotEx[{-eom1TF[2 π i f 1*^6], -eom2TF[2 π i f 1*^6], -eomTF[2 π i f 1*^6]} /. allEom,
  {f, 0.0001, 10}, MagnitudeRange → {-30, 50},
  PhaseRange → {-150, 100}, Evaluate[plotoptn[3]], XAxisLabel → "MHz"]
```



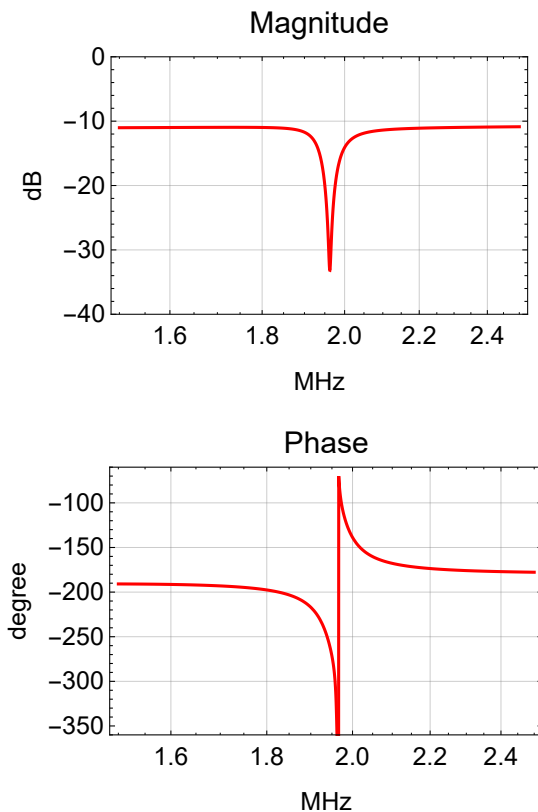
```
BodePlotEx[{-eom1TF[2 π i f 1*^6], -eom2TF[2 π i f 1*^6], -eomTF[2 π i f 1*^6]} /. allEom,  
{f, 0.1, 10}, MagnitudeRange → {-20, 0}, PhaseRange → {-150, 100},  
Evaluate[plotoptn[3]], XAxisLabel → "MHz"]
```



```
BodePlotEx[{-eom1TF[2 π i f 1*^6], -eom2TF[2 π i f 1*^6], -eomTF[2 π i f 1*^6]} /. allEom,
{f, 0.1, 10}, MagnitudeRange → {-20, 0}, PhaseRange → {-150, 100},
Evaluate[plotoptn[3]], XAxisLabel → "MHz"]
```



```
BodePlotEx[eomTF[2 π i f 1*^6] /. allEom, {f, 1.5, 2.5}, MagnitudeRange → {-40, 0},
PhaseRange → {-360, -60}, Evaluate[plotoptn[1]], XAxisLabel → "MHz"]
```



Overall Transfer Functions

```
allTTFSS := Join[allSensing, prmCommon, allFast, allEom]
Options[tffssTF] = Join[Options[sensingTF],
Options[commonTF], Options[fastTF], Options[eomTF]];
```

```
tffssCom[s_, opts___] := -sensingTF[s, opts] commonTF[s, opts]
tffssFastSplit[s_, opts___] := fastTF[s, opts] pztTF[s] pztCoeff[s]
tffssEomSplit[s_, opts___] := 10 eomTF[s, opts] eomActTF[s] eomCoeff[s]
tffssFast[s_, opts___] := tffssCom[s, opts] tffssFastSplit[s, opts]
tffssEom[s_, opts___] := tffssCom[s, opts] tffssEomSplit[s, opts]
tffssCrossTF[s_, opts___] :=  $\frac{\text{tffssFastSplit}[s, \text{opts}]}{\text{tffssEomSplit}[s, \text{opts}]}$ 
```

