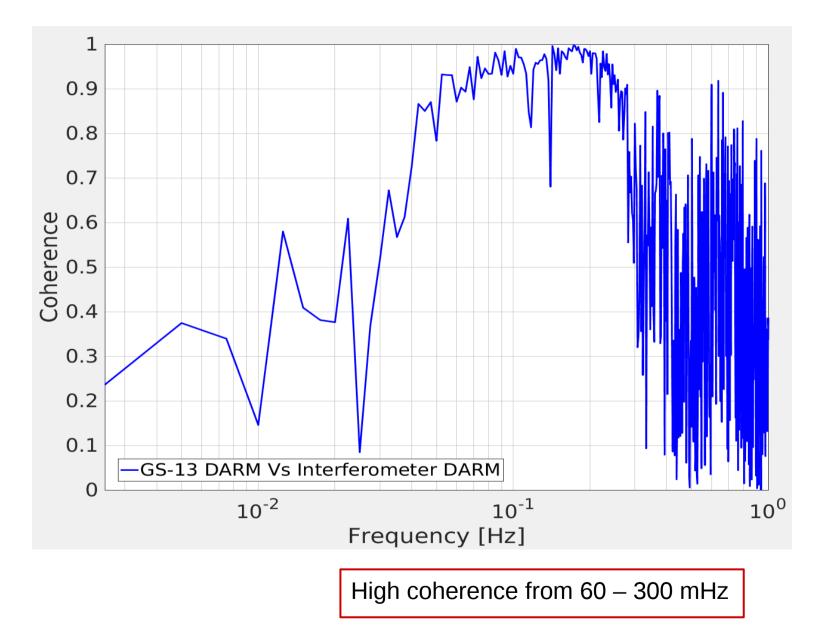
Improving DARM with ISI → SUS feedforward (short version)

Edgard Bonilla

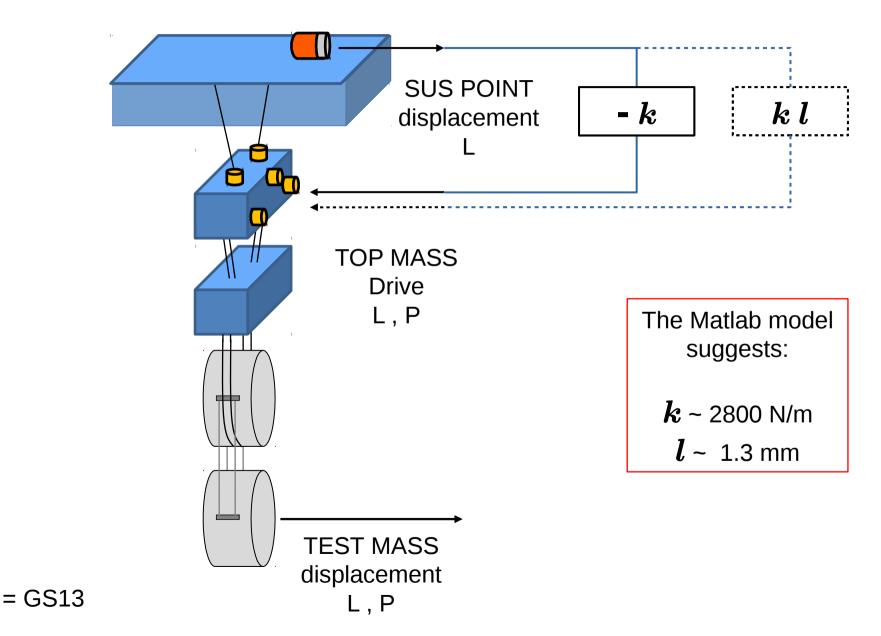
Motivation:



- SEI log 1237

Feedforward Diagram

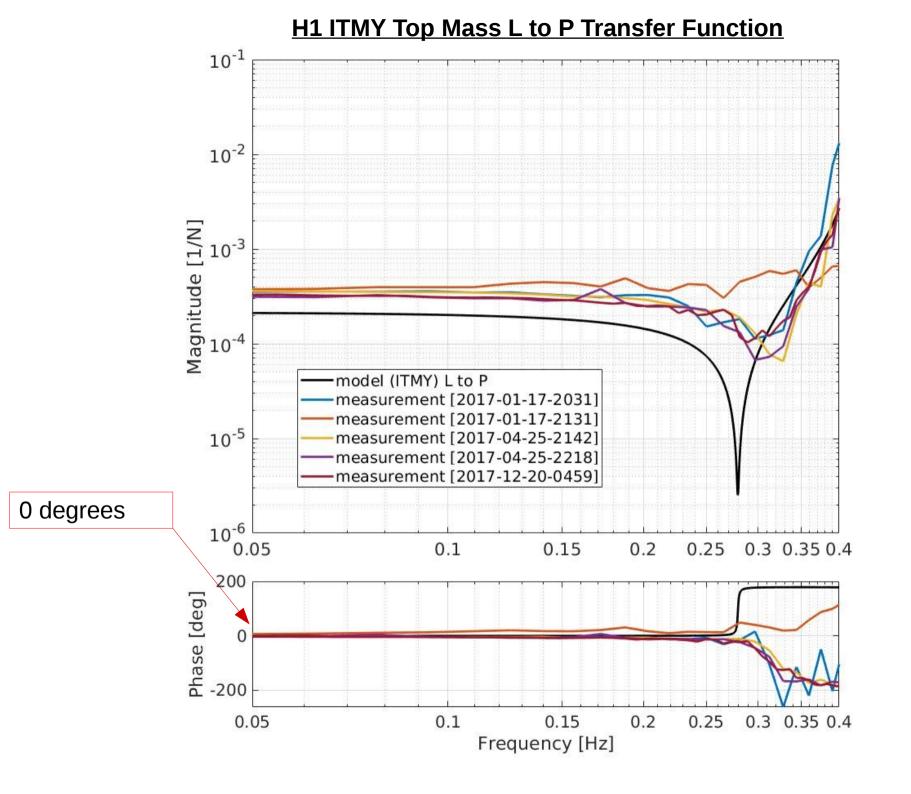




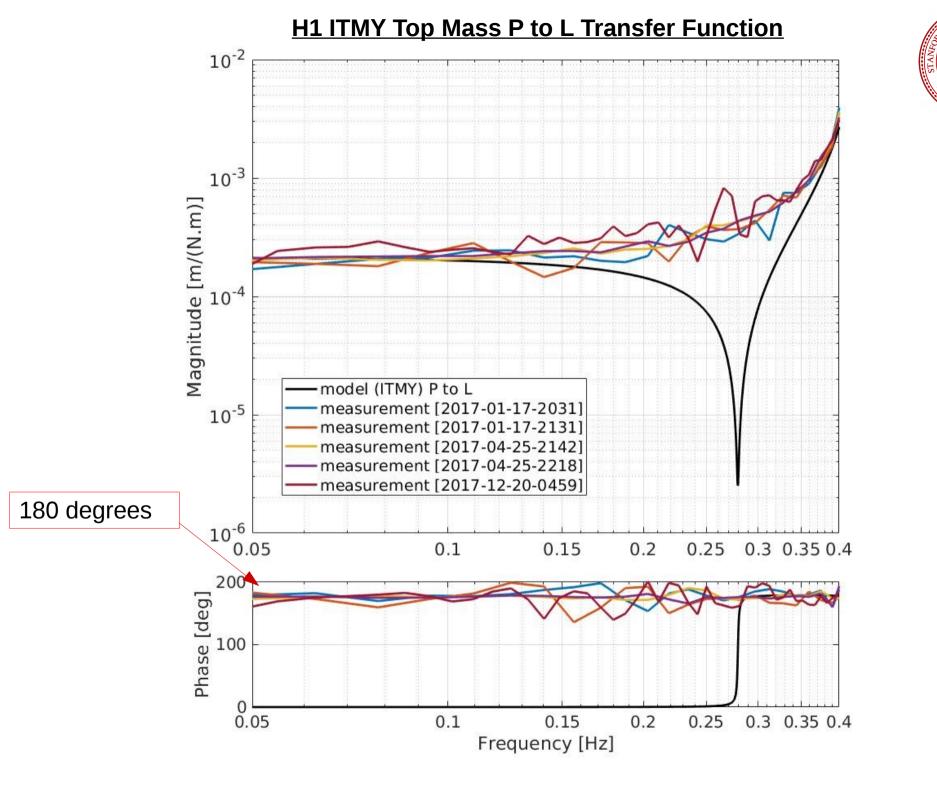


SUSPOINT L to TEST P (Model) **Pitch Compensation Comparison** 10⁴ 10³ —Sus Point L to Test P (No Feedforward) Only L feedforward ••••L and P feedforward ($\Delta z_{eff} = 10\%$) 10² **—** L and P feedforward ($\Delta z_{eff} = 1\%$) L and P feedforward ($\Delta z_{eff} = 0\%$) Magnitude [rad/m] 10¹ 10⁰ 10⁻¹ 10⁻² 10⁻³ 10⁻⁴ 10⁻² 10⁻¹ We can aim at 10% Frequency [Hz] accuracy when estimating **l** 4 - Edgard Bonilla,

SEI log 1325









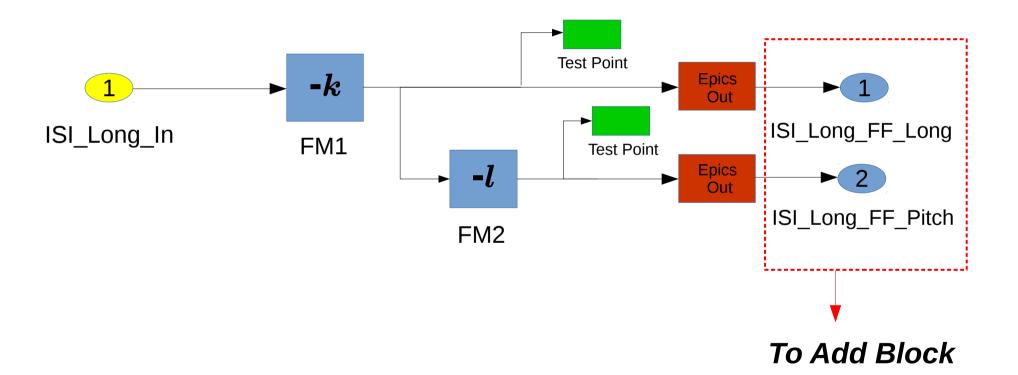
• From O2 we gather the values for the corner station quadruples at H1:

ITMX:
$$\bar{l} = -9600 \mu \text{m}$$
, $\Delta l = 1200 \mu \text{m}$, $\frac{\Delta l}{|l|} = 12.5\%$
ITMY: $\bar{l} = 2670 \mu \text{m}$, $\Delta l = 280 \mu \text{m}$, $\frac{\Delta l}{|l|} = 10.5\%$

- The non-reciprocity makes it hard to know if the absolute or relative error is the correct metric for accuracy.
- Testing this directly with the top mass at one of the sites might be a better option.



Feedforward tentative Diagram





- The FF would be active at both M0 and R0. Brian suggests that the Beam Splitter should have a similar compensation
- These filters should be turned on after the Seismic system is in the 'Isolated' state.
- Tuning should start by finding ${\pmb l}$. This can be done by taking top mass transfer functions only.
- We can find k by either taking a transfer function from ST2 X to M0 or estimate it from first principles. In either case, fine tuning by measuring M0 TFs is necessary.
- The coherence between GS13-DARM and DARM / DHARD could inform for readjustments