```
prmTTFSS = {FastOnly → False};
allTTFSS := Join[allSensing, prmCommon, allFast, allEom]
Options[tffssTF] = Join[Options[sensingTF],
Options[commonTF], Options[fastTF], Options[eomTF]];
```

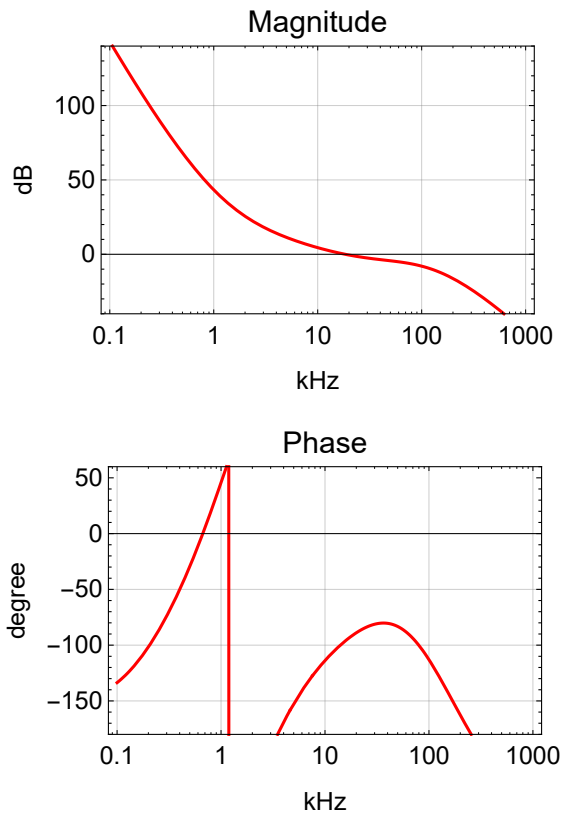
```
tffssTF[s_, opts___] :=
tffssFast[s, opts] + If[FastOnly /. {opts} /. allTTFSS, 0, tffssEom[s, opts]]
```


Options[tffssTF]

```
{Sensing → PFD, sBoost → False, cBoost1 → False, cBoost2 → False, FastOnly → False}
```

Crossover

```
BodePlotEx[tffssCrossTF[2 π i f 1*^3, FastOnly → False] /. fGain → 1020/20 /. allTFFSS,
  {f, 0.1, 1000}, MagnitudeRange → {-40, 140},
  PhaseRange → {-180, +60}, Evaluate[plotoptn[1]], XAxisLabel → "kHz"]
```

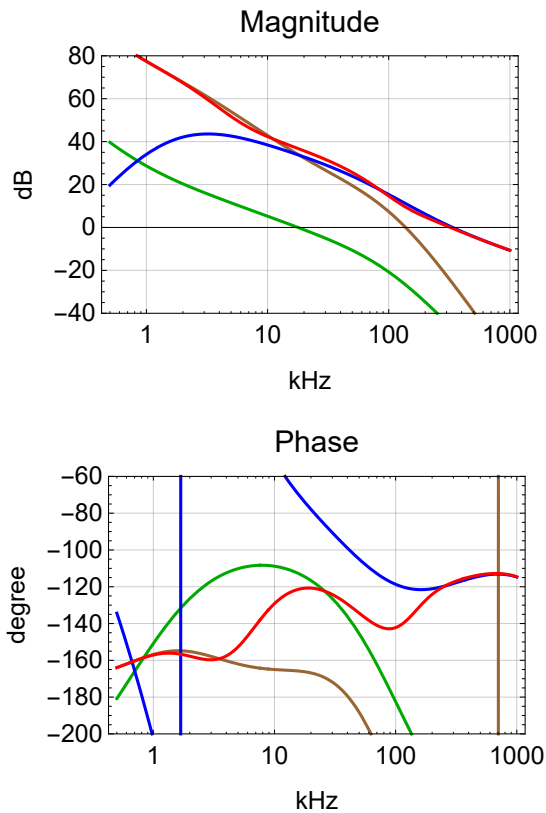


Components

```

opt = Sequence[sBoost → True];
prm = {cGain → 10 $\frac{12}{20}$ , fGain → 10 $\frac{20}{20}$ };
BodePlotEx[{ttfssFast[2  $\pi$  i f 1*3, FastOnly → False, opt] /. prm /. allTFSS,
  ttfssFast[2  $\pi$  i f 1*3, FastOnly → True, opt] /. prm /. allTFSS,
  ttfssEom[2  $\pi$  i f 1*3, FastOnly → False, opt] /. prm /. allTFSS,
  ttfssTF[2  $\pi$  i f 1*3, FastOnly → False, opt] /. prm /. allTFSS},
{f, 0.5, 1000}, MagnitudeRange → {-40, 80}, PhaseRange → {-200, -60},
Evaluate[plotoptn[4]], XAxisLabel → "kHz"]

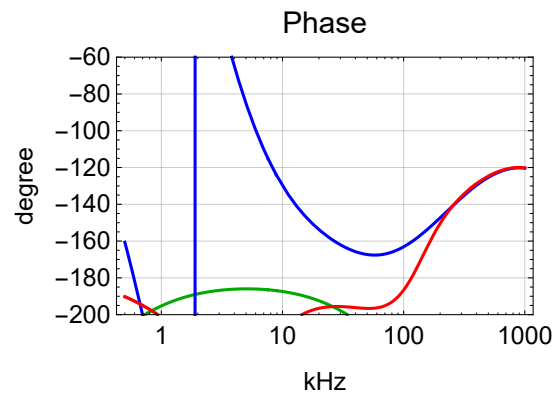
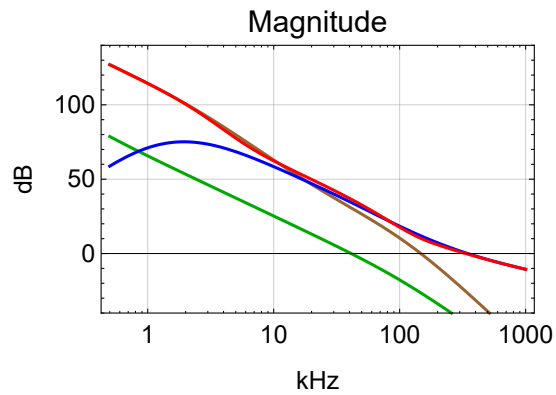
```



```

opt = Sequence[sBoost → False];
prm = {cGain → 10 $\frac{12}{20}$ , fGain → 10 $\frac{20}{20}$ };
BodePlotEx[{tffssFast[2  $\pi$  i f 1*3, FastOnly → False, opt] /. prm /. allTTFSS,
  tffssFast[2  $\pi$  i f 1*3, FastOnly → True, opt] /. prm /. allTTFSS,
  tffssEom[2  $\pi$  i f 1*3, FastOnly → False, opt] /. prm /. allTTFSS,
  tffssTF[2  $\pi$  i f 1*3, FastOnly → False, opt] /. prm /. allTTFSS},
{f, 0.5, 1000}, MagnitudeRange → {-40, 140}, PhaseRange → {-200, -60},
Evaluate[plotoptn[4]], XAxisLabel → "kHz"]

```

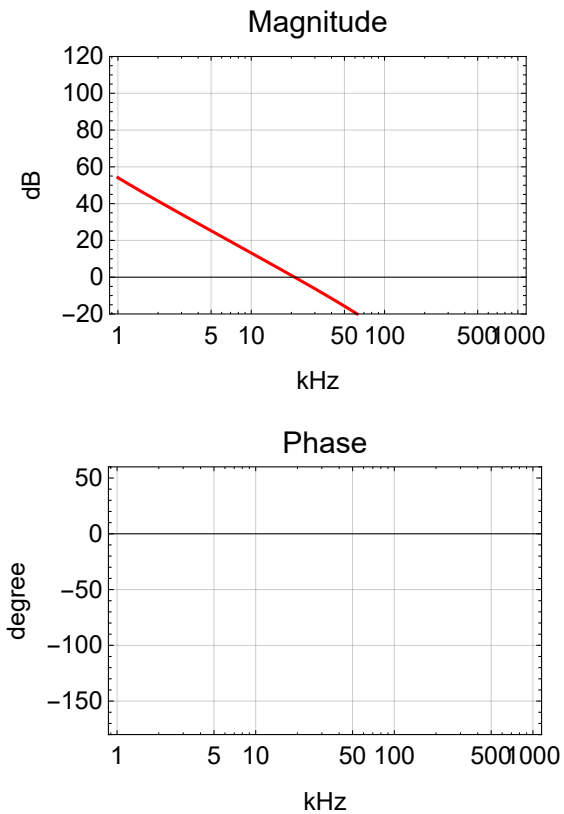


Combined Servo Path

Transfer Function

Bode Plot: PFD & Fast/EOM

```
BodePlotEx[ttfsvTF[2 π i f 1*^3, FastOnly → True, sBoost → False] /. fGain → 10-10/20 /. allTTFSS,
  {f, 1, 1000}, MagnitudeRange → {-20, 120}, PhaseRange → {-180, +60},
  Evaluate[plotoptn[1]], XAxisLabel → "kHz"]
```



TTFSS Servo

Additive Offset